

LB1854M

# **Three-Phase Brushless Motor Driver IC**

# **Overview**

The LB1854M is a three-phase brushless motor driver IC and is optimal, in particular, for driving VCR capstan and drum motors.

# **Features**

- 120° voltage linear drive technique
- The LB1854M soft switching scheme allows smaller external capacitors to be used (e.g., chip capacitors).
- Built-in thermal-shutdown function
- Built-in overcurrent protection circuit
- Built-in FG amplifiers (operational amplifier and Schmitt amplifier)
- Control start voltage set by an external voltage
- The output current feedback level can be changed by changing the control gain to one of two levels.

# **Package Dimensions**

unit: mm

### 3073A-MFP30S



# **Specifications**

# Absolute Maximum Ratings at Ta = $25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V <sub>CC</sub> 1 max		20	V
Maximum supply voltage	V <sub>CC</sub> 2 max		7.0	V
Applied output voltage	V <sub>OU, V, W</sub>		22	V
Maximum output current	I <sub>OUT</sub> max		1.5	A
Allowable power dissipation	Pd max		1.05	W
Operating temperature	Topr		-20 to +75	°C
Storage temperature	Tstg		-55 to +150	°C

## Allowable Operating Ranges at Ta = $25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V <sub>CC</sub> 1		5 to 18	V
Supply voltage	V <sub>CC</sub> 2		4.3 to 6.5	V

SANYO Electric Co., Ltd. Semiconductor Bussiness Headquarters TOKYO OFFICE Tokyo Bldg., 1-10, 1 Chome, Ueno, Taito-ku, TOKYO, 110 JAPAN

Parameter	Symbol	Conditions	min	typ	max	Unit
	I <sub>CC</sub> 1	$V_C = 0 V, R_L = \infty$		17	30	mA
Current drain	I <sub>CC</sub> 2	$V_{C} = 0 V$		6.5	9.5	mA
[Drive Block]	•					
	V <sub>O</sub> (sat) 1	I <sub>OUT</sub> = 0.5 A, sink + source		1.6	2.2	V
Output saturation voltage	V <sub>O</sub> (sat) 2	I <sub>OUT</sub> = 1.0 A, sink + source		2.0	3.0	V
Output TRS breakdown voltage	V <sub>O</sub> (sus)	I <sub>OUT</sub> = 20 mA*	20			V
Output resting potential	V <sub>OQ</sub>	$V_{C} = 0 V$	5.7	6.0	6.3	V
Hall amplifier input offset voltage	V <sub>H</sub> offset		-5		+5	mV
Hall amplifier input bias current	I <sub>H</sub> bias			1	5	μA
Hall amplifier common mode input voltage range	V <sub>H</sub> ch		1.3		2.2	V
Hall input/output voltage gain	GV <sub>HO</sub>		43	46	49	dB
[Control Block]				•	•	
	GV <sub>CO</sub> 1	High gain	37	40	43	dB
Control output drive gain	GV <sub>CO</sub> 2			34	37	dB
Control output CH difference	$\Delta GV_{CO}$		-2		+2	dB
Control start voltage	V <sub>CTH</sub>	When $V_{OUT}p-p = 2 V$		2.5		V
Gain control switching high level			4		5	V
Gain control switching middle level		Middle level when the input is open	2		3	V
Gain control switching low level			0		1	V
[FG Amplifier]			·	•	•	
FG amplifier input offset voltage	V <sub>FG</sub> offset		-8		+8	mV
Open-loop voltage gain	GV <sub>FG</sub>	f = 1 kHz		60		dB
Source output saturation voltage	V <sub>FG OU</sub>	I <sub>O</sub> = 2 mA	37			V
Sink output saturation voltage	V <sub>FG OD</sub>	I <sub>O</sub> = -2 mA			1.3	V
Common-mode signal rejection ratio	CHR	*		80		dB
FG amplifier common-mode input voltage range	V <sub>FG CH</sub>		0		3.5	V
Phase margin		*		20		Deg
0.1. 191. 1	∆Vsh1	FG <sub>OUT</sub> 2: High to low		22		mV
Schmitt hysteresis	∆Vsh2	FG <sub>OUT</sub> 2: Low to high		22		mV
Schmitt input voltage range	Vsh <sub>CH</sub>		0.7		3.5	V
[Thermal Shutdown]			·			
Operating temperature	TSD	*	150	180	210	°C
Hysteresis	ΔTSD	*		15		°C

# Electrical Characteristics at Ta = 25°C, $V_{\rm CC}1$ = 12 V, $V_{\rm CC}2$ = 5 V

Note: \* Items marked with an asterisk are design target values and are not measured.



# **Pin Assignment**



### **Block Diagram**





# **Sample Application Circuit**



# **Truth Table**

Source		Input			Forward and reverse control
	Sink		V	W	F/RC
1	W phase $\rightarrow$ V phase	Н	н	L	L
1	V phase $\rightarrow$ W phase				Н
2	W phase $\rightarrow$ U phase	н	1		L
2	U phase $\rightarrow$ W phase	н	L	L	Н
3	V phase $\rightarrow$ W phase		L	Н	L
3	W phase $\rightarrow$ V phase				Н
4	U phase $\rightarrow$ V phase		н		L
4	4 V phase $\rightarrow$ U phase		- 1	L	н
5	V phase $\rightarrow$ U phase	н	L	Н	L
5	U phase $\rightarrow$ V phase				Н
6	U phase $\rightarrow$ W phase		н	н	L
6	W phase $\rightarrow$ U phase	L	п	r1	Н

Input high: Phase 1 is 0.2 V or more higher than the corresponding phase 2 for each phase input. Low: Phase 1 is 0.2 V or more lower than the corresponding phase 2 for each phase input. Forward and reverse control high: 2.3 V to  $V_{CC}$ 1 Low: 0 V to 0.7 V

# **Pin Functions**

Unit (resistance:  $\Omega$ )

Pin No.	Symbol	Pin voltage	Equivalent circuit	Function
1, 2, 14, 15, 16, 17, 29, 30	FRAME (GND)			Ground for all circuits except the outputs
3	FC		VCC2	The gain frequency characteristics can be lowered by connecting a capacitor between this pin and ground to prevent oscillation.
4	V <sub>C REF</sub> V <sub>C</sub>	1.5 V min V <sub>CC</sub> 2 max 0 V min V <sub>CC</sub> 2 max	Vcc2	Speed control The LB1854M implements a voltage control scheme in which the output voltage is controlled by the pin 5 voltage. The pin 4 voltage determines the control start voltage.
6	V <sub>CC</sub> 1	5 to 18 V		Power supply that provides the drive outputs

Pin No.	Symbol	Din voltage	Equivalent circuit	Unit (resistance: C
7 8 9	U <sub>OUT</sub> V <sub>OUT</sub> W <sub>OUT</sub>	Pin voltage	Vcc1 Vcc1 Vcc1 Vcc1 Vcc1 Vcc1 Vcc1 Rf	Output pins
10	R <sub>f</sub>			Output transistor ground Feedback can be applied to the control amplifier by inserting resistor between this pin and GND and detecting the output current as a voltage. The overcurrent protection circuit (current limiter) operates by detecting the voltage on this pin.
11	V <sub>CC</sub> 2	4.3 to 6.5 V		Power supply provided to all blocks other than the output block This voltage must be stabilized so that no ripple or other noise is present.
12	CL	0 V min V <sub>CC</sub> 2 max	VCC2 (2) (2) (2) (2) (2) (2) (2) (3) (4) (5) (5) (5) (5) (5) (5) (5) (5	The current limiter operates when the R <sub>f</sub> pin reaches the same potential as pin 12. The pin 12 potential is set up externally.
13	GC	0 V min V <sub>CC</sub> 2 max	VCC2 ↓ 50k € ↓ 13 ↓ 0k ↓ 10k ↓ 10k ↓ 10k ↓ 10k ↓ 10k ↓	Control input to output gain switching pin High level (4 to 5 V): 34 dB Middle level (2 to 3 V) or open: 40 dB (low speed): 34 dB (high speed) Low level (0 to 1 V): 40 dB However, note that this applies when V <sub>CC</sub> 2 is 5 V.
18	FG <sub>OUT</sub> 2		V <sub>CC2</sub> () () () () () () () () () ()	FG Schmitt amplifier output
19	FG <sub>OUT</sub> 1			FG amplifier output

#### Continued from preceding page.

Pin No.	Symbol	Pin voltage	Equivalent circuit	Function
20 21	FG <sub>IN</sub> FG <sub>IN</sub> +	0 V min 3.5 V max (when V <sub>CC</sub> 2 is 5 V)		FG signal input
22	FRC	High: 2.3 V min Low: 0.7 V max	VREG 30k 30k 30k 30k 30k	Motor forward/reverse control pin Low level (0.7 V or lower): forward High level (2.3 V or higher): reverse
23 24 25 26 27 28	W <sub>IN</sub> 2 W <sub>IN</sub> 1 V <sub>IN</sub> 2 V <sub>IN</sub> 1 U <sub>IN</sub> 2 U <sub>IN</sub> 1	1.4 V min 2.0 V max	VREG VCC2 24 26 28 77 77 77	W phase Hall sensor input Logic high is the $W_{IN}1 > W_{IN}2$ state. V phase Hall sensor input Logic high is the $V_{IN}1 > V_{IN}2$ state. U phase Hall sensor input Logic high is the $U_{IN}1 > U_{IN}2$ state.

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