CMOS IC 8K-byte FROM and 256-byte RAM integrated 8-bit 1-chip Microcontroller



Overview

The LC87F2H08A is an 8-bit microcomputer that, centered around a CPU running at a minimum bus cycle time of 83.3ns, integrates on a single chip a number of hardware features such as 8K-byte flash ROM (On-board-programmable), 256-byte RAM, an On-chip-debugger, sophisticated 16-bit timers/counters (may be divided into 8-bit timers), a 16-bit timer/counter (may be divided into 8-bit timers/counters or 8-bit PWMs), two 8-bit timers with a prescaler, a base timer serving as a time-of-day clock, a high-speed clock counter, a synchronous SIO interface, an asynchronous/synchronous SIO interface, a UART interface (full duplex), two 12-bit PWM channels, a 12/8-bit 9-channel AD converter, a system clock frequency divider, an internal reset and a 20-source 10-vector interrupt feature.

Features

■Flash ROM

- Capable of on-board programming with a wide range (2.2 to 5.5V) of voltage source.
- Block-erasable in 128 byte units
- Writable in 2-byte units
- 8192 × 8 bits

■RAM

• 256×9 bits

■Minimum Bus Cycle

- 83.3ns (12MHz at V_{DD}=2.7V to 5.5V)
- 100ns (10MHz at VDD=2.2V to 5.5V)
- 250ns (4MHz at V_{DD}=1.8V to 5.5V)
- Note: The bus cycle time here refers to the ROM read speed.

* This product is licensed from Silicon Storage Technology, Inc. (USA).

■Minimum Instruction Cycle Time

- 250ns (12MHz at V_{DD}=2.7V to 5.5V)
- 300ns (10MHz at V_{DD}=2.2V to 5.5V)
- 750ns (4MHz at V_{DD}=1.8V to 5.5V)

■Ports

• Normal withstand voltage I/O ports

Ports whose I/O direction can be designated in 1-bit units 16 (Pin, P20, P21, P30, P31, P70 to P73)

- Ports whose I/O direction can be designated in 4-bit units
- Dedicated oscillator ports/input ports
- Reset pin
- Power pins
- ■Timers
 - Timer 0: 16-bit timer/counter with a capture register.

Mode 0: 8-bit timer with an 8-bit programmable prescaler (with an 8-bit capture register) \times 2 channels Mode 1: 8-bit timer with an 8-bit programmable prescaler (with an 8-bit capture register)

- + 8-bit counter (with an 8-bit capture register)
- Mode 2: 16-bit timer with an 8-bit programmable prescaler (with a 16-bit capture register)
- Mode 3: 16-bit counter (with a 16-bit capture register)
- Timer 1: 16-bit timer/counter that supports PWM/toggle outputs

Mode 0: 8-bit timer with an 8-bit prescaler (with toggle outputs) + 8-bit timer/

- counter with an 8-bit prescaler (with toggle outputs)
- Mode 1: 8-bit PWM with an 8-bit prescaler \times 2 channels
- Mode 2: 16-bit timer/counter with an 8-bit prescaler (with toggle outputs)

(toggle outputs also possible from the lower-order 8 bits)

Mode 3: 16-bit timer with an 8-bit prescaler (with toggle outputs)

(The lower-order 8 bits can be used as PWM)

- Timer 6: 8-bit timer with a 6-bit prescaler (with toggle outputs)
- Timer 7: 8-bit timer with a 6-bit prescaler (with toggle outputs)
- Base timer
 - 1) The clock is selectable from the subclock (32.768kHz crystal oscillation), system clock, and timer 0 prescaler output.
 - 2) Interrupts are programmable in 5 different time schemes
- ■High-Speed Clock Counter
 - Can count clocks with a maximum clock rate of 20MHz (at a main clock of 10MHz).
 - Can generate output real time.

■SIO

- SIO0: 8-bit Synchronous serial interface
 - 1) LSB first/MSB first mode selectable
 - 2) Built-in 8-bit baudrate generator (maximum transfer clock cycle=4/3tCYC)
- SIO1: 8-bit asynchronous/synchronous serial interface
 Mode 0: Synchronous 8-bit serial I/O (2- or 3-wire configuration, 2 to 512 tCYC transfer clocks)
 Mode 1: Asynchronous serial I/O (half-duplex, 8 data bits, 1 stop bit, 8 to 2048 tCYC baudrates)
 Mode 2: Bus mode 1 (start bit, 8 data bits, 2 to 512 tCYC transfer clocks)

Mode 3: Bus mode 2 (start detect, 8 data bits, stop detect)

- ■UART
 - Full Duplex
 - 7/8/9 bit data bits selectable
 - 1 Stop bit (2 bits in continuous data transmission)
 - Built-in baudrate generator

■AD Converter: 12 bits/8 bits × 9 channels

• 12/8 bits AD converter resolution selectable

16 (Pin, P20, P21, P30, P31, P70 to P73) 8 (P0n) 2 (<u>CF1/XT1, CF2/XT2</u>) 1 (<u>RES</u>) 3 (V_{SS}1, V_{SS}2, V_{DD}1)

■PWM: Multifrequency 12-bit PWM × 2 channels

Remote Control Receiver Circuit (sharing pins with P73, INT3, and T0IN)

- Noise rejection function (noise filter time constant selectable from 1 tCYC/32 tCYC/128 tCYC)
- Clock Output Function
 - Can generate clock outputs with a frequency of 1/1, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64 of the source clock selected as the system clock.
 - Can generate the source clock for the subclock

■Watchdog Timer

- External RC watchdog timer
- Interrupt and reset signals selectable

■Interrupts

- 20 sources, 10 vector addresses
 - 1) Provides three levels (low (L), high (H), and highest (X)) of multiplex interrupt control. Any interrupt requests of the level equal to or lower than the current interrupt are not accepted.
 - 2) When interrupt requests to two or more vector addresses occur at the same time, the interrupt of the highest level takes precedence over the other interrupts. For interrupts of the same level, the interrupt into the smallest vector address takes precedence.

No.	Vector Address	Level	Interrupt Source
1	00003H	X or L	INT0
2	0000BH	X or L	INT1
3	00013H	H or L	INT2/T0L/INT4
4	0001BH	H or L	INT3/INT5/base timer
5	00023H	H or L	тон
6	0002BH	H or L	T1L/T1H
7	00033H	H or L	SIO0/UART1 receive
8	0003BH	H or L	SIO1/UART1 transmit
9	00043H	H or L	ADC/T6/T7/PWM4, PWM5
10	0004BH	H or L	Port 0

• Priority levels X > H > L

• Of interrupts of the same level, the one with the smallest vector address takes precedence.

Subroutine Stack Levels: 128levels (The stack is allocated in RAM.)

■High-speed Multiplication/Division Instructions

- 16 bits \times 8 bits (5 tCYC execution time)
- 24 bits \times 16 bits (12 tCYC execution time)
- 16 bits ÷ 8 bits (8 tCYC execution time)
- 24 bits \div 16 bits (12 tCYC execution time)

■Oscillation Circuits

 Internal oscillation circuits 	
Low-speed RC oscillation circuit :	For system clock (100kHz)
Medium-speed RC oscillation circuit :	For system clock (1MHz)
Multifrequency RC oscillation circuit :	For system clock (8MHz)
 External oscillation circuits 	
Hi-speed CF oscillation circuit:	For system clock, with internal Rf
Low speed crystal oscillation circuit:	For low-speed system clock, with internal Rf
1) The CF and crystal oscillation circuit	s share the same pins. The active circuit is selected under program control.
2) Both the CF and crystal oscillator circ	cuits stop operation on a system reset. When the reset is released, only the
CF oscillation circuit resumes operati	on.

System Clock Divider Function

- Can run on low current.
- The minimum instruction cycle selectable from 300ns, 600ns, 1.2µs, 2.4µs, 4.8µs, 9.6µs, 19.2µs, 38.4µs, and 76.8µs (at a main clock rate of 10MHz).

■Internal reset function

- Power-on reset (POR) function
 - 1) POR reset is generated only at power-on time.
 - 2) The POR release level can be selected from 8 levels (1.67V, 1.97V, 2.07V, 2.37V, 2.57V, 2.87V, 3.86V, and 4.35V) through option configuration.
- Low-voltage detection reset (LVD) function
 - 1) LVD and POR functions are combined to generate resets when power is turned on and when power voltage falls below a certain level.
 - 2) The use/disuse of the LVD function and the low voltage threshold level (7 levels: 1.91V, 2.01V, 2.31V, 2.51V, 2.81V, 3.79V, 4.28V).

■Standby Function

- HALT mode: Halts instruction execution while allowing the peripheral circuits to continue operation.
 - 1) Oscillation is not halted automatically.
 - 2) There are three ways of resetting the HALT mode.
 - (1) Setting the reset pin to the low level
 - (2) System resetting by watchdog timer or low-voltage detection
 - (3) Occurrence of an interrupt
- HOLD mode: Suspends instruction execution and the operation of the peripheral circuits.
- 1) The CF, RC and crystal oscillators automatically stop operation.
- 2) There are four ways of resetting the HOLD mode.
 - (1) Setting the reset pin to the lower level.
 - (2) System resetting by watchdog timer or low-voltage detection
 - (3) Having an interrupt source established at either INT0, INT1, INT2, INT4 or INT5
 - * INT0 and INT1 HOLD mode reset is available only when level detection is set.
 - (4) Having an interrupt source established at port 0.
- X'tal HOLD mode: Suspends instruction execution and the operation of the peripheral circuits except the base timer.
 - 1) The CF and RC oscillator automatically stop operation.
 - 2) The state of crystal oscillation established when the X'tal HOLD mode is entered is retained.
 - 3) There are five ways of resetting the X'tal HOLD mode.
 - (1) Setting the reset pin to the low level.
 - (2) System resetting by watchdog timer or low-voltage detection.
 - (3) Having an interrupt source established at either INT0, INT1, INT2, INT4 or INT5
 - * INT0 and INT1 HOLD mode reset is available only when level detection is set.
 - (4) Having an interrupt source established at port 0.
 - (5) Having an interrupt source established in the base timer circuit.
 - Note: Available only when X'tal oscillation is selected.

Onchip Debugger

- Supports software debugging with the IC mounted on the target board.
- Two channels of on-chip debugger pins are available to be compatible with small pin count devices. DBGP0 (P0), DBGP1 (P1)
- Data Security Function (flash versions only)
 - Protects the program data stored in flash memory from unauthorized read or copy. Note: This data security function does not necessarily provide absolute data security.
- ■Package Form
 - QFP36 (7×7): Lead-free type

■Development Tools

• On-chip debugger: TCB87 type B + LC87F2H08A

■Programming Boards

Package	Programming boards		
QFP36(7×7)	W87F24Q		

■Flash ROM Programmer

Maker		Model	Supported version	Device
	Single Programmer	AF9708 AF9709/AF9709B/AF9709C (Including Ando Electric Co., Ltd. models)	Rev 02.72 or later	LC87F2H08A
Flash Support Group, Inc. (FSG)	Gang	AF9723/AF9723B(Main body) (Including Ando Electric Co., Ltd. models)	-	-
	Programmer	AF9833(Unit) (Including Ando Electric Co., Ltd. models)	-	-
Flash Support Group, Inc. (FSG) + Our company (Note 1)	In-circuit Programmer	AF9101/AF9103(Main body) (FSG models) SIB87(Inter Face Driver) (Our company model)	(Note 2)	LC87F2H08A
Our company	Single/Gang Programmer In-circuit/Gang Programmer	SKK/SKK Type B (SANYO FWS) SKK-DBG Type B (SANYO FWS)	Application Version 1.04 or later Chip Data Version 2.10 or later	LC87F2H08A

For information about AF-Series:

Flash Support Group, Inc.

TEL: +81-53-459-1050 E-mail: sales@j-fsg.co.jp

Note1: On-board-programmer from FSG (AF9101/AF9103) and serial interface driver from Our company (SIB87) together

can give a PC-less, standalone on-board-programming capabilities.

Note2: It needs a special programming devices and applications depending on the use of programming environment. Please ask FSG or Our company for the information.

Package Dimensions

unit : mm (typ) 3162C



Pin Assignment



QFP36 (7×7) "Lead-free Type"

QFP36	NAME	QFP36	NAME
1	P73/INT3/T0IN	19	P21/URX/INT4/T1IN
2	RES	20	P30/PWM4/INT5/T1IN
3	I.C.	21	P31/PWM5/INT5/T1IN
4	V _{SS} 1	22	N.C.
5	CF1/XT1	23	V _{SS} 2
6	CF2/XT2	24	P00/AN0
7	V _{DD} 1	25	P01/AN1
8	P10/SO0	26	P02/AN2
9	P11/SI0/SB0	27	P03/AN3
10	P12/SCK0	28	P04/AN4
11	P13/SO1/DBGP12	29	P05/AN5/CKO/DBGP00
12	P14/SI1/SB1/DBGP11	30	P06/AN6/T6O/DBGP01
13	P15/SCK1/DBGP10	31	P07/T7O/DBGP02
14	N.C.	32	N.C.
15	N.C.	33	N.C.
16	P16/T1PWML	34	P70/INT0/T0LCP/AN8
17	P17/T1PWMH/BUZ	35	P71/INT1/T0HCP/AN9
18	P20/UTX/INT4/T1IN	36	P72/INT2/T0IN

Note I.C. and N.C. pins must be held open (disconnected).

System Block Diagram



Pin Description

Pin Name	I/O			Des	scription			Option	
V _{SS} 1,V _{SS} 2	-	- power supply	power supply pins						
V _{DD} 1	-	+ power supply	power supply pin						
Port 0 P00 to P07	I/O	 8-bit I/O port I/O specifiable Pull-up resisted HOLD reset in Port 0 interrup Pin functions P05: System 0 P06: Timer 6 P07: Timer 7 P00(AN0) to F 	e in 4-bit units ors can be turned oput ot input clock output toggle output	nverter input				Yes	
Port 1 P10 to P17	1/0	Pin functions P10: SIO0 dat P11: SIO0 dat P11: SIO0 clo P13: SIO1 dat	ors can be turned ta output ta input/bus I/O ck I/O	P14 P15 P16 P17	I: SIO1 data inpu 5: SIO1 clock I/O 5: Timer 1 PWML 7: Timer 1 PWMH	. output	output	Yes	
Port 2 P20 to P21	1/0	2-bit I/O port I/O specifiable Pull-up resiste Pin functions P20: UART tra P21: UART re P20 to P21: IN til Interrupt ackn INT4	e in 1-bit units ors can be turned ansmit ceive	l on and off in 1 reset input/time		ner 0L capture i H level disable	nput/ L level disable	Yes	
Port 3 P30 to P31		Pin functions P30: PWM4 o P31: PWM5 o P30 to P31: IN ti	ors can be turned utput utput	reset input/time	-bit units. r 1 event input/tir Rising & Falling enable	ner 0L capture i H level disable	nput/ L level disable	Yes	

Continued on next page.

Pin Name	I/O		Description							
Port 7	I/O	 4-bit I/O port 	4-bit I/O port							
P70 to P73		 I/O specifiable 	in 1-bit units							
		Pull-up resistors can be turned on and off in 1-bit units.Pin functions								
		P70: INT0 inpu	t/HOLD reset in	put/timer 0L cap	ture input/watch	dog timer outpu	t			
		P71: INT1 inpu	t/HOLD reset in	put/timer 0H cap	oture input					
		P72: INT2 inpu	t/HOLD reset in	put/timer 0 even	t input/timer 0L o	apture input				
		P73: INT3 inpu	it (input with nois	se filter)/timer 0	event input/timer	0H capture inp	ut			
		P70(AN8),P71	P70(AN8),P71(AN9) : AD converter input							
		Interrupt ackno	wledge types	T	T			No		
			Rising	Falling	Rising &	H level	L level			
			Ttioning	i uning	Falling	1110101	210701			
		INT0	enable	enable	disable	enable	enable			
		INT1	enable	enable	disable	enable	enable			
		INT2	enable	enable	enable	disable	disable			
		INT3	enable	enable	enable	disable	disable			
		-								
RES	I/O	External reset In	put/internal rese	et output				No		
CF1/XT1	1	Ceramic reson	ator or 32.768kH	Hz crystal oscilla	tor input pin					
		 Pin function 								
		General-purpose input port								
CF2/XT2	I/O	Ceramic reson	ator or 32.768kH	Iz crystal oscilla	tor output pin					
		 Pin function 						No		
		General-purpose	e input port							

Port Output Types

The table below lists the types of port outputs and the presence/absence of a pull-up resistor.

Data can be read into any input port even if it is in the output mode.

Port Name	Option selected in units of	Option type	Output type	Pull-up resistor
P00 to P07	1 bit	1	CMOS	Programmable (Note 1)
		2	Nch-open drain	No
P10 to P17	1 bit	1	CMOS	Programmable
		2	Nch-open drain	Programmable
P20 to P21	1 bit	1	CMOS	Programmable
		2	Nch-open drain	Programmable
P30 to P31	1 bit	1	CMOS	Programmable
		2	Nch-open drain	Programmable
P70	-	No	Nch-open drain	Programmable
P71 to P73	-	No	CMOS	Programmable

Note 1: The control of the presence or absence of the programmable pull-up resistors for port 0 and the switching between low-and high-impedance pull-up connection is exercised in nibble (4-bit) units (P00 to 03 or P04 to 07).

Note: Be sure to electrically short-circuit between the V_{SS1} and V_{SS2} pins.

User Option Table

Option Name	Option to be Applied on	Flash-ROM Version	Option Selected in Units of	Option Selection
Port output type	P00 to P07	0	1 bit	CMOS
				Nch-open drain
	P10 to P17	0	1 bit	CMOS
				Nch-open drain
	P20 to P21	0	1 bit	CMOS
				Nch-open drain
	P30 to P31	0	1 bit	CMOS
				Nch-open drain
Program start	-	0	-	00000h
address				01E00h
Low-voltage	Detect function	0	-	Enable:Use
detection reset				Disable:Not Used
function	Detect level	0	-	7-level
Power-on reset function	Power-On reset level	0	-	8-level

Recommended Unused Pin Connections

Dart Name	Recommended Unused Pin Connections					
Port Name	Board	Software				
P00 to P07	Open	Output low				
P10 to P17	Open	Output low				
P20 to P21	Open	Output low				
P30 to P31	Open	Output low				
P70 to P73	Open	Output low				
CF1/XT1	Pulled low with a 100k Ω resistor or less	General-purpose input port				
CF2/XT2	Pulled low with a 100k Ω resistor or less	General-purpose input port				

On-chip Debugger pin connection requirements

For the treatment of the on-chip debugger pins, refer to the separately available documents entitled "RD87 on-chip debugger installation manual" and "LC872000 series on-chip debugger pin connection requirements"

Note: Be sure to electrically short-circuit between the $V_{\mbox{\scriptsize SS}}1$ and $V_{\mbox{\scriptsize SS}}2$ pins.

	Parameter	Symbol	Pin/Remarks	Conditions			Specif	ication	
	Parameter	Symbol	Pin/Remarks	Conditions	V _{DD} [V]	min	typ	max	uni
Maximum supply voltage Input voltage Input/output voltage		V _{DD} max	V _{DD} 1			-0.3		+6.5	
		VI	CF1, CF2			-0.3		V _{DD} +0.3	v
		V _{IO}	Ports 0, 1, 2, 3 Port 7			-0.3		V _{DD} +0.3	
	Peak output current	IOPH(1)	Ports 0, 1, 2, 3	CMOS output select Per 1 applicable pin		-10			
nt		IOPH(2)	P71 to P73	Per 1 applicable pin		-5			
High level output current	Mean output current	IOMH(1)	Ports 0, 1, 2, 3	CMOS output select Per 1 applicable pin		-7.5			
outpr	(Note 1-1)	IOMH(2)	P71 to P73	Per 1 applicable pin		-3			1
velo	Total output	ΣIOAH(1)	P71 to P73	Total of all applicable pins		-10			
gh le	current	ΣIOAH(2)	P10 to P14	Total of all applicable pins		-20			1
Ηġ		ΣIOAH(3)	P15 to P17 Ports 0, 2, 3	Total of all applicable pins		-20]
		ΣIOAH(4)	Ports 0, 1, 2, 3	Total of all applicable pins		-25			
	Peak output current	IOPL(1)	P02 to P07 Ports 1, 2, 3	Per 1 applicable pin				20	m
		IOPL(2)	P00, P01	Per 1 applicable pin				30	
		IOPL(3)	Port 7	Per 1 applicable pin				10	
Low level output current	Mean output current (Note 1-1)	IOML(1)	P02 to P07 Ports 1, 2, 3	Per 1 applicable pin				15	
utput		IOML(2)	P00, P01	Per 1 applicable pin				20	1
/el o		IOML(3)	Port 7	Per 1 applicable pin				7.5	
v lev	Total output	$\Sigma IOAL(1)$	Port 7	Total of all applicable pins				15	
Lo	current	ΣIOAL(2)	Port 0	Total of all applicable pins				40	
		ΣIOAL(3)	P10 to P14	Total of all applicable pins				35	
		ΣIOAL(4)	Ports 1, 2, 3	Total of all applicable pins				40	
		ΣIOAL(5)	Ports 0, 1, 2, 3	Total of all applicable pins				70	
	wer sipation	Pd max(1)	QFP36(7×7)	Ta=-40 to +85°C Package only				120	
2.00.putori		Pd max(2)		Ta=-40 to +85°C Package with thermal resistance board (Note 1-2)				275	m
	erating ambient mperature	Topr				-40		+85	
Sto	brage ambient	Tstg				-55		+125	• •(

Absolute Maximum Ratings at $Ta = 25^{\circ}C$, $V_{SS}1 = V_{SS}2 = 0V$

Note 1-1: The mean output current is a mean value measured over 100ms.

Note 1-2: SEMI standards thermal resistance board (size: 76.1×114.3×1.6tmm, glass epoxy) is used.

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

Parameter	Symbol	Pin/Remarks	Conditions			Specif	ication	•
Falametei	Symbol	FINAL	Conditions	V _{DD} [V]	min	typ	max	unit
Operating	V _{DD} (1)	V _{DD} 1	$0.245 \mu s \leq tCYC \leq 200 \mu s$		2.7		5.5	
supply voltage	V _{DD} (2)		$0.294 \mu s \leq tCYC \leq 200 \mu s$		2.2		5.5	
(Note 2-1)	V _{DD} (3)		$0.735\mu s \le tCYC \le 200\mu s$		1.8		5.5	
Memory sustaining supply voltage	VHD	V _{DD} 1	RAM and register contents sustained in HOLD mode.		1.6			
High level input voltage	∨ _{IH} (1)	Ports 1, 2, 3, P71 to P73 P70 port input/ interrupt side		1.8 to 5.5	0.3V _{DD} +0.7		V _{DD}	
	V _{IH} (2)	Ports 0		1.8 to 5.5	0.3V _{DD} +0.7		V _{DD}	
	V _{IH} (3)	Port 70 watchdog timer side		1.8 to 5.5	0.9V _{DD}		V _{DD}	V
	V _{IH} (4)	CF1, RES		1.8 to 5.5	0.75V _{DD}		V _{DD}	
Low level	V _{IL} (1)	Ports 1, 2, 3,		4.0 to 5.5	V _{SS}		0.1V _{DD} +0.4	
input voltage		P71 to P73 P70 port input/ interrupt side		1.8 to 4.0	V _{SS}		0.2V _{DD}	
	V _{IL} (2)	Ports 0		4.0 to 5.5	V _{SS}		0.15V _{DD} +0.4	
				1.8 to 4.0	VSS		0.2V _{DD}	
	V _{IL} (3)	Port 70 watchdog timer side		1.8 to 5.5	V _{SS}		0.8V _{DD} -1.0	
	V _{IL} (4)	CF1, RES		1.8 to 5.5	V _{SS}		0.25V _{DD}	
Instruction	tCYC			2.7 to 5.5	0.245		200	
cycle time	(Note 2-2)			2.2 to 5.5	0.294		200	με
(Note 2-1)				1.8 to 5.5	0.735		200	1
External	FEXCF	CF1	CF2 pin open	2.7 to 5.5	0.1		12	
system clock frequency			 System clock frequency division ratio=1/1 External system clock duty=50±5% 	1.8 to 5.5	0.1		4	
			CF2 pin open	3.0 to 5.5	0.2		24.4	MH
			 System clock frequency division ratio=1/2 External system clock duty=50±5% 	2.0 to 5.5	0.2		8	
Oscillation frequency	FmCF(1)	CF1, CF2	12MHz ceramic oscillation See Fig. 1.	2.7 to 5.5		12		
range (Note 2-3)	FmCF(2)	CF1, CF2	10MHz ceramic oscillation See Fig. 1.	2.2 to 5.5		10		
	FmCF(3)	CF1, CF2	4MHz ceramic oscillation. CF oscillation normal amplifier size selected. See Fig. 1. (CFLAMP=0)	1.8 to 5.5		4		
			4MHz ceramic oscillation. CF oscillation low amplifier size selected. (CFLAMP=1) See Fig. 1.	2.2 to 5.5		4		MF
	FmMRC		Frequency variable RC oscillation. 1/2 frequency division ration. (RCCTD=0) (Note 2-4)	2.7 to 5.5	7.44	8.0	8.56	
	FmRC		Internal medium-speed RC oscillation	1.8 to 5.5	0.5	1.0	2.0	
	FmSRC		Internal low-speed RC oscillation	1.8 to 5.5	50	100	200	
	FsX'tal	XT1, XT2	32.768kHz crystal oscillation See Fig. 2.	1.8 to 5.5		32.768		kH
		•	· · · · · · · · · · · · · · · · · · ·		•			

Allowable Operating Conditions at $Ta = -40^{\circ}C$ to $+85^{\circ}C$, $V_{SS}1 = V_{SS}2 = 0V$

Note 2-1: V_{DD} must be held greater than or equal to 2.2V in the flash ROM onboard programming mode.

Note 2-2: Relationship between tCYC and oscillation frequency is 3/FmCF at a division ratio of 1/1 and 6/FmCF at a division ratio of 1/2.

- Note 2-3: See Tables 1 and 2 for the oscillation constants.
- Note 2-4: When switching the system clock, allow an oscillation stabilization time of 100µs or longer after the multifrequency RC oscillator circuit transmits from the "oscillation stopped" to "oscillation enabled" state.

Doromotor	Symbol	Pin/Remarks	Conditions			Specifica	ation	
Parameter	Symbol	Pin/Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
High level input current	I _{IH} (1)	Ports 0, 1, 2, 3 Port 7 RES	Output disabled Pull-up resistor off VIN=VDD (Including output Tr's off leakage current)	1.8 to 5.5			1	
	I _{IH} (2)	CF1	V _{IN} =V _{DD}	1.8 to 5.5			15	
Low level input current	I _{IL} (1)	Ports 0, 1, 2, 3 Port 7 RES	Output disabled Pull-up resistor off VIN=VSS (Including output Tr's off leakage current)	1.8 to 5.5	-1			μA
	I _{IL} (2)	CF1	V _{IN} =V _{SS}	1.8 to 5.5	-15			
High level output	V _{OH} (1)	Ports 0, 1, 2	I _{OH} =-1mA	4.5 to 5.5	V _{DD} -1			
voltage	V _{OH} (2)	P71 to P73	I _{OH} =-0.35mA	2.7 to 5.5	V _{DD} -0.4			
	V _{OH} (3)		I _{OH} =-0.15mA	1.8 to 5.5	V _{DD} -0.4			
	V _{OH} (4)	Port 3	I _{OH} =-6mA	4.5 to 5.5	V _{DD} -1			
	V _{OH} (5)		I _{OH} =-1.4mA	2.7 to 5.5	V _{DD} -0.4			
	V _{OH} (6)		I _{OH} =-0.8mA	1.8 to 5.5	V _{DD} -0.4			
Low level output	V _{OL} (1)	Ports 0, 1, 2, 3	I _{OL} =10mA	4.5 to 5.5			1.5	
voltage	V _{OL} (2)		I _{OL} =1.4mA	2.7 to 5.5			0.4	V
	V _{OL} (3)		I _{OL} =0.8mA	1.8 to 5.5			0.4	
	V _{OL} (4)	Port 7	I _{OL} =1.4mA	2.7 to 5.5			0.4	
	V _{OL} (5)		I _{OL} =0.8mA	1.8 to 5.5			0.4	
	V _{OL} (6)	P00, P01	I _{OL} =25mA	4.5 to 5.5			1.5	
	V _{OL} (7)		I _{OL} =4mA	2.7 to 5.5			0.4	
	V _{OL} (8)		I _{OL} =2mA	1.8 to 5.5			0.4	
Pull-up resistance	Rpu(1)	Ports 0, 1, 2, 3	V _{OH} =0.9V _{DD}	4.5 to 5.5	15	35	80	
	Rpu(2)	Port 7	When Port 0 selected low-impedance pull-up.	1.8 to 4.5	18	50	230	kΩ
	Rpu(3)	Port 0	V _{OH} =0.9V _{DD} When Port 0 selected high-impedance pull-up.	1.8 to 5.5	100	210	400	K32
Hysteresis voltage	VHYS(1)	Ports 1, 2, 3, 7		2.7 to 5.5		0.1V _{DD}		v
	VHYS(2)	RES		1.8 to 2.7		0.07V _{DD}		v
Pin capacitance	СР	All pins	For pins other than that under test: VIN=VSS f=1MHz Ta=25°C	1.8 to 5.5		10		pF

Electrical Characteristics at $Ta = -40^{\circ}C$ to $+85^{\circ}C$, $V_{SS}1 = V_{SS}2 = 0V$

Serial I/O Characteristics at $Ta = -40^{\circ}C$ to $+85^{\circ}C$, $V_{SS}1 = V_{SS}2 = 0V$ 1. SIO0 Serial I/O Characteristics (Note 4-1-1)

		Deremeter	Cumbol	Pin/	Conditions			Speci	fication	
	1	Parameter	Symbol	Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
		Frequency	tSCK(1)	SCK0(P12)	See Fig. 5.		2			
	Input clock	Low level pulse width	tSCKL(1)			1.8 to 5.5	1			101/0
Serial clock	lnp	High level pulse width	tSCKH(1)				1			tCYC
erial	×	Frequency	tSCK(2)	SCK0(P12)	CMOS output selected		4/3			
Š	put clock	Low level pulse width	tSCKL(2)		• See Fig. 5.	1.8 to 5.5		1/2		tSCK
	Output 6	High level pulse width	tSCKH(2)					1/2		ISCK
Serial input	Da	ata setup time	tsDI(1)	SB0(P11), SI0(P11)	 Must be specified with respect to rising edge of SIOCLK. 	1.8 to 5.5	0.05			
Seri	Da	ata hold time	thDI(1)		• See Fig. 5.		0.05			
	Input clock	Output delay time	tdD0(1)	SO0(P10), SB0(P11)	Continuous data transmission/reception mode (Note 4-1-2)				(1/3)tCYC +0.08	μs
Serial output	lnpu		tdD0(2)		Synchronous 8-bit mode (Note 4-1-2)	1.8 to 5.5			1tCYC +0.08	
Serial	Output clock		tdD0(3)		(Note 4-1-2)	1.0 10 5.5			(1/3)tCYC +0.08	

Note 4-1-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-1-2: Must be specified with respect to falling edge of SIOCLK. Must be specified as the time to the beginning of output state change in open drain output mode. See Fig. 5.

2. SIO1 Serial I/O Characteristics (Note 4-2-1)

		Parameter	Sumbol	Pin/	Conditions			Spec	ification	
		Parameter	Symbol	Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
	×	Frequency	tSCK(3)	SCK1(P15)	See Fig. 5.		2			
	Input clock	Low level pulse width	tSCKL(3)]		1.8 to 5.5	1			
clock	lu	High level	tSCKH(3)				1			tCYC
Serial clock	ъ К	Frequency	tSCK(4)	SCK1(P15)	CMOS output selected See Fig. 5.		2			
	Output clock	Low level pulse width	tSCKL(4)			1.8 to 5.5		1/2		
	Õ	High level pulse width	tSCKH(4)					1/2		tSCK
Serial input	Da	ata setup time	tsDI(2)	SB1(P14), SI1(P14)	 Must be specified with respect to rising edge of SIOCLK. See Fig. 5. 		0.05			
Serial	Da	ata hold time	thDI(2)			1.8 to 5.5	0.05			
Serial output	0	utput delay time	tdD0(4)	SO1(P13), SB1(P14)	 Must be specified with respect to falling edge of SIOCLK. Must be specified as the time to the beginning of output state change in open drain output mode. See Fig. 5. 	1.8 to 5.5			(1/3)tCYC +0.08	μs

Note 4-2-1: These specifications are theoretical values. Add margin depending on its use.

Pulse Input Conditions at $Ta = -40^{\circ}C$ to $+85^{\circ}C$, $V_{SS}1 = V_{SS}2 = 0V$

Decemeter	Cumhal	Din/Domort/o	Conditions			Speci	fication	
Parameter	Symbol	Pin/Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
High/low level	tPIH(1)	INT0(P70),	 Interrupt source flag can be set. 					
pulse width	tPIL(1)	INT1(P71),	 Event inputs for timer 0 or 1 are 					
		INT2(P72),	enabled.	1.8 to 5.5	1			
		INT4(P20 to P21),						
		INT5(P30 to P31)						
	tPIH(2)	INT3(P73) when noise	 Interrupt source flag can be set. 					
	tPIL(2)	filter time constant is	 Event inputs for timer 0 are 	1.8 to 5.5	2			tCYC
		1/1	enabled.					
	tPIH(3)	INT3(P73) when noise	 Interrupt source flag can be set. 					
	tPIL(3)	filter time constant is	 Event inputs for timer 0 are 	1.8 to 5.5	64			
		1/32	nabled.					
	tPIH(4)	INT3(P73) when noise	 Interrupt source flag can be set. 					
	tPIL(4)	filter time constant is	 Event inputs for timer 0 are 	1.8 to 5.5	256			
		1/128	enabled.					
	tPIL(5)	RES	 Resetting is enabled. 	1.8 to 5.5	200			μs

AD Converter Characteristics at $V_{SS}1 = V_{SS}2 = 0V$

<12bits AD Converter Mode/Ta = -40° C to $+85^{\circ}$ C >

D						Specifi	cation	
Parameter	Symbol	Pin/Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
Resolution	N	AN0(P00) to		2.4 to 5.5		12		bit
Absolute	ET	AN6(P06),	(Note 6-1)	3.0 to 5.5			±16	
accuracy		AN8(P70), AN9(P71)	(Note 6-1) ● Ta=-10 to +50°C	2.4 to 3.6			±20	LSB
Conversion time	TCAD		See Conversion time calculation	4.0 to 5.5	32		115	
			formulas. (Note 6-2)	3.0 to 5.5	64		115	
			 See Conversion time calculation formulas. (Note 6-2) Ta=-10 to +50°C 	2.4 to 3.6	410		425	μs
Analog input voltage range	VAIN			2.4 to 5.5	V _{SS}		V _{DD}	V
Analog port	IAINH]	VAIN=V _{DD}	2.4 to 5.5			1	
input current	IAINL]	VAIN=V _{SS}	2.4 to 5.5	-1			μΑ

<8bits AD Converter Mode/Ta = -40°C to +85°C >

Deservator	Question	Die (Darsaalus	Oraclitican			Specifi	cation	
Parameter	Symbol	Pin/Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
Resolution	N	AN0(P00) to		2.4 to 5.5		8		bit
Absolute accuracy	ET	AN6(P06) AN8(P70)	(Note 6-1)	2.4 to 5.5			±1.5	LSB
Conversion time	TCAD	AN9(P71)	See Conversion time calculation	4.0 to 5.5	20		90	
			formulas. (Note 6-2)	3.0 to 5.5	40		90	
			 See Conversion time calculation formulas. (Note 6-2) Ta=-10 to +50°C 	2.4 to 3.6	250		265	μs
Analog input voltage range	VAIN			2.4 to 5.5	V _{SS}		V _{DD}	V
Analog port	IAINH		VAIN=V _{DD}	2.4 to 5.5			1	
input current	IAINL		VAIN=V _{SS}	2.4 to 5.5	-1			μA

Conversion time calculation formulas:

12bits AD Converter Mode: TCAD(Conversion time) = $((52/(AD \text{ division ratio}))+2)\times(1/3)\times tCYC$ 8bits AD Converter Mode: TCAD(Conversion time) = $((32/(AD \text{ division ratio}))+2)\times(1/3)\times tCYC$

External oscillation	Operating supply voltage range	System division ratio	Cycle time	AD division ratio	AD conversion time (TCAD)		
(FmCF)	(V _{DD})	(SYSDIV)	(tCYC)	(ADDIV)	12bit AD	8bit AD	
	4.0V to 5.5V	1/1	250ns	1/8	34.8µs	21.5µs	
CF-12MHz	3.0V to 5.5V	1/1	250ns	1/16	69.5µs	42.8µs	
	4.0V to 5.5V	1/1	300ns	1/8	41.8µs	25.8µs	
CF-10MHz	3.0V to 5.5V	1/1	300ns	1/16	83.4µs	51.4µs	
	3.0V to 5.5V	1/1	750ns	1/8	104.5µs	64.5µs	
CF-4MHz	2.4V to 3.6V	1/1	750ns	1/32	416.5µs	256.5µs	

Note 6-1: The quantization error (±1/2LSB) must be excluded from the absolute accuracy. The absolute accuracy must be measured in the microcontroller's state in which no I/O operations occur at the pins adjacent to the analog input channel.

The conversion time is 2 times the normal-time conversion time when:

- The first AD conversion is performed in the 12-bit AD conversion mode after a system reset.
- The first AD conversion is performed after the AD conversion mode is switched from 8-bit to 12-bit conversion mode.

Note 6-2: The conversion time refers to the period from the time an instruction for starting a conversion process till the time the conversion results register(s) are loaded with a complete digital conversion value corresponding to the analog input value.

					\sim	~~		
						Specif	ication	
Parameter	Symbol	Pin/Remarks	Conditions	Option selected voltage	min	typ	max	unit
POR release	PORRL		Select from option.	1.67V	1.55	1.67	1.79	
voltage			(Note 7-1)	1.97V	1.85	1.97	2.09	
				2.07V	1.95	2.07	2.19	
				2.37V	2.25	2.37	2.49	
				2.57V	2.45	2.57	2.69	
				2.87V	2.75	2.87	2.99	V
				3.86V	3.73	3.86	3.99	
				4.35V	4.21	4.35	4.49	
Detection voltage unknown state	POUKS		• See Fig. 7. (Note 7-2)			0.7	0.95	
Power supply rise time	PORIS		Power supply rise time from 0V to 1.6V.				100	ms

Note7-1: The POR release level can be selected out of 8 levels only when the LVD reset function is disabled. Note7-2: POR is in an unknown state before transistors start operation.

Low Voltage Detection Reset (LVD) Characteristics at $Ta = -40^{\circ}C$ to $+85^{\circ}C$, $V_{SS}1=V_{SS}2=0V$

						Specific	cation	
Parameter	Symbol	Pin/Remarks	Conditions	Option selected voltage	min	typ	max	unit
LVD reset Voltage	LVDET		Select from option.	1.91V	1.81	1.91	2.01	
(Note 8-2)			(Note 8-1)	2.01V	1.91	2.01	2.11	
			(Note 8-3) • See Fig. 8.	2.31V	2.21	2.31	2.41	
			• See Fig. 6.	2.51V	2.41	2.51	2.61	V
				2.81V	2.71	2.81	2.91	
				3.79V	3.69	3.79	3.89	
				4.28V	4.18	4.28	4.38	
LVD hysteresys	LVHYS		1.91V		55			
width				2.01V		55		
				2.31V		55		
				2.51V		55		mV
				2.81V		60		
				3.79V		65		
				4.28V		65		
Detection voltage unknown state	LVUKS		• See Fig. 8. (Note 8-4)			0.7	0.95	V
Low voltage detection minimum Width (Reply sensitivity)	TLVDW		• LVDET-0.5V • See Fig. 9.		0.2			ms

Note8-1: The LVD reset level can be selected out of 7 levels only when the LVD reset function is enabled.

Note8-2: LVD reset voltage specification values do not include hysteresis voltage.

Note8-3: LVD reset voltage may exceed its specification values when port output state changes and/or when a large current flows through port.

Note8-4: LVD is in an unknown state before transistors start operation.

Consumption Current Characteristics at $Ta = -40^{\circ}C$ to $+85^{\circ}C$, $V_{SS}1 = V_{SS}2 = 0V$

Parameter	Symbol	Pin/	Conditions	·		Speci	fication	
Falainelei	Зупрог	Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
Normal mode consumption current	IDDOP(1)	V _{DD} 1	 FmCF=12MHz ceramic oscillation mode System clock set to 12MHz side Internal low speed and medium speed RC 	2.7 to 5.5		7.4	13.0	
(Note 9-1) (Note 9-2)			oscillation stopped. • Frequency variable RC oscillation stopped. • 1/1 frequency division ratio	2.7 to 3.6		4.4	8.1	
	IDDOP(2)		 CF1=24MHz external clock System clock set to CF1 side Internal low speed and medium speed RC 	3.0 to 5.5		9.7	16.2	
			oscillation stopped. Frequency variable RC oscillation stopped. 1/2 frequency division ratio 	3.0 to 3.6		5.3	8.7	
	IDDOP(3)	FmCF=10MHz ceramic oscillation mode System clock set to 10MHz side Internal low speed and medium speed RC	2.2 to 5.5		6.6	11.9	-	
			 oscillation stopped. Frequency variable RC oscillation stopped. 1/1 frequency division ratio 	2.2 to 3.6		4.0	7.4	
	IDDOP(4)		 FmCF=4MHz ceramic oscillation mode System clock set to 4MHz side Internal low speed and medium speed RC 	1.8 to 5.5		2.9	6.5	
			oscillation stopped. Frequency variable RC oscillation stopped. 1/1 frequency division ratio 	1.8 to 3.6		2.2	4.2	mA
	IDDOP(5)		 CF oscillation low amplifier size selected. (CFLAMP=1) FmCF=4MHz ceramic oscillation mode System clock set to 4MHz side 	2.2 to 5.5		1.1	2.5	
			 Internal low speed and medium speed RC oscillation stopped. Frequency variable RC oscillation stopped. 1/4 frequency division ratio 	2.2 to 3.6		0.6	1.3	
	IDDOP(6)		 FsX'tal=32.768kHz crystal oscillation mode Internal low speed RC oscillation stopped. System clock set to internal medium speed 	1.8 to 5.5		0.6	1.7	
			RC oscillation.Frequency variable RC oscillation stopped.1/2 frequency division ratio	1.8 to 3.6		0.3	0.9	
	IDDOP(7)		 FsX'tal=32.768kHz crystal oscillation mode Internal low speed and medium speed RC oscillation stopped. 	2.7 to 5.5		5.0	9.1	
			 System clock set to 8MHz with frequency variable RC oscillation 1/1 frequency division ratio 	2.7 to 3.6		3.6	5.8	
	IDDOP(8)		 External FsX'tal and FmCF oscillation stopped. System clock set to internal low speed RC oscillation. 	1.8 to 5.5		75	370	
			 Internal medium speed RC oscillation sopped. Frequency variable RC oscillation stopped. 1/1 frequency division ratio 	1.8 to 3.6		46	192	
	IDDOP(9)		 External FsX'tal and FmCF oscillation stopped. System clock set to internal low speed RC oscillation. 	5.0		75	176	μA
			Internal medium speed RC oscillation sopped.Frequency variable RC oscillation stopped.	3.3		46	115	
			 1/1 frequency division ratio Ta=-10 to +50°C 	2.5		35	85	

Note9-1: Values of the consumption current do not include current that flows into the output transistors and internal pull-up resistors.

Note9-2: The consumption current values do not include operational current of LVD function if not specified.

Continued on next page.

Parameter	Symbol	Pin/	Conditions	·		Speci	fication	
Falametei	Symbol	Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
Normal mode consumption current	IDDOP(10)	V _{DD} 1	 FsX'tal=32.768kHz crystal oscillation mode System clock set to 32.768kHz side Internal low speed and medium speed RC 	1.8 to 5.5		38	139	
(Note 9-1) (Note 9-2)			oscillation stopped.Frequency variable RC oscillation stopped.1/2 frequency division ratio	1.8 to 3.6		15	66	
	IDDOP(11)		FsX'tal=32.768kHz crystal oscillation mode System clock set to 32.768kHz side	5.0		38	101	μA
			Internal low speed and medium speed RC oscillation stopped.	3.3		15	46	
			 Frequency variable RC oscillation stopped. 1/2 frequency division ratio Ta=-10 to +50°C 	2.5		9.0	28	
HALT mode consumption current	IDDHALT(1)	V _{DD} 1	HALT mode FmCF=12MHz ceramic oscillation mode System clock set to 12MHz side	2.7 to 5.5		3.1	5.6	
(Note 9-1) (Note 9-2)			 Internal low speed and medium speed RC oscillation stopped. Frequency variable RC oscillation stopped. 1/1 frequency division ratio 	2.7 to 3.6		1.6	2.9	
	IDDHALT(2)		HALT mode GF1=24MHz external clock System clock set to CF1 side Internal low speed and medium speed RC	3.0 to 5.5		4.9	8.6	
			 Internation speed and medium speed RC oscillation stopped. Frequency variable RC oscillation stopped. 1/2 frequency division ratio 	3.0 to 3.6		2.3	3.8	
	IDDHALT(3)		HALT mode FmCF=10MHz ceramic oscillation mode System clock set to 10MHz side Internal low speed and medium speed RC	2.2 to 5.5		2.7	5.3	
			 Internation speed and medium speed RC oscillation stopped. Frequency variable RC oscillation stopped. 1/1 frequency division ratio 	2.2 to 3.6		1.4	2.6	
	IDDHALT(4)		 HALT mode FmCF=4MHz ceramic oscillation mode System clock set to 4MHz side Internal low speed and medium speed RC 	1.8 to 5.5		1.4	3.5	mA
			 Frequency variable RC oscillation stopped. 1/1 frequency division ratio 	1.8 to 3.6		0.7	1.3	
	IDDHALT(5)		HALT mode CF oscillation low amplifier size selected. (CFLAMP=1) FmCF=4MHz ceramic oscillation mode System clock opt to 4MHz side	2.2 to 5.5		0.7	1.8	
			 System clock set to 4MHz side Internal low speed and medium speed RC oscillation stopped. Frequency variable RC oscillation stopped. 1/4 frequency division ratio 	2.2 to 3.6		0.3	0.7	
	IDDHALT(6)		HALT mode FsX'tal=32.768kHz crystal oscillation mode Internal low speed RC oscillation stopped.	1.8 to 5.5		0.4	1.1	
			 System clock set to internal medium speed RC oscillation Frequency variable RC oscillation stopped. 1/2 frequency division ratio 	1.8 to 3.6		0.2	0.5	

Note9-1: Values of the consumption current do not include current that flows into the output transistors and internal pull-up resistors.

Note9-2: The consumption current values do not include operational current of LVD function if not specified.

Continued on next page.

Continued from	preceding page.	1	1					
Parameter	Symbol	Pin/	Conditions			Speci	fication	
	Cymbol	remarks		V _{DD} [V]	min	typ	max	unit
HALT mode consumption current (Note 9-1)	IDDHALT(7)	V _{DD} 1	 HALT mode FsX'tal=32.768kHz crystal oscillation mode Internal low speed and medium speed RC oscillation stopped. 	2.7 to 5.5		1.8	3.5	
(Note 9-2)			System clock set to 8MHz with frequency variable RC oscillation 1/1 frequency division ratio	2.7 to 3.6		1.1	2.0	
	IDDHALT(8)		HALT mode External FsX'tal and FmCF oscillation stopped. System clock set to internal low speed RC Set to internal low speed RC	1.8 to 5.5		23	260	
			 oscillation. Internal medium speed RC oscillation sopped. Frequency variable RC oscillation stopped. 1/1 frequency division ratio 	1.8 to 3.6		13	119	μA
	IDDHALT(9)		HALT mode External FsX'tal and FmCF oscillation stopped. Contrar shall ext to internal law area of PC	5.0		23	65	
			 System clock set to internal low speed RC oscillation. Internal medium speed RC oscillation sopped. 	3.3		13	35	
			 Frequency variable RC oscillation stopped. 1/1 frequency division ratio Ta=-10 to +50°C 	2.5		9.2	25	
	IDDHALT(10)		 HALT mode FsX'tal=32.768kHz crystal oscillation mode System clock set to 32.768kHz side Internal low speed and medium speed RC 	1.8 to 5.5		25	112	
		HALT(11)	 Internation speed and medium speed RC oscillation stopped. Frequency variable RC oscillation stopped. 1/2 frequency division ratio 	1.8 to 3.6		8.5	56	μΑ
	IDDHALT(11)		HALT mode FsX'tal=32.768kHz crystal oscillation mode System clock set to 32.768kHz side	5.0		25	69	
			 Internal low speed and medium speed RC oscillation stopped. Frequency variable RC oscillation stopped. 	3.3		8.5	29	
	• 1/2 • Ta:		 1/2 frequency division ratio Ta=-10 to +50°C 	2.5		4.2	15	
HOLD mode	IDDHOLD(1)	V _{DD} 1	HOLD mode	1.8 to 5.5		0.04	30	
consumption current			• CF1=V _{DD} or open (External clock mode)	1.8 to 3.6		0.02	21	
(Note 9-1)	IDDHOLD(2)	OLD(2)	 HOLD mode CF1=V_{DD} or open (External clock mode) 	5.0		0.04	2.3	
(Note 9-2)			• Ta=-10 to +50°C	3.3		0.02	1.5	
				2.5		0.017	1.2	
	IDDHOLD(3)		 HOLD mode CF1=V_{DD} or open (External clock mode) 	1.8 to 5.5		3.2	35	
			LVD option selected	1.8 to 3.6		2.7	24	
	IDDHOLD(4)		HOLD mode	5.0		3.2	6.5	μΑ
			• CF1=V _{DD} or open (External clock mode) • Ta=-10 to +50°C	3.3		2.7	4.5	
			LVD option selected	2.5		2.5	4.2	
Timer HOLD	IDDHOLD(5)	V _{DD} 1	Timer HOLD mode	1.8 to 5.5		22	106	
mode			• FsX'tal=32.768 kHz crystal oscillation mode	1.8 to 3.6		7.5	45	
consumption current	IDDHOLD(6)		Timer HOLD mode	5.0		22	62	
(Note 9-1)			• FsX'tal=32.768kHz crystal oscillation mode	3.3		7.5	23	
(Note 9-2)			• Ta=-10 to +50°C	2.5		2.9	12	

Note9-1: Values of the consumption current do not include current that flows into the output transistors and internal pull-up resistors.

Note9-2: The consumption current values do not include operational current of LVD function if not specified.

Demonster	Ourschal	Dia (Desservice	O and this are	_		Specification				
Parameter	Symbol Pin/Remarks		Conditions	V _{DD} [V]	min	typ	max	unit		
Onboard programming current	IDDFW(1)	V _{DD} 1	Only current of the Flash block.	2.2 to 5.5		5	10	mA		
Programming	tFW(1)		Erasing time	0.0 40 5 5		20	30	ms		
time tFW(2)		Programming time		2.2 to 5.5		40	60	μs		

UART (Full Duplex) Operating Conditions at $Ta = -40^{\circ}C$ to $+85^{\circ}C$, $V_{SS}1 = V_{SS}2 = 0V$

	Ourseland	Dia (Deservator			Specification				
Parameter	Symbol	Pin/Remarks	Conditions	V _{DD} [V]	min	typ	max	unit	
Transfer rate	UBR	UTX(P20)		1.8 to 5.5	16/3		8192/3	tCYC	
		URX(P21)		1.6 10 5.5	10/3		0192/3	lore	
D. (. 1	7/0/01:4	(ICD C)							

Data length:7/8/9 bits (LSB first)Stop bits:1 bit (2-bit in continuous data transmission)Parity bits:None

Example of Continuous 8-bit Data Transmission Mode Processing (First Transmit Data=55H)



Example of Continuous 8-bit Data Reception Mode Processing (First Receive Data=55H)



Characteristics of a Sample Main System Clock Oscillation Circuit

Given below are the characteristics of a sample main system clock oscillation circuit that are measured using a Our designated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Table 1 Characteristics of a Sample Main System Clock Oscillator Circuit with a Ceramic Oscillator • CF oscillation normal amplifier size selected (CFLAMP=0)

■MURATA

Nominal	Ŧ			Circuit (Constant		Operating	Oscillation Stabilization Time		
Frequency	Frequency	Oscillator Name	C1	C2	Rf	Rf Rd	Voltage Range [V]	typ	max	Remarks
			[pF]	[pF]	[Ω]	[Ω]	[v]	[ms]	[ms]	
12MHz	SMD	CSTCE12M0G52-R0	(10)	(10)	Open	1.0k	2.7 to 5.5	0.1	0.5	
	0145		(10)	(10)	Open	680	2.2 to 3.6	0.1	0.5	
10MHz	SMD	CSTCE10M0G52-R0	(10)		Open	1.0k	2.3 to 5.5	0.1	0.5	
	LEAD	CSTLS10M0G53-B0	(15)	(15)	Open	1.0k	2.5 to 5.5	0.1	0.5	
01411	SMD	CSTCE8M00G52-R0	(10)	(10)	Open	1.5k	2.2 to 5.5	0.1	0.5	
8MHz	LEAD	CSTLS8M00G53-B0	(15)	(15)	Open	1.5k	2.2 to 5.5	0.1	0.5	Internal C1,C2
01411	SMD	CSTCR6M00G53-R0	(15)	(15)	Open	2.2k	2.2 to 5.5	0.1	0.5	01,02
6MHz	LEAD	CSTLS6M00G53-B0	(15)	(15)	Open	2.2k	2.2 to 5.5	0.1	0.5	
	0145	D CSTCR4M00G53-R0	(45)	(45)	Open	1.5k	1.8 to 2.7	0.2	0.6	
4MHz	SMD		(15)	(15)	Open	3.3k	1.9 to 5.5	0.2	0.6	
	LEAD	CSTLS4M00G53-B0	(15)	(15)	Open	3.3k	1.9 to 5.5	0.2	0.6	

• CF oscillation low amplifier size selected (CFLAMP=1)

Nominal Frequency	-		Circuit Constant				Operating	Oscillation Stabilization Time			
	Oscillator Name	C1 [pF]	C2 [pF]	Rf [Ω]	Rd [Ω]	Voltage Range [V]	Typ [ms]	Max [ms]	Remarks		
		CSTCR4M00G53-R0 SMD		(15)	Open	1.0k	2.1 to 2.7	0.2	0.6		
	SMD		(15)		Open	2.2k	2.5 to 5.5	0.2	0.6		
45411-		CSTCR4M00G53095-R0	(15)	(15)	Open	1.0k	1.9 to 2.7	0.2	0.7	Internal	
4MHz LE				(1 =)	Open	1.0k	2.2 to 2.7	0.2	0.6	C1,C2	
	LEAD	CSTLS4M00G53-B0	(15)	(15)	Open	2.2k	2.5 to 5.5	0.2	0.6		
		CSTLS4M00G53095-B0	(15)	(15)	Open	1.0k	2.0 to 2.7	0.2	0.7		

The oscillation stabilization time refers to the time interval that is required for the oscillation to get stabilized after V_{DD} goes above the operating voltage lower limit (see Figure 3).

Characteristics of a Sample Subsystem Clock Oscillator Circuit

Given below are the characteristics of a sample subsystem clock oscillation circuit that are measured using a Our designated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Table 2 Characteristics of a Sample Subsystem Clock Oscillator Circuit with a Crystal Oscillator ■EPSON TOYOCOM

Nominal Frequency Type	_ Oscillator	Oscillator	Circuit Constant				Operating	Oscillation Stabilization Time		
	l ype Name	C1 [pF]	C2 [pF]	Rf [Ω]	Rd [Ω]	Voltage Range [V]	typ [s]	max [s]	Remarks	
32.768kHz	SMD	MC-306	9	9	Open	330k	1.8 to 5.5	1.4	4.0	Applicable CL value = 7.0pF

The oscillation stabilization time refers to the time interval that is required for the oscillation to get stabilized after the instruction for starting the subclock oscillation circuit is executed and to the time interval that is required for the oscillation to get stabilized after the HOLD mode is reset (see Figure 3):

Note: The components that are involved in oscillation should be placed as close to the IC and to one another as possible because they are vulnerable to the influences of the circuit pattern.



Figure 1 CF and XT Oscillator Circuit



Figure 2 AC Timing Measurement Point



Reset Time and Oscillation Stabilization Time



HOLD Reset Signal and Oscillation Stabilization Time

Note: External oscillation circuit is selected.

Figure 3 Oscillation Stabilization Times



Figure 4 Reset Circuit



Figure 5 Serial I/O Output Waveforms



Figure 6 Pulse Input Timing Signal Waveform



(RESET pin: Pull-up resistor R_{RES} only)

- The POR function generates a reset only when power is turned on starting at the VSS level.
- No stable reset will be generated if power is turned on again when the power level does not go down to the VSS level as shown in (a). If such a case is anticipated, use the LVD function together with the POR function or implement an external reset circuit.
- A reset is generated only when the power level goes down to the VSS level as shown in (b) and power is turned on again after this condition continues for 100µs or longer.



Figure 8 Waveform observed when both POR and LVD functions are used (RESET pin: Pull-up resistor R_{RES} only)

- Resets are generated both when power is turned on and when the power level lowers.
- A hysteresis width (LVHYS) is provided to prevent the repetitions of reset release and entry cycles near the detection level.



Figure 9 Low voltage detection minimum width (Example of momentary power loss/Voltage variation waveform)

ON Semiconductor and the ON logo are registered trademarks of Semiconductor Components Industries, LLC (SCILLC). SCILLC owns the rights to a number of patents, trademarks, copyrights, trade secrets, and other intellectual property. A listing of SCILLC's product/patent coverage may be accessed at www.onsemi.com/site/pdf/Patent-Marking.pdf. SCILLC reserves the right to make changes without further notice to any products herein. SCILLC makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does SCILLC assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation special, consequential or incidental damages. "Typical" parameters which may be provided in SCILLC data sheets and/or specifications can and do vary in different applications and actual performance may vary over time. All operating parameters, including "Typical" must be validated for each customer application by customer's technical experts. SCILLC does not convey any license under its patent rights nor the rights of others. SCILLC products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the SCILLC product could create a situation where personal injury or death may occur. Should Buyer purchase or use SCILLC products for any such unintended or unauthorized application, Buyer shall indemnify and hold SCILLC and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that SCILLC was negligent regarding the design or manufacture of the part. SCILLC is an Equal