National Semiconductor

DS90C031
LVDS Quad CMOS Differential Line Driver

General Description

The DS90C031 is a quad CMOS differential line driver designed for applications requiring ultra low power dissipation and high data rates. The device is designed to support data rates in excess of 155.5 Mbps (77.7 MHz) utilizing Low Voltage Differential Signaling (LVDS) technology.

The DS90C031 accepts TTL/CMOS input levels and translates them to low voltage (350 mV) differential output signals. In addition the driver supports a TRI-STATE® function that may be used to disable the output stage, disabling the load current, and thus dropping the device to an ultra low idle power state of 11 mW typical.

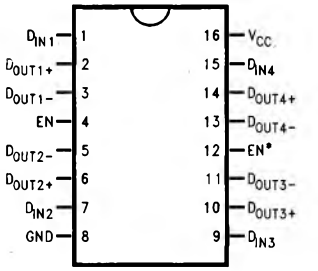
The DS90C031 and companion line receiver (DS90C032) provide a new alternative to high power psuedo-ECL devices for high speed point-to-point interface applications.

Features

- >155.5 Mbps (77.7 MHz) switching rates
- ±350 mV differential signaling
- Ultra low power dissipation
- 400 ps maximum differential skew (5V, 25°C)
- 3.5 ns maximum propagation delay
- Industrial operating temperature range
- Available in surface mount packaging (SOIC)
- Pin compatible with DS26C31, MB571 (PECL) and 41LG (PECL)
- Compatible with IEEE 1596.3 SCI LVDS standard
- Compatible with proposed TIA LVDS standard

Connection Diagram

Dual-In-Line



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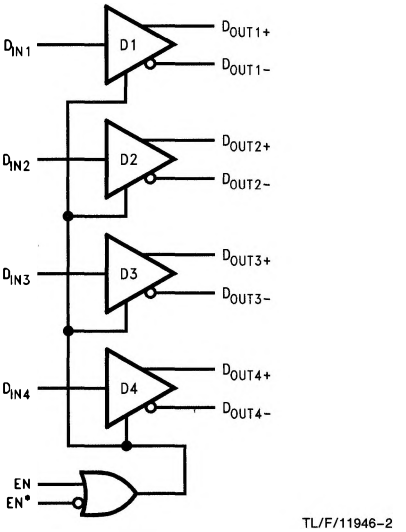
Order Number DS90C031TM
See NS Package Number M16A

Functional Diagram and Truth Tables



TL/F/11946–2

DRIVER

Enables		Input	Outputs	
EN	**EN***	**D_{IN}**	**$D_{OUT}+$**	**$D_{OUT}-$**
L	H	X	Z	Z
All other combinations of ENABLE inputs		L	L	H
		H	H	L

Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

Supply Voltage (V_{CC})	−0.3V to +6V
Input Voltage (D_{IN})	−0.3V to (V_{CC} + 0.3V)
Enable Input Voltage (EN, EN*)	−0.3V to (V_{CC} + 0.3V)
Output Voltage ($D_{OUT}+$, $D_{OUT}-$)	−0.3V to (V_{CC} + 0.3V)
Short Circuit Duration ($D_{OUT}+$, $D_{OUT}-$)	Continuous
Maximum Package Power Dissipation @ +25°C M Package	1068 mW
Derate M Package	8.5 mW/°C above +25°C
Storage Temperature Range	−65°C to +150°C
Lead Temperature Range Soldering (4 sec.)	+260°C
Maximum Junction Temperature	+150°C
ESD Rating (HBM, 1.5 kΩ, 100 pF)	≥3,500V (Note 7)

Recommended Operating Conditions

	Min	Typ	Max	Units
Supply Voltage (V_{CC})	+4.5	+5.0	+5.5	V
Operating Free Air Temperature (T_A)	−40	+25	+85	°C

Electrical Characteristics

Over supply voltage and operating temperature ranges, unless otherwise specified (Notes 2 and 3).

Symbol	Parameter	Conditions	Pin	Min	Typ	Max	Units
V_{OD1}	Differential Output Voltage	R_L = 100Ω (*Figure 1*)	$D_{OUT}-$, $D_{OUT}+$	250	345	450	mV
ΔV_{OD1}	Change in Magnitude of V_{OD1} for Complementary Output States				4	35	|mV|
V_{OS}	Offset Voltage			1.125	1.25	1.375	V
ΔV_{OS}	Change in Magnitude of V_{OS} for Complementary Output States				5	25	|mV|
V_{OH}	Output Voltage High	R_L = 100Ω			1.41	1.60	V
V_{OL}	Output Voltage Low			0.90	1.07		V
V_{IH}	Input Voltage High		D_{IN}, EN, EN*	2.0		V_{CC}	V
V_{IL}	Input Voltage Low			GND		0.8	V
I_I	Input Current	V_{IN} = V_{CC}, GND, 2.5V, or 0.4V		−10	±1	+10	μA
V_{CL}	Input Clamp Voltage	I_{CL} = −18 mA		−1.5	−0.8		V
I_{OS}	Output Short Circuit Current	V_{OUT} = 0V (Note 8)	$D_{OUT}-$, $D_{OUT}+$		−3.5	−5.0	mA
I_{OZ}	Output TRI-STATE Current	EN = 0.8V and EN* = 2.0V, V_{OUT} = 0V or V_{CC}		−10	±1	+10	μA
I_{CC}	No Load Supply Current Drivers Enabled	D_{IN} = V_{CC} or GND	V_{CC}		1.7	3.0	mA
		D_{IN} = 2.5V or 0.4V			4.0	6.5	mA
I_{CCL}	Loaded Supply Current Drivers Enabled	R_L = 100Ω All Channels V_{IN} = V_{CC} or GND (all inputs)			15.4	21.0	mA
I_{CCZ}	No Load Supply Current Drivers Disabled	D_{IN} = V_{CC} or GND EN = GND, EN* = V_{CC}			2.2	4.0	mA

Switching Characteristics

V_{CC} = +5.0V, T_A = +25°C (Notes 3, 4, 6, 9)

Symbol	Parameter	Conditions	Min	Typ	Max	Units
t_{PHLD}	Differential Propagation Delay High to Low	R_L = 100Ω, C_L = 5 pF (*Figures 2* and *3*)	1.0	2.0	3.0	ns
t_{PLHD}	Differential Propagation Delay Low to High		1.0	2.1	3.0	ns
t_{SKD} $\lvert t_{PHLD} - t_{PLHD} \rvert$	Differential Skew		0	80	400	ps
t_{SK1}	Channel to Channel Skew	Note 4	0	300	600	ps
t_{TLH}	Rise Time	R_L = 100Ω, C_L = 5 pF (*Figures 2* and *3*)		0.35	1.5	ns
t_{THL}	Fall Time			0.35	1.5	ns
t_{PHZ}	Disable Time High to Z	(*Figures 4* and *5*)		2.5	10	ns
t_{PLZ}	Disable Time Low to Z			2.5	10	ns
t_{PZH}	Enable Time Z to High			2.5	10	ns
t_{PZL}	Enable Time Z to Low			2.5	10	ns

Switching Characteristics

V_{CC} = +5.0V ±10%, T_A = −40°C to +85°C (Notes 3–6, 9)

Symbol	Parameter	Conditions	Min	Typ	Max	Units
t_{PHLD}	Differential Propagation Delay High to Low	R_L = 100Ω, C_L = 5 pF (*Figures 2* and *3*)	0.5	2.0	3.5	ns
t_{PLHD}	Differential Propagation Delay Low to High		0.5	2.1	3.5	ns
t_{SKD} $\lvert t_{PHLD} - t_{PLHD} \rvert$	Differential Skew		0	80	900	ps
t_{SK1}	Channel to Channel Skew	Note 4	0	0.3	1.0	ns
t_{SK2}	Chip to Chip Skew	Note 5			3.0	ns
t_{TLH}	Rise Time	R_L = 100Ω, C_L = 5 pF (*Figures 2* and *3*)		0.35	2.0	ns
t_{THL}	Fall Time			0.35	2.0	ns
t_{PHZ}	Disable Time High to Z	(*Figures 4* and *5*)		2.5	15	ns
t_{PLZ}	Disable Time Low to Z			2.5	15	ns
t_{PZH}	Enable Time Z to High			2.5	15	ns
t_{PZL}	Enable Time Z to Low			2.5	15	ns

Parameter Measurement Information

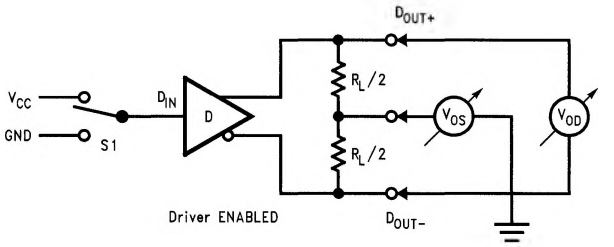


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FIGURE 1. Driver V_{OD} and V_{OS} Test Circuit

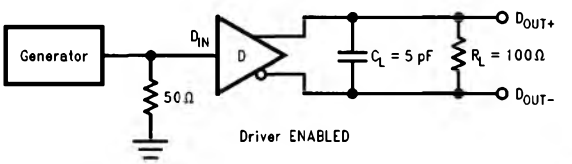

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FIGURE 2. Driver Propagation Delay and Transition Time Test Circuit

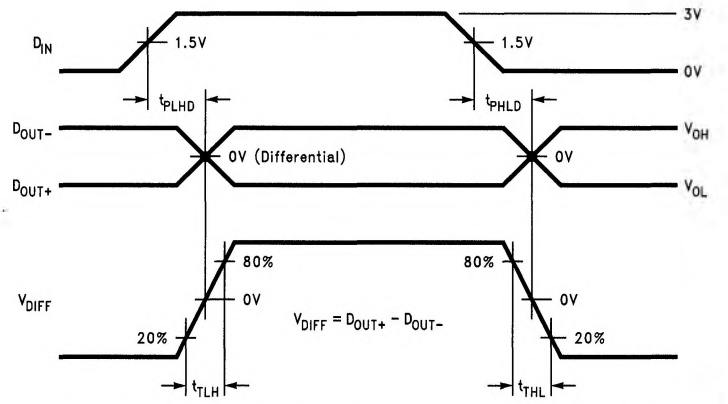

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FIGURE 3. Driver Propagation Delay and Transition Time Waveforms

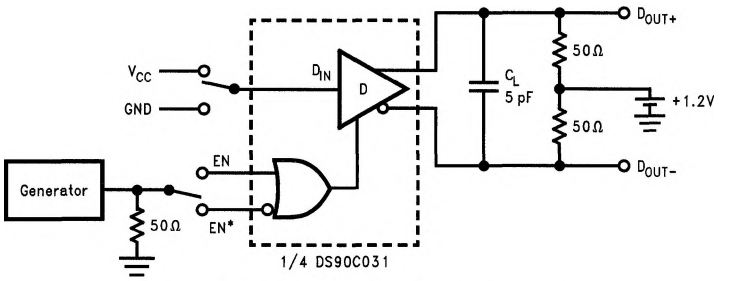

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FIGURE 4. Driver TRI-STATE Delay Test Circuit

Parameter Measurement Information (Continued)

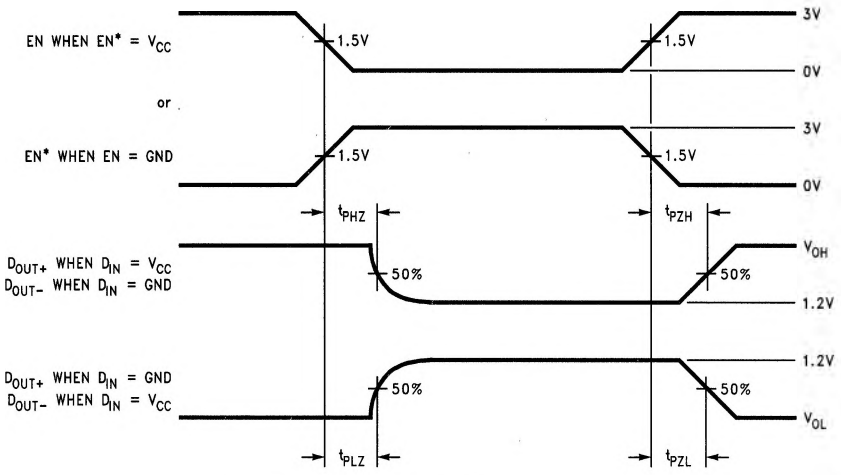

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FIGURE 5. Driver TRI-STATE Delay Waveform

Typical Application

Balanced System

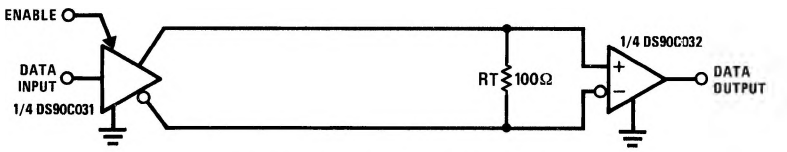

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FIGURE 6. Point-to-Point Application

Applications Information

LVDS drivers and receivers are intended to be primarily used in an uncomplicated point-to-point configuration as is shown in *Figure 6*. This configuration provides a clean signaling environment for the quick edge rates of the drivers. The receiver is connected to the driver through a balanced media which may be a standard twisted pair cable, a parallel pair cable, or simply PCB traces. Typically, the characteristic impedance of the media is in the range of 100Ω. A termination resistor of 100Ω should be selected to match the media, and is located as close to the receiver input pins as possible. The termination resistor converts the current sourced by the driver into a voltage that is detected by the receiver. Other configurations are possible such as a multireceiver configuration, but the effects of a mid-stream connector(s), cable stub(s), and other impedance discontinuities as well as ground shifting, noise margin limits, and total termination loading must be taken into account.

The DS90C031 differential line driver is a balanced current source design. A current mode driver, generally speaking has a high output impedance and supplies a constant current for a range of loads (a voltage mode driver on the other hand supplies a constant voltage for a range of loads). Current is switched through the load in one direction to produce a logic state and in the other direction to produce the other logic state. The typical output current is mere 3.4 mA, a minimum of 2.5 mA, and a maximum of 4.5 mA. The current mode **requires** (as discussed above) that a resistive termination be employed to terminate the signal and to complete the loop as shown in *Figure 6*. AC or unterminated configurations are not allowed. The 3.4 mA loop current will develop a differential voltage of 340 mV across the 100Ω termination resistor which the receiver detects with a 240 mV minimum differential noise margin neglecting resistive line losses (driven signal minus receiver threshold (340 mV–100 mV = 240 mV)). The signal is centered around +1.2V (Driver Offset, V_{OS}) with respect to ground as shown in *Figure 7*. Note that the steady-state voltage (V_{SS}) peak-to-peak swing is twice the differential voltage (V_{OD}) and is typically 680 mV.

The current mode driver provides substantial benefits over voltage mode drivers, such as an RS-422 driver. Its quiescent current remains relatively flat versus switching frequency. Whereas the RS-422 voltage mode driver increases exponentially in most case between 20 MHz–50 MHz. This is due to the overlap current that flows between the rails of the device when the internal gates switch. Whereas the current mode driver switches a fixed current between its output without any substantial overlap current. This is similar to some ECL and PECL devices, but without the heavy static I_{CC} requirements of the ECL/PECL designs. LVDS requires >80% less current than similar PECL devices. AC specifications for the driver are a tenfold improvement over other existing RS-422 drivers.

The TRI-STATE function allows the driver outputs to be disabled, thus obtaining an even lower power state when the transmission of data is not required.

The footprint of the DS90C031 is the same as the industry standard 26LS31 Quad Differential (RS-422) Driver.

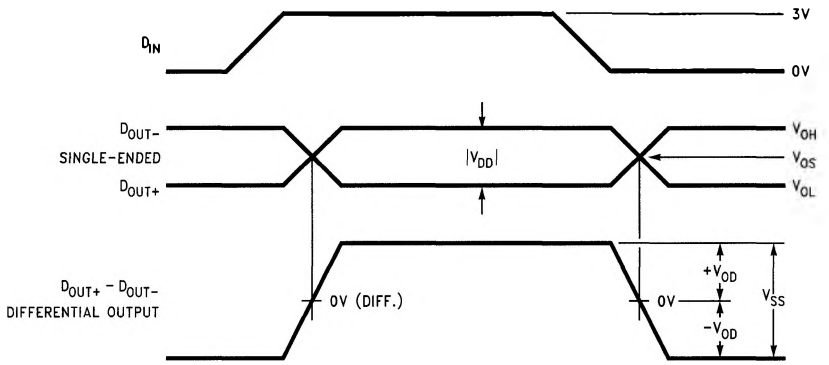

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FIGURE 7. Driver Output Levels

Pin Descriptions

Pin No.	Name	Description
1, 7, 9, 15	D_{IN}	Driver input pin, TTL/CMOS compatible
2, 6, 10, 14	$D_{OUT}+$	Non-inverting driver output pin, LVDS levels
3, 5, 11, 13	$D_{OUT}-$	Inverting driver output pin, LVDS levels
4	EN	Active high enable pin, OR-ed with EN*
12	EN*	Active low enable pin, OR-ed with EN
16	V_{CC}	Power supply pin, +5V ±10%
8	GND	Ground pin

Ordering Information

Operating Temperature	Package Type/ Number	Order Number
−40°C to +85°C	SOP/M16A	DS90C031TM

Note 1: "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. They are not meant to imply that the devices should be operated at these limits. The table of "Electrical Characteristics" specifies conditions of device operation.

Note 2: Current into device pins is defined as positive. Current out of device pins is defined as negative. All voltages are referenced to ground except: V_{OD1} and ΔV_{OD1}.

Note 3: All typicals are given for: V_{CC} = +5.0V, T_A = +25°C.

Note 4: Channel to Channel Skew is defined as the difference between the propagation delay of the channel and the other channels in the same chip with an event on the inputs.

Note 5: Chip to Chip Skew is defined as the difference between the minimum and maximum specified differential propagation delays.

Note 6: Generator waveform for all tests unless otherwise specified: f = 1 MHz, Z_O = 50Ω, $t_r \leq 6$ ns, and $t_f \leq 6$ ns.

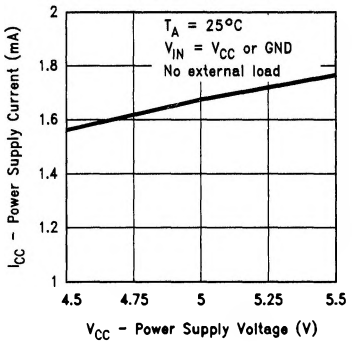
Note 7: ESD Ratings: HBM (1.5 kΩ, 100 pF) ≥ 3,500V
EIAJ (0Ω, 200 pF) ≥ 250V

Note 8: Output short circuit current (I_{OS}) is specified as magnitude only, minus sign indicates direction only.

Note 9: C_L includes probe and jig capacitance.

Typical Performance Characteristics

Power Supply Current vs Power Supply Voltage



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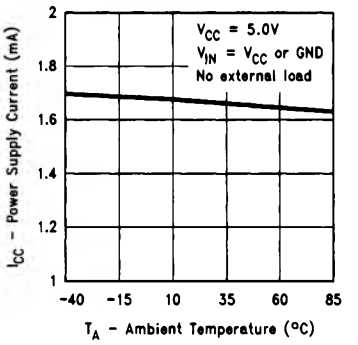
Power Supply Current vs Temperature



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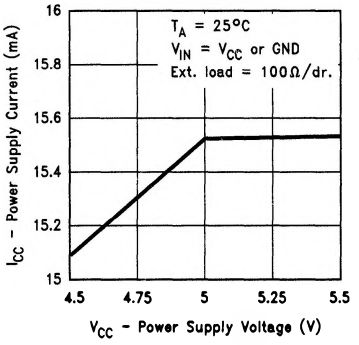
Power Supply Current vs Power Supply Voltage



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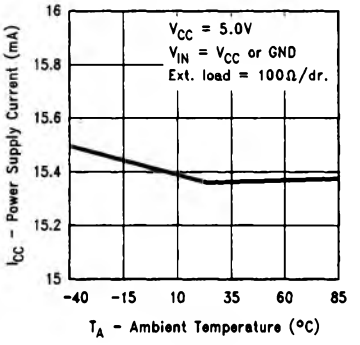
Power Supply Current vs Temperature



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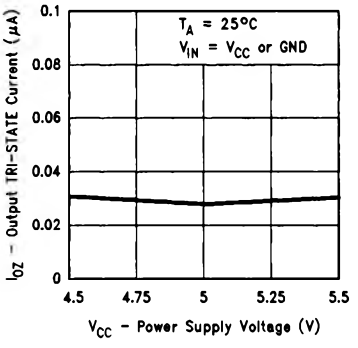
Output TRI-STATE Current vs Power Supply Voltage



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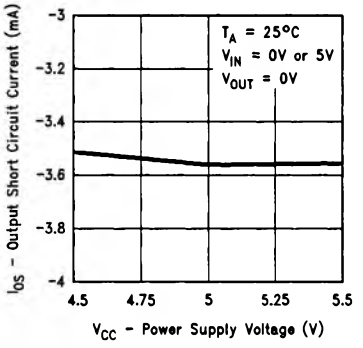
Output Short Circuit Current vs Power Supply Voltage



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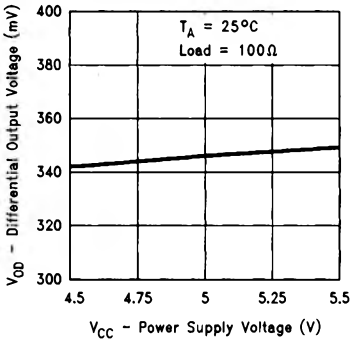
Typical Performance Characteristics (Continued)

Differential Output Voltage vs Power Supply Voltage



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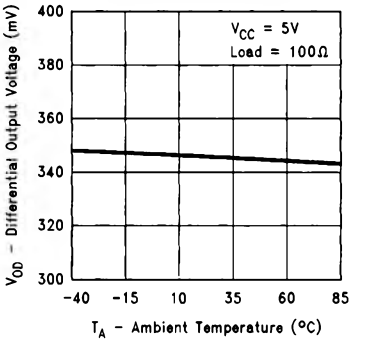
Differential Output Voltage vs Ambient Temperature



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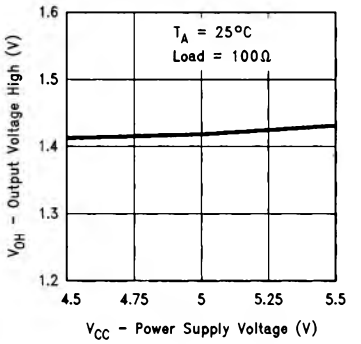
Output Voltage High vs Power Supply Voltage



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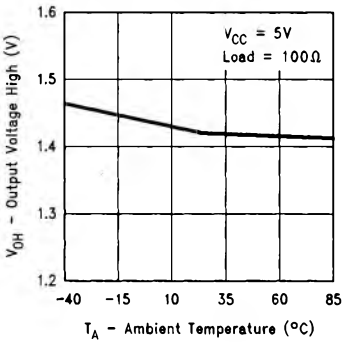
Output Voltage High vs Ambient Temperature



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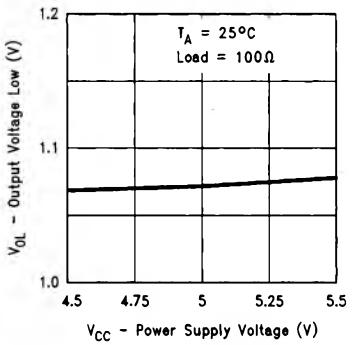
Output Voltage Low vs Power Supply Voltage



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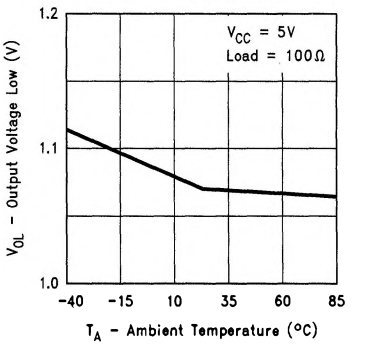
Output Voltage Low vs Ambient Temperature



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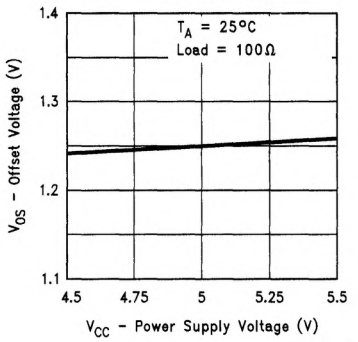
Typical Performance Characteristics (Continued)

Offset Voltage vs Power Supply Voltage



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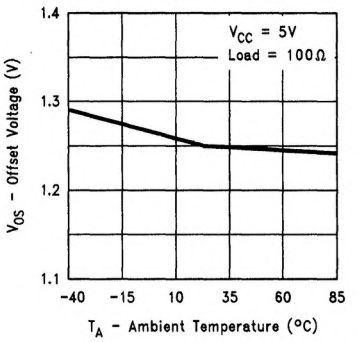
Offset Voltage vs Ambient Temperature



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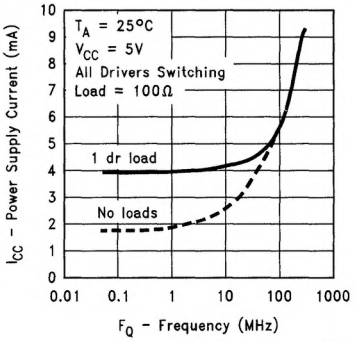
Power Supply Current vs Frequency



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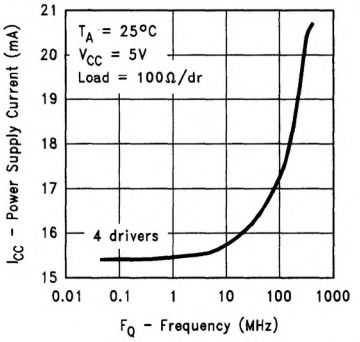
Power Supply Current vs Frequency



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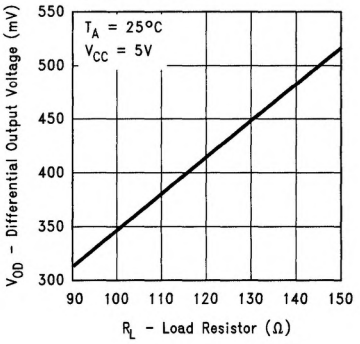
Differential Output Voltage vs Load Resistor



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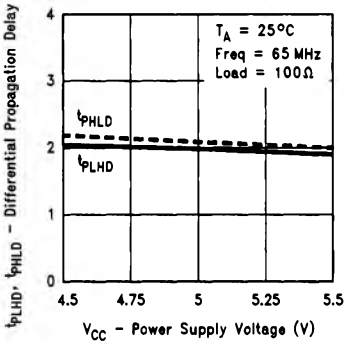
Typical Performance Characteristics (Continued)

Differential Propagation Delay vs Power Supply Voltage



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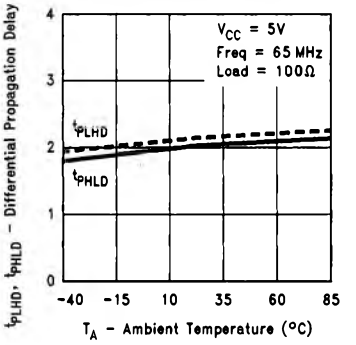
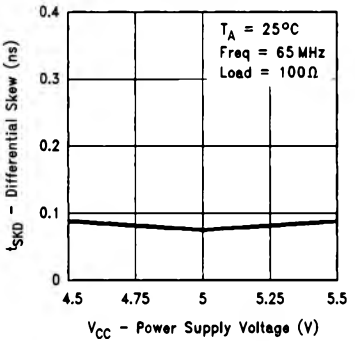
Differential Propagation Delay vs Ambient Temperature



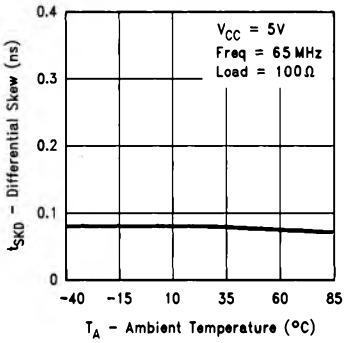
TL/F/11946–28

Differential Skew vs Power Supply Voltage



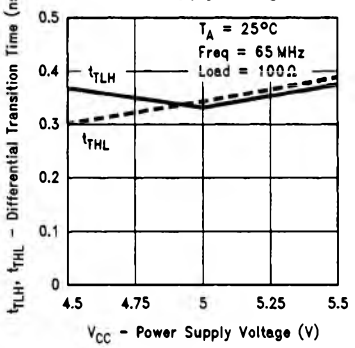
TL/F/11946–29

Differential Skew vs Ambient Temperature



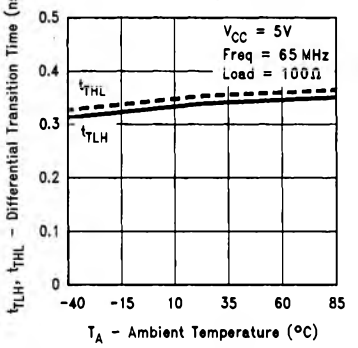
TL/F/11946–30

Differential Transition Time vs Power Supply Voltage



TL/F/11946–31

Differential Transition Time vs Ambient Temperature



TL/F/11946–32