

FUNCTIONAL DESCRIPTION — The '192 and '193 are asynchronously presettable decade and 4-bit binary synchronous up/down (reversible) counters. The operating modes of the '192 decade counter and the '193 binary counter are identical, with the only difference being the count sequences as noted in the State Diagram. Each circuit contains four master/slave flip-flops, with internal gating and steering logic to provide master reset, individual preset, count up and count down operations.

Each flip-flop contains JK feedback from slave to master such that a LOW-to-HIGH transition on its T input causes the slave, and thus the Q output to change state. Synchronous switching, as opposed to ripple counting, is achieved by driving the steering gates of all stages from a common Count Up line and a common Count Down line, thereby causing all state changes to be initiated simultaneously. A LOW-to-HIGH transition on the Count Up input will advance the count by one; a similar transition on the Count Down input will decrease the count by one. While counting with one clock input, the other should be held HIGH. Otherwise, the circuit will either count by twos or not at all, depending on the state of the first flip-flop, which cannot toggle as long as either Clock input is LOW.

The Terminal Count Up (\overline{TC}_U) and Terminal Count Down (\overline{TC}_D) outputs are normally HIGH. When a circuit has reached the maximum count state (9 for the '192, 15 for the '193), the next HIGH-to-LOW transition of the Count Up Clock will cause \overline{TC}_U to go LOW. \overline{TC}_U will stay LOW until CPU goes HIGH again, thus effectively repeating the Count Up Clock, but delayed by two gate delays. Similarly, the \overline{TC}_D output will go LOW when the circuit is in the zero state and the Count Down Clock goes LOW. Since the \overline{TC} outputs repeat the clock waveforms, they can be used as the clock input signals to the next higher order circuit in a multistage counter.

$$\overline{TC}_{U} = Q_{0} \bullet Q_{3} \bullet \overline{CP}_{U}$$
$$\overline{TC}_{D} = \overline{Q}_{0} \bullet \overline{Q}_{1} \bullet \overline{Q}_{2} \bullet \overline{Q}_{3} \bullet \overline{CP}_{D}$$

Each circuit has an asynchronous parallel load capability permitting the counter to be preset. When the Parallel Load (\overrightarrow{PL}) and the Master Reset (MR) inputs are LOW, information present on the Parallel Data inputs ($P_0 - P_3$) is loaded into the counter and appears on the outputs regardless of the conditions of the clock inputs. A HIGH signal on the Master Reset input will disable the preset gates, override both Clock inputs, and latch each Q output in the LOW state. If one of the Clock inputs is LOW during and after a reset or load operation, the next LOW-to-HIGH transition of that Clock will be interpreted as a legitimate signal and will be counted.



MODE SELECT TABLE

MR	PL	CPu	CPD	MODE
н	х	х	х	Reset (Asyn.)
L	L	X	Х	Preset (Asyn.)
L	н	н	н	No Change
L	н	7	н	Count Up
L	н	н		Count Down

H = HIGH Voltage Level L = LOW Voltage Level X = Immaterial STATE DIAGRAM



DC CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE (unless otherwise specified)

SYMBOL	PARAMETER		54/74		54/74LS		UNITS	CONDITIONS
01111202			MIn	Max	Min	Max	0.0.10	001121110110
los	Output Short Circuit Current	XM XC	-20 -18	-65 -65	-20 -20	-100 -100	mA	V _{CC} = Max
lcc	Power Supply Current	XM XC		89 102		34 34	mA	V _{CC} = Max; MR, PL = Gnd Other Inputs = 4.5 V

AC CHARACTERISTICS: V_{CC} = +5.0 V, T_A = +25°C (See Section 3 for waveforms and load configurations)

		54/74	54/74LS		
SYMBOL	PARAMETER	CL = 15 pF RL = 400 Ω	C _L = 15 pF	UNITS	CONDITIONS
		Min Max	Min Max		
fmax	Maximum Count Frequency	25	30	MHz	Figs. 3-1, 3-8
tPLH tPHL	Propagation Delay CP_U or CP_D to Q_n	38 47	31 28	ns	
tPLH tPHL	Propagation Delay CPU to TCU	26 24	16 21	ns	Figs. 3-1, 3-5
tPLH tPHL	Propagation Delay CP _D to TC _D	24 24	16 24		
tPLH tPHL	Propagation Delay P _n to Q _n		20 30	ns	Figs. 3-1, 3-5
tPLH tPHL	Propagation Delay PL to Q _n	40 40	32 30	ns	Figs. 3-1, 3-16
tPHL .	Propagation Delay, MR to Qn	35	25	.10	

SYMBOL	PARAMETER	54/74		54/74LS		UNITS	CONDITIONS
		Min	Max	Min	Max	UNITO	
t _s (H) t _s (L)	Setup Time HIGH or LOW P_n to PL	20 20		20 10		ns	Fig. 3-13 CP _U = CP _D = LOW
t _h (H) t _h (L)	Hold Time HIGH or LOW P_n to \overline{PL}	0 3.0		3.0 3.0			
t _w (L)	CP Pulse Width LOW	20		17		ns	Fig. 3-8
t _w (L)	PL Pulse Width LOW	20		20			
t _w (H)	MR Pulse Width HIGH	20		15		ns	Fig. 3-16
trec	Recovery Time, MR to CP	6.0		3.0			1 19. 0 10
trec	Recovery Time, PL to CP	6.0		10			