

## **LB1910N**

## **FDD Spindle Motor Driver**

## Overview

The LB1910N is a 3-phase disc drive motor driver that is optimal for use as a 3.5-inch FDD spindle motor driver.

## **Functions and Features**

- Three-phase full-wave linear driver
- Digital speed control circuit
- Start and stop circuits (active low)
- RPM switching H: 300 rpm L: 360 rpm
- Current limiter circuit
- · Built-in index comparator
- Thermal shutdown circuit

## **Package Dimensions**

unit: mm 3222-HSOP28



## Specifications

#### Absolute Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V <sub>CC</sub> max		7.0	V
Maximum output current	I <sub>O</sub> max1	l≤0.5s	1.0	A
Maximum steady-state output current	I <sub>O</sub> max2	<u> </u>	0.7	A
Allowable power dissipation	Pd max	Independent iC	0.5	w
Operating temperature	Topr	······································	-20 to +80	°C
Storage temperature	Tstg	······································	-40 to +150	•C

#### Allowable Operating Ranges at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Recommended supply voltage	Vcc		4.2 to 6.5	v

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# Electrical Characteristics at Ta = 25°C, $V_{CC}$ = 5 V

Parameter	Symbol	Conditions	min	typ	max	Unit
Ourseast datain	Icco	S/S = 5 V (standby)		····	10	μA
Current drain	lcc	S/S = 0 V (steady state)		12	18	mA
SL bias current	I <sub>SL</sub>	V <sub>SL</sub> = 0 V			10	μA
SL input low-level voltage	V <sub>SLL</sub>		0		1.0	٧
SL input high-level voltage	VSLH		3.5		V <sub>CC</sub>	v
S/S blas current	I <sub>S/S</sub>			180	270	μA
S/S tow-level voltage	V <sub>S/SL</sub>	· · · · · · · · · · · · · · · · · · ·	0		0.8	٧
S/S high-level voltage	V <sub>S/SH</sub>		3.5		V <sub>CC</sub>	v
Hall amplifier input bias current	I <sub>HB</sub>				10	μA
Common-mode Input voltage range	Vh		1.5		V <sub>CC</sub> - 1.0	V
Differential input voltage range	Vdif		50		200	mVp-p
Hall bias output voltage	VH	I <sub>H</sub> = 5 mA		0.8		V
Leakage current	I <sub>HE</sub>	S/S = 5 V			±10	μA
Output saturation voltage	Vsat	I <sub>O</sub> = 0.7 A, sink + source		1.3	1.8	v
Output leakage current	loL				1.0	mA
Current limiter	Vlim		0.27	0.3	0.33	v
Control amplifier voltage gain	G <sub>C</sub>			-7		dB
Voltage gain difference between phases	∆G <sub>C</sub>	· · · · · · · · · · · · · · · · · · ·			±1	dB
V/I conversion source current	1+	· · · · · · · · · · · · · · · · · · ·	9	14	19	μA
V/I conversion sink current	1		-9	14	-19	. μΑ
V/I conversion current ratio	+/ -		0.8	1.0	1.2	
DSC buffer input current	IDSC				1.0	μA
FG Schmitt hysteresis	ΔVsh	*		50		mV
Speed discriminator counts	N			1041.5		
Discriminator operating frequency	۶ <sub>D</sub>	*			1.1	MHz
Oscillator frequency range	Fosc	*			1.1	MHz
Index Input hysteresis	VIDH		18	23	28	mV
Index input	VIDO	I <sub>O</sub> = 2 mA	-5	0	+5	mV
Index output low-level voltage	VIDL	$I_0 = 2 \text{ mA}$			0.4	v
Index output leakage current	IDL				±10	μA
FG amplifier voltage gain	G <sub>FG</sub>	*		48		dB
FG amplifier input offset	V <sub>FG O</sub>				±10	mV
FG amplifier Internal reference voltage	V <sub>FG B</sub>		2.2	2.5	2.8	v
Thermal shutdown temperature	TSD	*	150	180		°C
Hysteresis	ΔTSD	*	· · ·	40		°C

Note: \* Items marked with an asterisk are design target values and are not measured.



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No. 5562-3/7

### **Block Diagram**



A06535

## **Pin Functions**

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Pin No.	Symbol	Pin voltage	Equivalent circuit diagram	Function
18 19 20 21 22 23	U <sub>IN</sub> + U <sub>IN</sub> - V <sub>IN</sub> + V <sub>IN</sub> - W <sub>IN</sub> + W <sub>IN</sub> -	1.5 V min V <sub>CC</sub> – 1.0 V max	$ \begin{array}{c} 18 \\ 20 \\ 22 \\ 18 \\ 22 \\ 18 \\ 22 \\ 18 \\ 18 \\ 22 \\ 18 \\ 18 \\ 18 \\ 18 \\ 18 \\ 18 \\ 18 \\ 18$	U phase Hall element input V phase Hall element input W phase Hall element input
24	нв	0.8 V typ (I <sub>H</sub> = 5 mA)	24 77 77 77 77 77 77 77 77 77 806537	Minus side connection for providing the Hall blas current This pin becomes open in the stopped state, thus cutting the Hall blas current.
25 26 27	FG <sub>IN</sub> ≁ FG <sub>IN</sub> − FG <sub>OUT</sub>	2.5 V	26 WCC 27 75 75 75 75 75 75 75 75 75 7	<ul> <li>FG amplifier plus input A 2.5-V reference voltage is generated internally.</li> <li>FG amplifier minus input</li> <li>FG amplifier output</li> </ul>
28 1	+ }-		28 2000 1 2000	Index input
2	D	L: 0.4 V max H: 4.5 V min	2 	Index output

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Pin No.	Symbol	Pin voltage	Equivalent circuit diagram	Function
4	SS	L: 0.8 Ý max H: 3.5 V min		Start/stop mode switching This is an active-low input.
5	SL	L: 1.0 V max H: 3.5 V min		Rotational speed switching
6	CLK	L: 1.0 V max H: V <sub>CC</sub> – 1.0 V min		Reference clock input A 1-MHz input frequency corresponds to speeds of 300 and 360 rpm.
7	GND			<ul> <li>Ground</li> <li>This pin, pin 14, and the frame must all be grounded together.</li> </ul>
8	Vcc			Power supply This voltage must be stabilized so that ripple and noise do not enter the IC,
9	Rf			Output current detection The output current is detected as a voltage by connecting the resistor RI between this pin and $V_{CC}$ . The current limiter operates by detecting the voltage on this pin.
10	DO			Speed discriminator
11	F <sub>C</sub>			Frequency characteristics compensation Current control system loop oscillation is prevented by connecting a capacitor between this pin and ground.

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Pin No.	Symbol	bol Pin voltage Equivalent circult diagram		Function
13 15 16	υ <sub>ουτ</sub> ν <sub>ουτ</sub> Ψουτ			U phase output V phase output W phase output
14	PGND			Output transistor ground connection

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