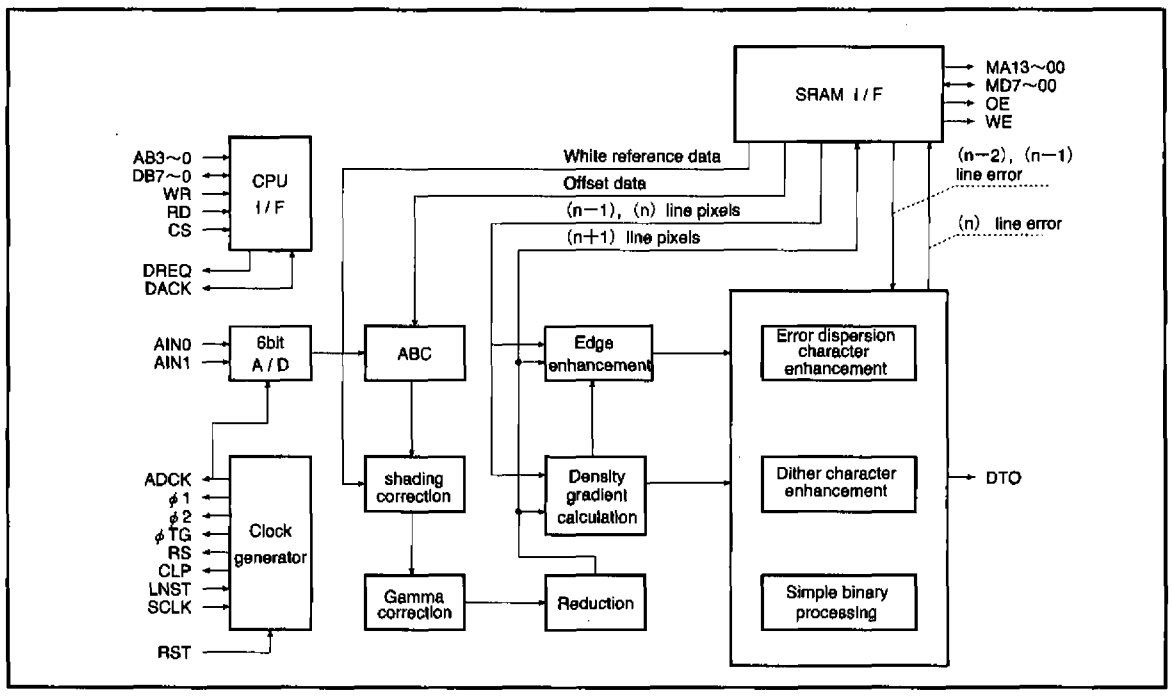
Gray scale processor (32 tones)
BU2134AK

The BU2134AK is an LSI designed for use in image scanners and facsimile machines, with a function which takes analog image signals output from an image sensor in an image processing device and converts them to binary format.
This product is equipped with an internal 6-bit A/D converter, image sensor control circuit, and CPU interface, and can be configured easily for data reading.

●Applications
Facsimile machines, word processors, and other similar devices

●Features
1) Internal 6-bit A/D converter. (internal data width after shading : 5 bits)
2) Shading correction function.
3) ABC (Auto Background Control) function.
4) Pseudo intermediate processing based on organizational dither method.
5) Pseudo intermediate processing based on error dispersion method.
6) Simple binary processing.
7) 2-dimensional edge enhancement and 2-dimensional character enhancement.
8) γ correction.
9) Reduction in horizontal direction.

●Block diagram



●Absolute maximum ratings (Unless otherwise noted, Ta=25℃, V_{DD}=5V)

Parameter	Symbol	Limits	Unit
Power supply voltage	V_{DD}	−0.3～7.0	V
Input voltage	V_{IN}	−0.3～V_{DD}+0.3	V
Analog power supply voltage	AV_{DD}	−0.3～V_{DD}+0.3	V
Analog input voltage	AV_{IN}	−0.3～AV_{DD}+0.3	V
Operating temperature	Topr	0～70	℃
Storage temperature	Tstg	−55～150	℃
Input current	I_{IN}	±20	mA
Output current	Io	±20	mA
Power dissipation	Pd	800*	mW

* Reduced by 8mW for each increase in Ta of 1℃ over 25℃.

●Recommended operating conditions (Unless otherwise noted, Ta=25℃, V_{DD}=5V)

Parameter	Symbol	Min.	Typ.	Max.	Unit
Power supply voltage	V_{DD}	4.75	5	5.25	V
Input voltage	V_{IN}	0	—	V_{DD}	V
Analog power supply voltage	AV_{DD}	0	—	V_{DD}	V
Analog ground voltage	A_{GND}	—	0	—	V
Reference voltage +	R_{EF}+	3	—	AV_{DD}	V
Reference voltage −	R_{EF}−	0	—	1	V
Analog input voltage	A_{IN}	R_{EF}−	—	R_{EF}+	V

●Pin description

Parameter	Pin Name	I/O	Function
Video signal output	DTO	Output	Outputs binary video signal as serial data.
Line memory interface	MA13~MA00	Output	Outputs external SRAM address; MA13 is MSB.
	MD7~MD0	Input/Output	Data bus for external SRAM; MD7 is MSB.
	$\overline{OE}$	Output	Output Enable signal for external SRAM (negative logic)
	$\overline{WE}$	Output	Write Enable signal for external SRAM (negative logic)
CPU interface	AB3~AB0	Input	Address input pin; AB3 is MSB.
	DB7~DB0	Input/Output	Data input/output pin; DB7 is MSB.
	$\overline{WR}$	Input	Write input pin for setting internal register (negative logic)
	$\overline{RD}$	Input	Read input pin for reading internal register (negative logic)
	DREQ	Output	Outputs DMA Request signal in parallel mode. Outputs DTO latch clock in serial mode.
	$\overline{DACK}$	Input/Output	Inputs DMA Acknowledge signal in parallel mode (negative logic). Outputs DTO Enable signal in serial mode (negative logic).
	$\overline{CS}$	Input	Chip Select input pin which enables access to internal register (negative logic)
	$\overline{RST}$	Input	System reset input pin (negative logic)
System clock	SCLK	Input	System clock input pin
Line start	$\overline{LNST}$	Input	Inputs line start signal.
Image sensor interface	ϕ1	Output	Output pin 1 for image sensor drive clock
	ϕ2	Output	Output pin 2 for image sensor drive clock
	RS	Output	Image sensor reset signal output pin.
	ϕTG	Output	Image sensor transfer gate pulse output pin.
	CLP	Output	Analog ground signal
Analog interface	AIN0	Input	Inputs image sensor analog video signals.
	AIN1	Input	Inputs analog signals (such as temperature sensor).
	REF+	—	Connect this to reference voltage of the A/D converter full-scale point.
	REF−	—	Connect this to reference voltage of the A/D converter zero point.
Power supply/ground	V_{DD}	—	Connect this to the digital power supply (+5 V) (Pin 3).
	GND	—	Connect this to the digital ground (Pin 4).
	AV_{DD}	—	Connect this to the analog power supply (Pin 1).
	AGND	—	Connect this to the analog ground (Pin 1).

●Pin descriptions

Pin No.	I / O	Pin Name	Pin No.	I / O	Pin Name	Pin No.	I / O	Pin Name	Pin No.	I / O	Pin Name
1	O	MA00	17	O	OE	33	I / O	DB5	49	V	AV_{DD}
2	O	MA01	18	O	WE	34	I / O	DB6	50	I	AIN 0
3	O	MA02	19	I / O	MD0	35	I / O	DB7	51	I	AIN 1
4	O	MA03	20	I / O	MD1	36	I	AB0	52	—	REF+
5	O	MA04	21	I / O	MD2	37	I	AB1	53	—	REF−
6	O	MA05	22	I / O	MD3	38	I	AB2	54	G	AGND
7	O	MA06	23	I / O	MD4	39	I	AB3	55	—	NC
8	G	GND	24	G	GND	40	G	GND	56	V	V_{DD}
9	V	V_{DD}	25	I / O	MD5	41	V	V_{DD}	57	O	ϕ1
10	O	MA07	26	I / O	MD6	42	I / O	DACK	58	O	ϕ2
11	O	MA08	27	I / O	MD7	43	O	DREQ	59	O	RS
12	O	MA09	28	I / O	DB0	44	I	WR	60	O	ϕTG
13	O	MA10	29	I / O	DB1	45	I	RD	61	O	CLP
14	O	MA11	30	I / O	DB2	46	I	CS	62	O	DTO
15	O	MA12	31	I / O	DB3	47	I	RST	63	G	GND
16	O	MA13	32	I / O	DB4	48	I	LNST	64	I	SCLK

TTL level input: WR, RD, DACK, DB0 to DB7, MD0 to MD7, AB0 to AB4

CMOS level input: SCLK, LNST, RST, CS

●Pin assignments

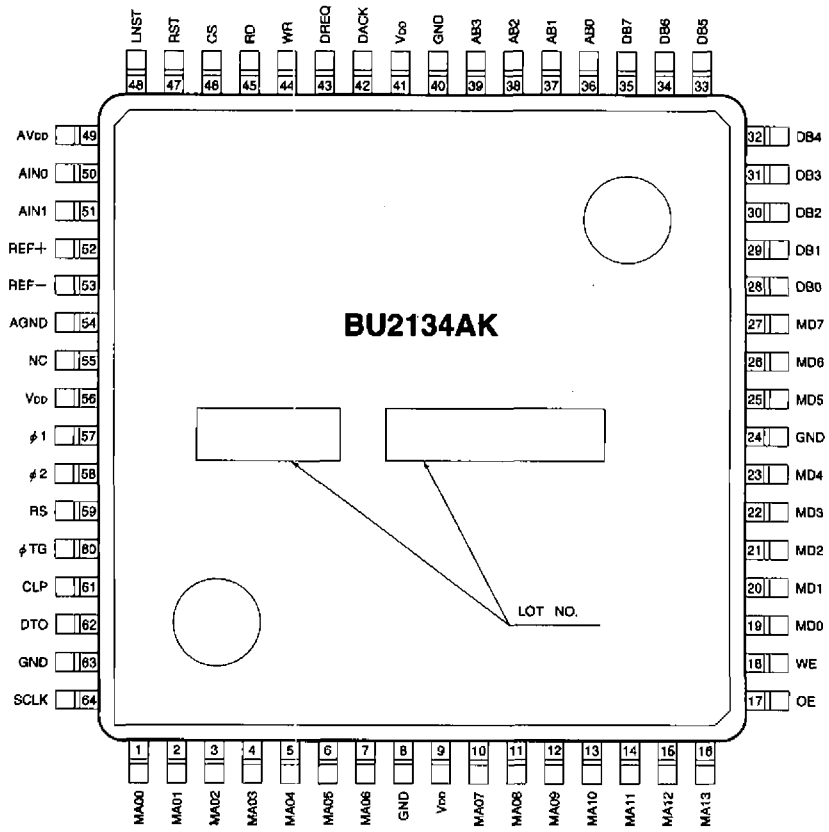
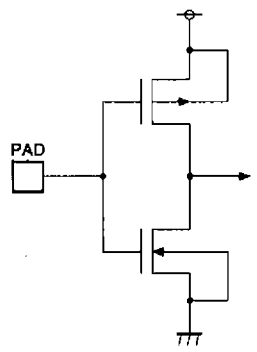
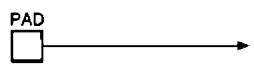


Fig. 1

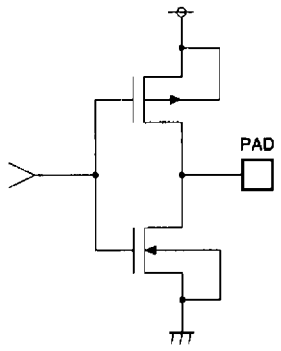
●Input/output circuits



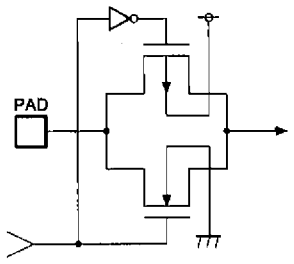
CMOS input, TTL input



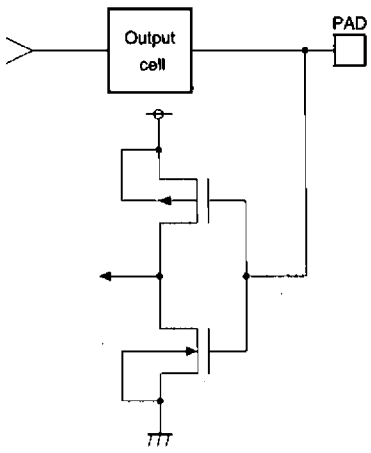
Reference voltage



CMOS output



Analog input



Bi-directional CMOS, bi-directional TTL

●Electrical characteristics

DC characteristics (Unless otherwise noted, Ta=25℃, V_{DD}=5V)

Parameter	Symbol	Min.	Typ.	Max.	Unit	Conditions
Input voltage "H"	V_{IH}	3.5	—	V_{DD}	V	CMOS level
Input voltage "L"	V_{IL}	0	—	1.5	V	CMOS level
Input voltage "H"	V_{IH}	2.4	—	V_{DD}	V	TTL level
Input voltage "L"	V_{IL}	0	—	0.8	V	TTL level
Input current "H"	I_{IH}	—	—	−10	μA	$V_{IH}=V_{DD}$
Input current "L"	I_{IL}	—	—	10	μA	V_{IL}=GND
Output current "H"	I_{OH}	−1.0	—	—	mA	$V_{OH}=V_{DD}-0.4V$
Output current "L"	I_{OL}	3.2	—	—	mA	V_{OL}=0.4V
Output leakage current	I_{OZ}	—	—	±10	μA	$V_O=V_{DD}$ or GND
Static current consumption	I_{ST}	—	—	100	μA	$V_I=V_{DD}$ or GND

●Switching characteristics (Unless otherwise noted, Ta=25℃, V_{DD}=5V)

Parameter		No.	Min.	Typ.	Max.	Unit
System clock	System clock cycle, tcyc	1	100	—	—	ns
	System clock pulse width "H", twh	2	40	—	—	ns
	System clock pulse width "L" ,twl	3	40	—	—	ns
CPU interface	CS ~ WR, RD setup time	4	0	—	—	ns
	AB ~ WR, RD setup time	5	20	—	—	ns
	DB ~ WR setup time	6	50	—	—	ns
	WR, RD pulse width	7	100	—	—	ns
	WR, RD ~ CS hold time	8	0	—	—	ns
	WR, RD ~ AB hold time	9	20	—	—	ns
	WR ~ DB hold time	10	20	—	—	ns
	RD ~ DB hold time	10	0	—	—	ns
SRAM interface	Read cycle time	11	—	tcyc	—	ns
	MA, MCS ~ OE setup time	12	—	twh	—	ns
	OE pulse width	13	—	twl	—	ns
	OE ~ MA, MCS hold time	14	0	—	—	ns
	Write cycle time	15	—	tcyc	—	ns
	MA, MCS ~ WE setup time	16	—	twh	—	ns
	MD ~ WE setup time	17	—	twl	—	ns
	WE pulse width	18	—	twl	—	ns
	WE ~ MA, MCS hold time	19	0	—	—	ns
	WE ~ MD hold time	20	0	—	—	ns

●Data input/output timing

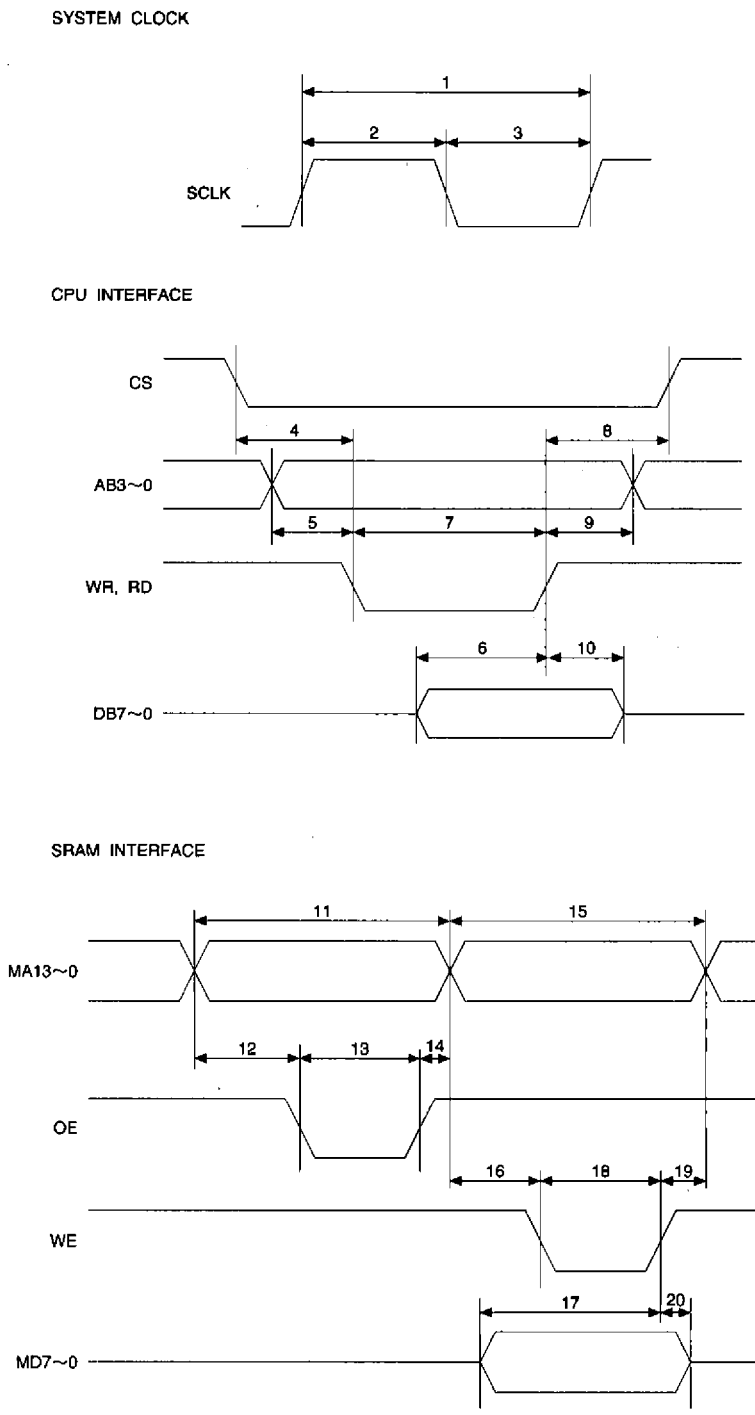


Fig. 2

●Description of register functions

Address	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0	R	W
0	＊8	＊7	＊6	＊5	＊4	＊3	＊2	＊1	○	○
1	＊14	＊13			＊12	＊11	＊10	＊9	×	○
2	0	＊20	＊19		＊18	＊17	＊16	＊15	×	○
3	Line clamp/start position MSB is #				0	＊21			×	○
4	#	Line clamp/end position							×	○
5	Distortion correction start position								×	○
6	0	ABC start position							×	○
7	ABC end position								×	○
8	＊22								○	○
9	＊23								×	○
A	＊25				＊24				×	○
B	＊27		0		＊26				×	○
C	＊29				＊28				×	○
D	＊31				＊30				×	○
E	0	＊33			＊32				×	○

＊1 White reference screen scan (read enabled)
When 0 : Stop
When 1 : Start
＊2 Offset scan (read enabled)
When 0 : Stop
When 1 : Start
＊3 Binary processing (read enabled)
When 0 : Stop
When 1 : Start
＊4 ABC Enable (read enabled)
When 0 : Off
When 1 : On
＊5 ABC initialization
When 0 : Off
When 1 : On
＊6 Data table/Write Enable
When 0 : Writing of data table to Address 8 is off
When 1 : Writing of data table to Address 8 is on
1) For simple binary processing : 5 bits × 32 words (gamma correction data)
2) For dither method : 5 bits × 64 words (slice data)
3) For error dispersion method : 5 bits × 32 words (density adjustment data)
＊7 White reference data/Write Enable
When 0 : Writing of white reference data to Address 8 is off
When 1 : Writing of white reference data to Address 8 is on
＊8 White reference data/Read Enable
When 0 : Reading of white reference data from Address 8 is off
When 1 : Reading of white reference data from Address 8 is on
＊9 Binary video signal output mode
When 0 : Binary video signals are output as serial data.
When 1 : Binary video signals are output as parallel data.
＊10 Parallel mode specification
When 0 : First bit of binary video signal is taken as LSB.
When 1 : First bit of binary video signal is taken as MSB.
＊11 Binary video signal selection
When 0 : Black = 0, White = 1
When 1 : Black = 1, White = 0

*12 Offset correction
When 0 : Off
When 1 : On
*13 Internal sample / hold timing
When 000 : Sampled at S1 cycle
When 001 : Sampled at S2 cycle
When 010 : Sampled at S3 cycle
When 011 : Sampled at S4 cycle
When 100 : Sampled at S5 cycle
When 101 : Sampled at S6 cycle
When 110 : Sampled at S7 cycle
When 111 : Sampled at S0 cycle
*14 A / D converter channel switching
When 0 : Connected to AIN0
When 1 : Connected to AIN1
*15 Image sensor
When 0 : CCD
When 1 : CIS
*16 ϕTG output logic
When 0 : Positive logic
When 1 : Negative logic
*17 RS and CLP output logic
When 0 : Positive logic
When 1 : Negative logic
*18 Clamping method
When 0 : Bit clamping
When 1 : Line clamping
*19 ϕ1 clock and RS output specification
1) ϕ1 clock duty (when using CIS)
When 00 : HIGH for S0 to S3 cycles, LOW for S4 to S7 cycles
When 01 : HIGH for S0 to S3 cycles, LOW for S4 to S7 cycles
When 10 : HIGH for S0 to S1 cycles, LOW for S2 to S7 cycles
When 11 : HIGH for S0 to S5 cycles, LOW for S6 to S7 cycles
2) RS output position (when using CCD)
When 00 : Output at S5 cycle
When 01 : Output at S6 cycle
*20 ϕTG pulse width
When using CCD
When 0 : Output at S1 to S6 cycles
When 1 : Output at S0 to S7 cycles
When using CIS
When 0 : Output at S1 to S0 cycles
When 1 : Output at S0 to S7 cycles
*21 Original width specification

DB2	DB1	DB0	Distortion correction width	Reading width	Reading position
0	0	0	1728	1728 (A4, 8dot / mm or equivalent)	—
0	0	1	2048	1728 (A4, 8dot / mm or equivalent)	Center
0	1	0	2048	2048 (B4, 8dot / mm or equivalent)	—
0	1	1	2432	1728 (A4, 8dot / mm or equivalent)	Center
1	0	0	2432	2048 (B4, 8dot / mm or equivalent)	Center
1	0	1	2432	2432 (A3, 8dot / mm or equivalent)	—
1	1	0	2592	2592 (A4, 12dot / mm or equivalent)	—

*22 Numerator of reduction ratio in horizontal direction
*23 Denominator of reduction ratio in horizontal direction *23
The reduction ratio is set as shown below, using Address 8 (numerator) and Address 9 (denominator).

$$\text{Reduction ratio} = \frac{(\text{value set for reduction ratio numerator}) + 1}{(\text{value set for reduction ration denominator}) + 1}$$

*24 Black follow-up speed
When 0 : ABC circuit not followed on dark background
When 1 to 15 : The larger the set value, the faster the ABC is followed on a dark background.
*25 White follow-up speed
When 0 : ABC circuit not followed on light background
When 1 to 15 : The larger the set value, the faster the ABC is followed on a light background.
*26 Binary parameter
1) For simple binary processing : Set the slice level.
2) For organizational dither processing : This parameter is invalid.
3) For error dispersion processing : Set the black level.
*27 Binary mode
When 00 : Simple binary processing
When 01 : Simple binary processing
When 10 : Pseudo intermediate processing using organizational dither method
When 11 : Pseudo intermediate processing using error dispersion method
*28 Degree of edge enhancement in horizontal direction
When 0 : Edge enhancement off
When 1 to 15 : The larger the set value, the stronger the enhancement will be.
*29 Degree of edge enhancement in vertical direction
When 0 : Edge enhancement off
When 1 to 15 : The larger the set value, the stronger the enhancement will be.
*30 Correction parameter in horizontal direction
This parameter is used as a threshold to determine whether or not edge enhancement is to be carried out when the amount of density in the horizontal direction is changed.
*31 Correction parameter in vertical direction
This parameter is used as a threshold to determine whether or not edge enhancement is to be carried out when the amount of density in the vertical direction is changed.
*32 Character enhancement parameter B
When pseudo intermediate processing is used, this parameter is used as a threshold to determine whether or not edge enhancement is to be carried out when the amount of density in both the horizontal and vertical directions is changed.
*33 Character enhancement parameter A
1) This parameter defines character enhancement when pseudo intermediate processing is used.
2) When using the dither method
When 000 : Character enhancement off
When 001 to 111 : The larger the set value, the stronger the enhancement will be.
3) When using the error dispersion method
When 000 : Character enhancement off
When 001 to 111 : The larger the set value, the stronger the enhancement will be.
*34 Resetting the internal registers of Addresses 0 to 2 clears the values to 0.
The set values for other internal registers do not change when a reset is initiated.
*35 Register setting unit
1) The line clamping start and end positions can be specified in units of 1 pixel.
2) The distortion correction start position can be specified in units of 1 pixel.
3) The ABC start and end positions can be specified in units of 16 pixels.
*36 In the following cases, Address 8 should be used for reading and writing of data.
1) Writing data tables
2) Reading and writing white reference data
3) Reading digital data after A/D conversion

●Operation timing charts

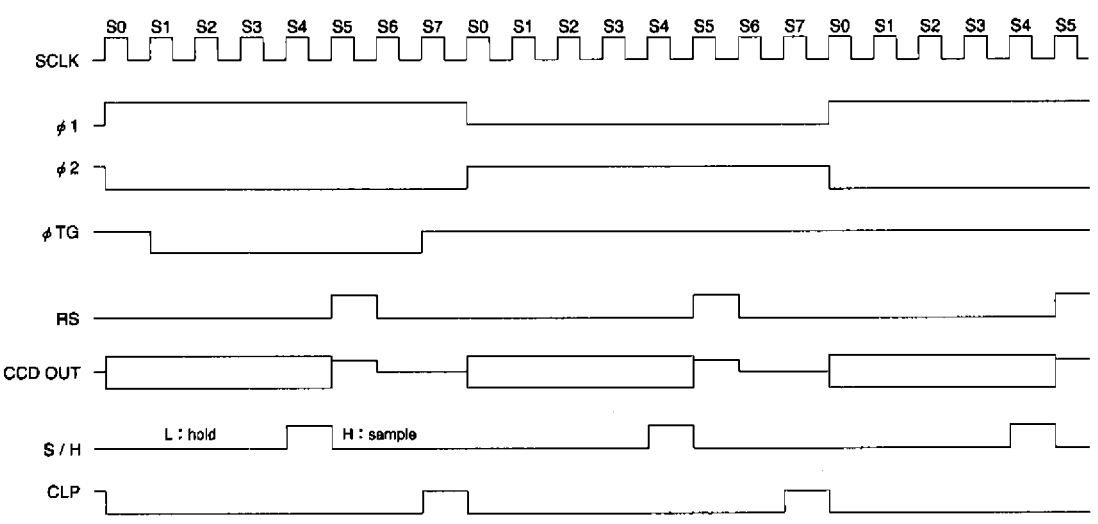


Fig. 3 CCD drive timing diagram -1

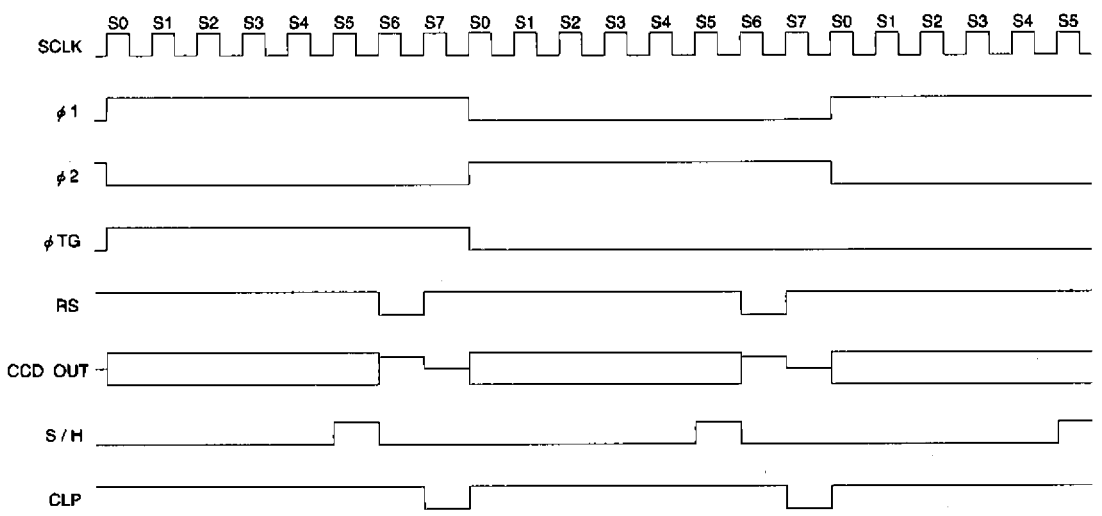


Fig. 4 CCD drive timing diagram -2

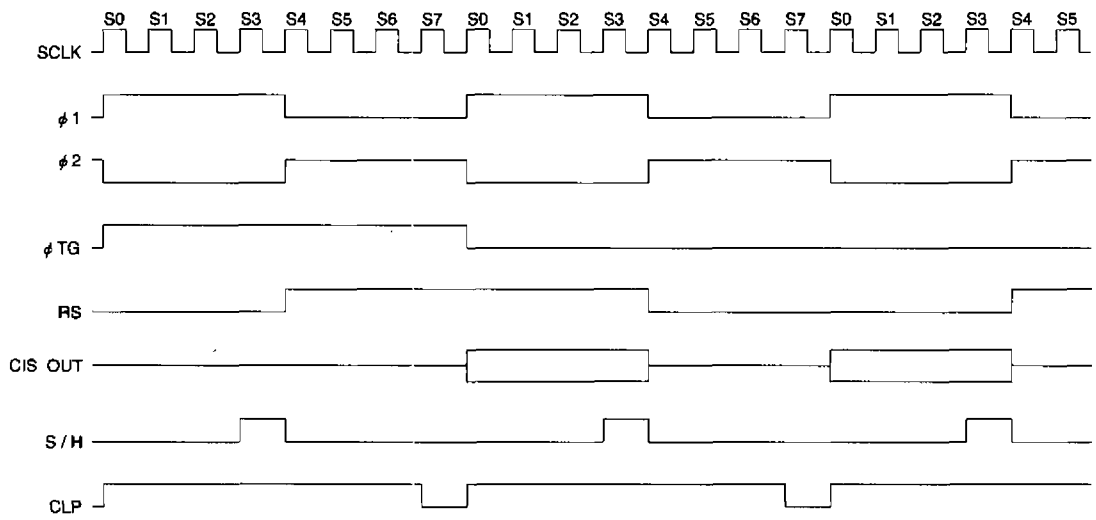
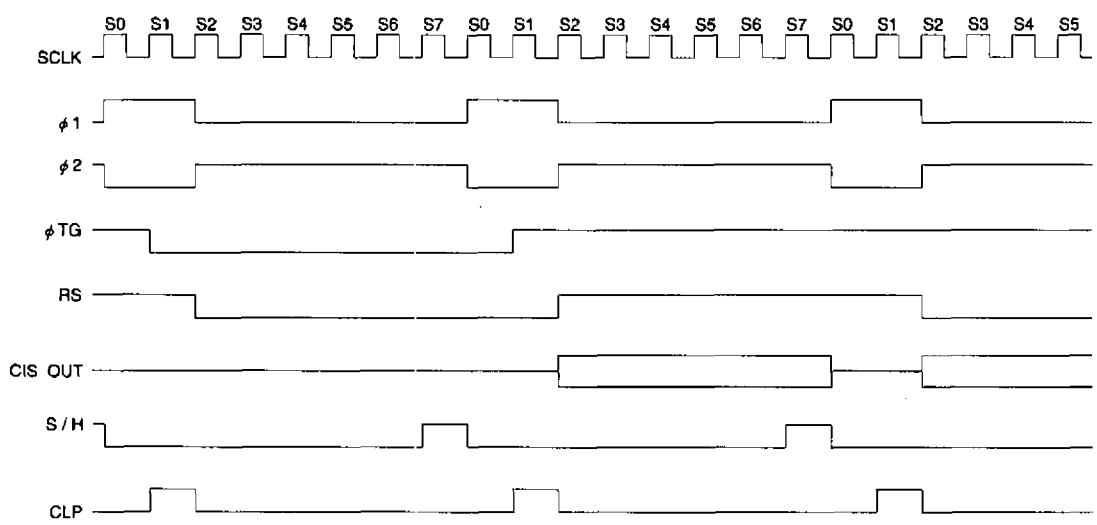


Fig. 5 CIS drive timing diagram -1



Fig, 6 CIS drive timing diagram -2

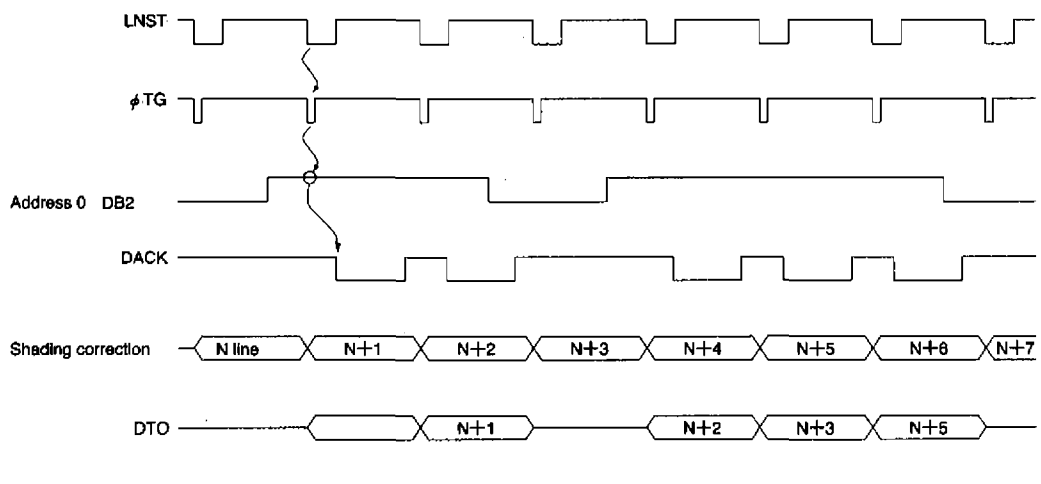


Fig. 7 Line control timing diagram

●Operation timing charts

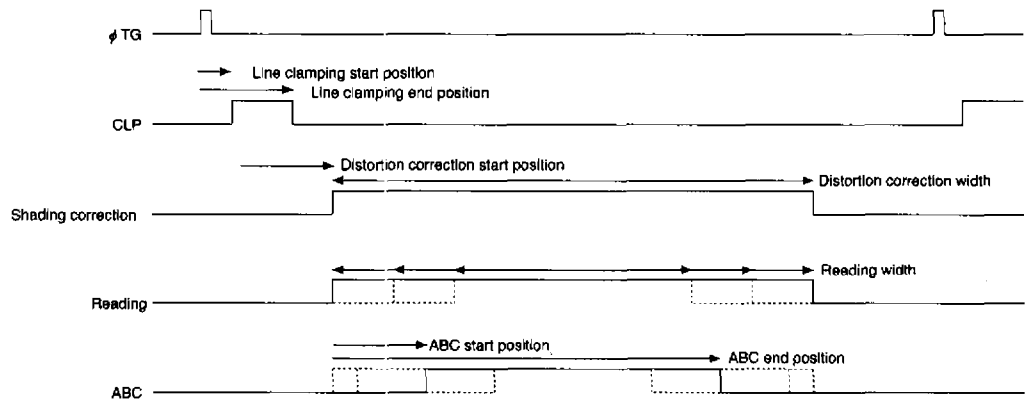


Fig. 8 Scan timing diagram

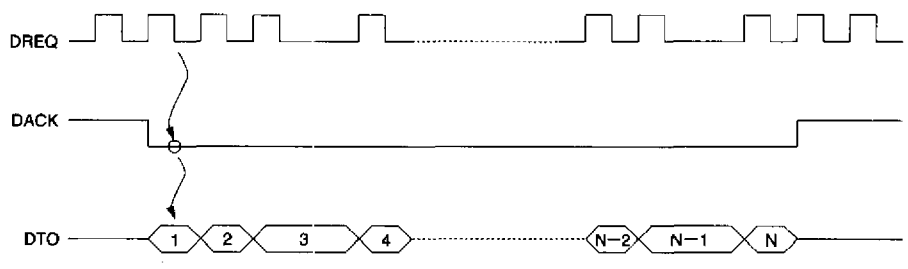


Fig. 9 Output timing diagram (serial mode)

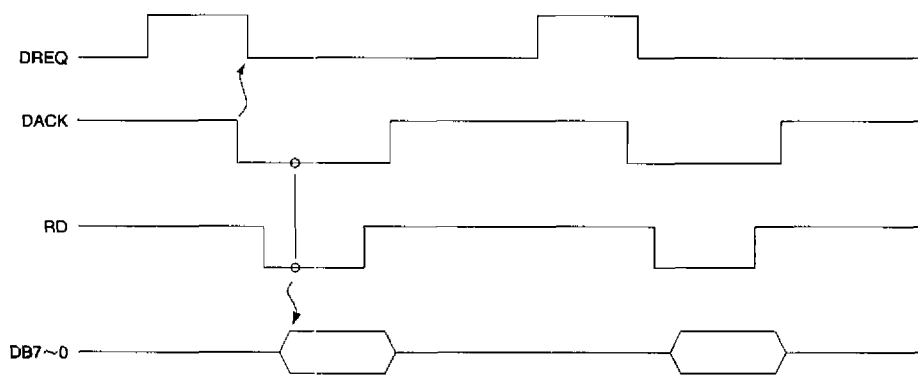


Fig. 10 Output timing diagram (parallel mode)

●Application example

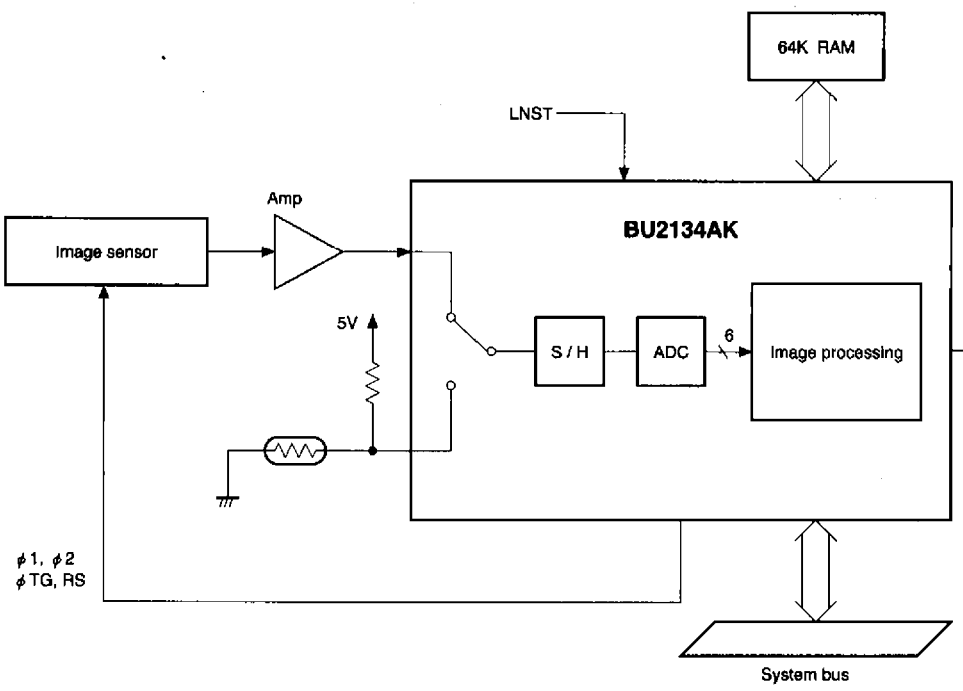
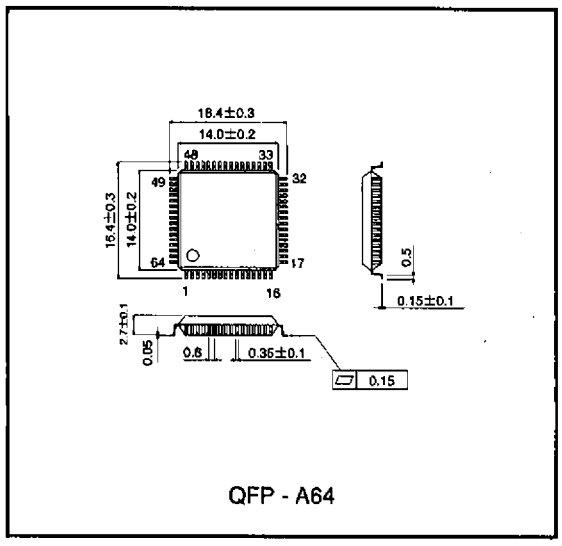


Fig. 11

●External dimensions (Units: mm)



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