



MODE SELECT TABLE

| | INP | UTS | MODE | |
|----|-----|--------|------|------------------------|
| PL | ĈĒ | Ū/D | СР | |
| н | L | L H | L | Count Up Count Down |
| Ľ | x | x | x | Preset (Asyn.) |
| н | н | X | X | No Change (Hold) |

H = HIGH Voltage Level

L = LOW Voltage Level X = Immaterial

RC TRUTH TABLE

| _ | NPUT | OUTPUT | | |
|--------|------|--------|----|--|
| CE TC* | | СР | RC | |
| Г | Н | J | ъ. | |
| н | X | X | н | |
| Х | L | Х | н | |

*TC is generated internally

STATE DIAGRAM



190

FUNCTIONAL DESCRIPTION — The '190 is a synchronous up/down BCD decade counter and the '191 is a synchronous up/down 4-bit binary counter. The operating modes of the '190 decade counter and the '191 binary counter are identical, with the only difference being the count sequences as noted in the state diagrams. Each circuit contains four master/slave flip-flops, with internal gating and steering logic to provide individual preset, count-up and count-down operations.

Each circuit has an asynchronous parallel load capability permitting the counter to be preset to any desired number. When the Parallel Load (\overline{PD} input is LOW, information present on the Parallel Data inputs ($P_0 - P_3$) is loaded into the counter and appears on the Q outputs. This operation overrides the counting functions, as indicated in the Mode Select Table.

A HIGH signal on the \overline{CE} input inhibits counting. When \overline{CE} is LOW, internal state changes are initiated synchronously by the LOW-to-HIGH transition of the clock input. The direction of counting is determined by the \overline{U}/D input signal, as indicated in the Mode Select Table. When counting is to be enabled, the \overline{CE} signal can be made LOW when the clock is in either state. However, when counting is to be inhibited, the LOW-to-HIGH \overline{CE} transition must occur only while the clock is HIGH. Similarly, the \overline{U}/D signal should only be changed when either \overline{CE} or the clock is HIGH. These restrictions do not apply to the 'LS190 and 'LS191; \overline{CE} and \overline{U}/D can be changed with the clock in either state, provided only that the recommended setup and hold times are observed.

Two types of outputs are provided as overflow/underflow indicators. The Terminal Count (TC) output is normally LOW and goes HIGH when a circuit reaches zero in the count-down mode or reaches maximum (9 for the '190, 15 for the '191) in the count-up mode. The TC output will then remain HIGH until a state change occurs, whether by counting or presetting or until \overline{U}/D is changed. The TC output should not be used as a clock signal because it is subject to decoding spikes.

The TC signal is also used internally to enable the Ripple Clock (\overline{RC}) output. The \overline{RC} output is normally HIGH. When \overline{CE} is LOW and TC is HIGH, the \overline{RC} output will go LOW when the clock next goes LOW and will stay LOW until the clock goes HIGH again. This feature simplifies the design of multi-stage counters, as indicated in *Figures a and b*. In *Figure a*, each \overline{RC} output is used as the clock input for the next higher stage. This configuration is particularly advantageous when the clock source has a limited drive capability, since it drives only the first stage. To prevent counting in all stages it is only necessary to inhibit the first stage, since a HIGH signal on \overline{CE} inhibits the \overline{RC} output pulse, as indicated in the \overline{RC} Truth Table. A disadvantage of this configuration, in some applications, is the timing skew between state changes in the first and last stages. This represents the cumulative delay of the clock as it ripples through the preceding stages.

A method of causing state changes to occur simultaneously in all stages in shown in *Figure b*. All clock inputs are driven in parallel and the RC outputs propagate the carry/borrow signals in ripple fashion. In this configuration the LOW state duration of the clock must be long enough to allow the negative-going edge of the carry/borrow signal to ripple through to the last stage before the clock goes HIGH. There is no such restriction on the HIGH state duration of the clock, since the RC output of any package goes HIGH shortly after its CP input goes HIGH.

The configuration shown in *Figure c* avoids ripple delays and their associated restrictions. The \overline{CE} input for a given stage is formed by combining the TC signals from all the preceding stages. Note that in order to inhibit counting an enable signal must be included in each carry gate. The simple inhibit scheme of *Figures a and b* doesn't apply, because the TC output of a given stage is not affected by its own \overline{CE} .





Fig. b Synchronous N-Stage Counter Using Ripple Carry/Borrow



Fig. c Synchronous N-Stage Counter with Parallel Gated Carry/Borrow



190

<u>190</u>

| MBOL | PARAMETER | 54/74 | 54/74LS | UNITS | CONDITIONS | | |
|--|--|--|------------------------|-------------|---|--|--|
| | | Min Max | Min Max | | | | |
| lcc | Power Supply Current XM | 99 105 | 35 35 | mA | V _{CC} = Max All Inputs = Gnd | | |
| AC CHAR | ACTERISTICS: $V_{CC} = +5.0 \text{ V}, \text{ T}_{\text{A}} =$ | = +25° C (See \$ | Section 3 for | waveforms a | and load configurations) | | |
| | | 54/74 | 54/74LS | UNITS | CONDITIONS | | |
| SYMBOL | PARAMETER | $C_L = 15 \text{ pF}$ $R_L = 400 \Omega$ | C _L = 15 pF | | | | |
| | | Min Max | Min Max | | | | |
| fmax | Maximum Count Frequency | 20 | 20 | MHz | | | |
| tPLH tPHL | Propagation Delay CP to Q _n | 24 36 | 24 36 | ns | Figs. 3-1, 3-8 | | |
| tPLH tPHL | Propagation Delay CP to TC | 42 52 | 42 52 | ns |] | | |
| tPLH tPHL | Propagation Delay CP to RC | 20 24 | 20 24 | ns | | | |
| tplh tphl | Propagation Delay Pn to Qn | 22 50 | 22 50 | ns | Figs. 3-1, 3-5 | | |
| tPLH tPHL | Propagation Delay CE to RC | 33 33 | 33 33 | ns | | | |
| tPLH tPHL | Propagation Delay PL to Qn | 33 50 | 33 50 | ns | Figs. 3-1, 3-16 | | |
| tPLH tPHL | Propagation Delay U/D to RC | 45 45 | 45 45 | ns | | | |
| tPLH tPHL | Propagation Delay U/D to TC | 33 33 | 33 33 | ns | Fig. 3-1, Fig. d | | |
| | TING REQUIREMENTS: V _{CC} = + | 5.0 V. TA = +2 | 25°C | | | | |
| | | 54/74 | | | | | |
| SYMBOL | PARAMETER | Min Max | Min Max | UNITS | CONDITIONS | | |
| ts (H) ts (L) | Setup Time HIGH or LOW P_n to \overline{PL} | 20 20 | 20 20 | ns | Fig. 3-12 | | |
| t _h (H) t _h (L) | Hold Time HIGH or LOW P_n to \overline{PL} | 0 | 5.0 5.0 | ns | Fig. 3-13 | | |
| ts (L) | Setup Time LOW CE to CP | 20 | 20 | ns | — Fig. 3-6 | | |
| t _h (L) | Hold Time LOW CE to CP | 0 | 0 | ns | | | |
| | CP Pulse Width LOW | 25 | 20 | ns | Fig. 3-8 | | |
| t _w (L) | | | | | | | |
| tw (L) tw (L) | PL Pulse Width LOW | 35 | 35 | ns | Fig. 3-16 | | |