

LM6181 100 mA, 100 MHz Current Feedback Amplifier

Check for Samples: [LM6181](#)

FEATURES

- (Typical unless otherwise noted)
- Slew rate: 2000 V/ μ s
- Settling time (0.1%): 50 ns
- Characterized for supply ranges: ± 5 V and ± 15 V
- Low differential gain and phase error: 0.05%, 0.04°
- High output drive: ± 10 V into 100 Ω
- Guaranteed bandwidth and slew rate

- Improved performance over EL2020, OP160, AD844, LT1223 and HA5004

APPLICATIONS

- Coax cable driver
- Video amplifier
- Flash ADC buffer
- High frequency filter
- Scanner and Imaging systems

DESCRIPTION

The LM6181 current-feedback amplifier offers an unparalleled combination of bandwidth, slew-rate, and output current. The amplifier can directly drive up to 100 pF capacitive loads without oscillating and a 10V signal into a 50 Ω or 75 Ω back-terminated coax cable system over the full industrial temperature range. This represents a radical enhancement in output drive capability for an 8-pin DIP high-speed amplifier making it ideal for video applications.

Built on National's advanced high-speed VIP™ II (Vertically Integrated PNP) process, the LM6181 employs current-feedback providing bandwidth that does not vary dramatically with gain; 100 MHz at $A_V = -1$, 60 MHz at $A_V = -10$. With a slew rate of 2000V/ μ s, 2nd harmonic distortion of -50 dBc at 10 MHz and settling time of 50 ns (0.1%) the LM6181 dynamic performance makes it ideal for data acquisition, high speed ATE, and precision pulse amplifier applications.

Typical Application

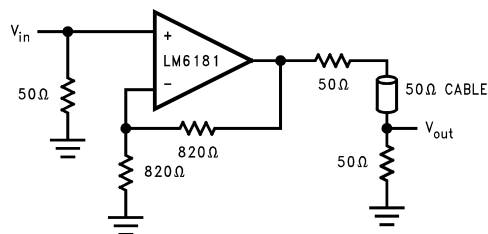


Figure 1. Cable Driver



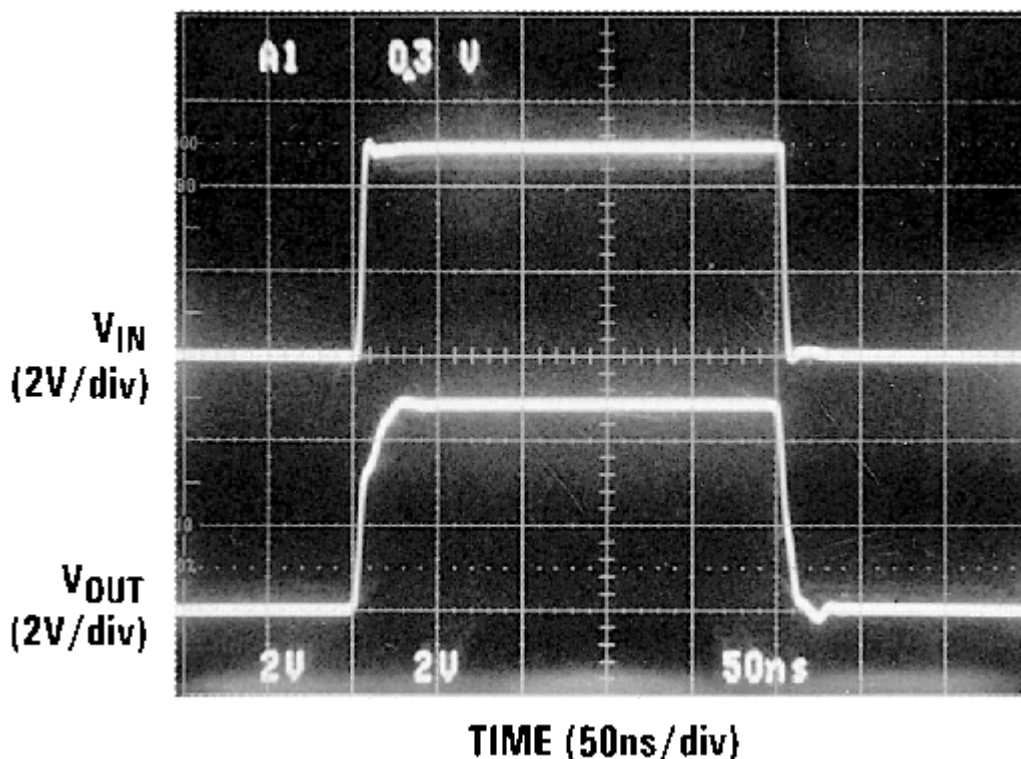
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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

Absolute Maximum Ratings ⁽¹⁾

Supply Voltage	±18V
Differential Input Voltage	±6V
Input Voltage	±Supply Voltage
Inverting Input Current	15 mA
Soldering Information	
Dual-In-Line Package (N)	
Soldering (10 sec)	260°C
Small Outline Package (M)	
Vapor Phase (60 seconds)	215°C
Infrared (15 seconds)	220°C
Output Short Circuit	⁽²⁾
Storage Temperature Range	-65°C ≤ T _J ≤ +150°C
Maximum Junction Temperature	150°C
ESD Rating ⁽³⁾	±3000V

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating ratings indicate conditions the device is intended to be functional, but device parameter specifications may not be guaranteed under these conditions. For guaranteed specifications and test conditions, see the Electrical Characteristics.
- (2) Continuous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 150°C. Output currents in excess of ±130 mA over a long term basis may adversely affect reliability.
- (3) Human body model 100 pF and 1.5 kΩ.

Operating Ratings

Supply Voltage Range	7V to 32V
Junction Temperature Range ⁽¹⁾	
LM6181AM	$-55^{\circ}\text{C} \leq T_J \leq +125^{\circ}\text{C}$
LM6181AI, LM6181I	$-40^{\circ}\text{C} \leq T_J \leq +85^{\circ}\text{C}$
Thermal Resistance (θ_{JA} , θ_{JC})	
8-pin DIP (N)	102°C/W, 42°C/W
8-pin SO (M-8)	153°C/W, 42°C/W
16-pin SO (M)	70°C/W, 38°C/W

- (1) The typical junction-to-ambient thermal resistance of the molded plastic DIP(N) package soldered directly into a PC board is 102°C/W. The junction-to-ambient thermal resistance of the S.O. surface mount (M) package mounted flush to the PC board is 70°C/W when pins 1, 4, 8, 9 and 16 are soldered to a total 2 in² 1 oz. copper trace. The 16-pin S.O. (M) package must have pin 4 and at least one of pins 1, 8, 9, or 16 connected to V⁻ for proper operation. The typical junction-to-ambient thermal resistance of the S.O. (M-8) package soldered directly into a PC board is 153°C/W.

±15V DC Electrical Characteristics

The following specifications apply for Supply Voltage = ±15V, $R_F = 820\Omega$, and $R_L = 1\text{ k}\Omega$ unless otherwise noted. **Boldface** limits apply at the temperature extremes; all other limits $T_J = 25^\circ\text{C}$.

Symbol	Parameter	Conditions	LM6181AM		LM6181AI		LM6181I		Units
			Typical	Limit	Typical	Limit	Typical	Limit	
			(1)	(2)	(1)	(2)	(1)	(2)	
V_{OS}	Input Offset Voltage		2.0	3.0	2.0	3.0	3.5	5.0	mV
				4.0		3.5		5.5	max
$TC_{V_{OS}}$	Input Offset Voltage Drift		5.0		5.0		5.0		$\mu\text{V}/^\circ\text{C}$
I_B	Inverting Input Bias Current		2.0	5.0	2.0	5.0	5.0	10	μA max
				12.0		12.0		17.0	
	Non-Inverting Input Bias Current		0.5	1.5	0.5	1.5	2.0	3.0	
				3.0		3.0		5.0	
TC_{I_B}	Inverting Input Bias Current Drift		30		30		30		nA/ $^\circ\text{C}$
	Non-Inverting Input Bias		10		10		10		
	Current Drift								
I_B	Inverting Input Bias Current	$V_S = \pm 4.5\text{V}, \pm 16\text{V}$	0.3	0.5	0.3	0.5	0.3	0.75	$\mu\text{A}/\text{V}$ max
PSR	Power Supply Rejection			3.0		3.0		4.5	
	Non-Inverting Input Bias Current	$V_S = \pm 4.5\text{V}, \pm 16\text{V}$	0.05	0.5	0.05	0.5	0.05	0.5	
	Power Supply Rejection			1.5		1.5		3.0	
I_B	Inverting Input Bias Current	$-10\text{V} \leq V_{CM} \leq +10\text{V}$	0.3	0.5	0.3	0.5	0.3	0.75	
CMR	Common Mode Rejection			0.75		0.75		1.0	
	Non-Inverting Input Bias Current	$-10\text{V} \leq V_{CM} \leq +10\text{V}$	0.1	0.5	0.1	0.5	0.1	0.5	
	Common Mode Rejection			0.5		0.5		0.5	
CMRR	Common Mode Rejection Ratio	$-10\text{V} \leq V_{CM} \leq +10\text{V}$	60	50	60	50	60	50	dB
				50		50		50	min
PSRR	Power Supply Rejection Ratio	$V_S = \pm 4.5\text{V}, \pm 16\text{V}$	80	70	80	70	80	70	dB
				70		70		65	min
R_O	Output Resistance	$A_V = -1, f = 300\text{ kHz}$	0.2		0.2		0.2		Ω
R_{IN}	Non-Inverting Input Resistance		10		10		10		M Ω
									min
V_O	Output Voltage Swing	$R_L = 1\text{ k}\Omega$	12	11	12	11	12	11	V min
				11		11		11	
		$R_L = 100\Omega$	11	10	11	10	11	10	
				7.5		8.0		8.0	
I_{SC}	Output Short Circuit Current		130	100	130	100	130	100	mA
				75		85		85	min
Z_T	Transimpedance	$R_L = 1\text{ k}\Omega$	1.8	1.0	1.8	1.0	1.8	0.8	
				0.5		0.5		0.4	M Ω
		$R_L = 100\Omega$	1.4	0.8	1.4	0.8	1.4	0.7	min
				0.4		0.4		0.35	
I_S	Supply Current	No Load, $V_O = 0\text{V}$	7.5	10	7.5	10	7.5	10	mA
				10		10		10	max
V_{CM}	Input Common Mode		$V^+ - 1.7\text{V}$		$V^+ - 1.7\text{V}$		$V^+ - 1.7\text{V}$		V
	Voltage Range		$V^- + 1.7\text{V}$		$V^- + 1.7\text{V}$		$V^- + 1.7\text{V}$		

(1) Typical values represent the most likely parametric norm.

(2) All limits guaranteed at room temperature (standard type face) or at operating temperature extremes (**bold face type**).

±15V AC Electrical Characteristics

The following specifications apply for Supply Voltage = ±15V, $R_F = 820\Omega$, $R_L = 1\text{ k}\Omega$ unless otherwise noted. **Boldface** limits apply at the temperature extremes; all other limits $T_J = 25^\circ\text{C}$.

Symbol	Parameter	Conditions	LM6181AM		LM6181AI		LM6181I		Units
			Typical	Limit	Typical	Limit	Typical	Limit	
			(1)	(2)	(1)	(2)	(1)	(2)	
BW	Closed Loop Bandwidth	$A_V = +2$	100		100		100		MHz min
	-3 dB	$A_V = +10$	80		80		80		
		$A_V = -1$	100	80	100	80	100	80	
		$A_V = -10$	60		60		60		
PBW	Power Bandwidth	$A_V = -1$, $V_O = 5\text{ V}_{PP}$	60		60		60		
SR	Slew Rate	Overdriven	2000		2000		2000		V/ μs min
		$A_V = -1$, $V_O = \pm 10\text{V}$,	1400	1000	1400	1000	1400	1000	
		$R_L = 150\Omega$ ⁽³⁾							
t_s	Settling Time (0.1%)	$A_V = -1$, $V_O = \pm 5\text{V}$	50		50		50		ns
		$R_L = 150\Omega$							
t_r , t_f	Rise and Fall Time	$V_O = 1\text{ V}_{PP}$	5		5		5		
t_p	Propagation Delay Time	$V_O = 1\text{ V}_{PP}$	6		6		6		
$i_{n(+)}$	Non-Inverting Input Noise	$f = 1\text{ kHz}$	3		3		3		pA/ $\sqrt{\text{Hz}}$ (1)
	Current Density								
$i_{n(-)}$	Inverting Input Noise	$f = 1\text{ kHz}$	16		16		16		pA/ $\sqrt{\text{Hz}}$ (2)
	Current Density								
e_n	Input Noise Voltage Density	$f = 1\text{ kHz}$	4		4		4		nV/ $\sqrt{\text{Hz}}$ (3)
	Second Harmonic Distortion	2 V_{PP} , 10 MHz	-50		-50		-50		dBc
	Third Harmonic Distortion	2 V_{PP} , 10 MHz	-55		-55		-50		
	Differential Gain	$R_L = 150\Omega$							
		$A_V = +2$	0.05		0.05		0.05		%
		NTSC							
	Differential Phase	$R_L = 150\Omega$							
		$A_V = +2$	0.04		0.04		0.04		Deg
		NTSC							

(1) Typical values represent the most likely parametric norm.

(2) All limits guaranteed at room temperature (standard type face) or at operating temperature extremes (**bold face type**).

(3) Measured from +25% to +75% of output waveform.

±5V DC Electrical Characteristics

The following specifications apply for Supply Voltage = $\pm 5\text{V}$, $R_F = 820\Omega$, and $R_L = 1\text{ k}\Omega$ unless otherwise noted. **Boldface** limits apply at the temperature extremes; all other limits $T_J = 25^\circ\text{C}$.

Symbol	Parameter	Conditions	LM6181AM		LM6181AI		LM6181I		Units
			Typical	Limit	Typical	Limit	Typical	Limit	
			(1)	(2)	(1)	(2)	(1)	(2)	
V_{OS}	Input Offset Voltage		1.0	2.0	1.0	2.0	1.0	3.0	mV
				3.0		2.5		3.5	max
$TC_{V_{OS}}$	Input Offset Voltage Drift		2.5		2.5		2.5		$\mu\text{V}/^\circ\text{C}$
I_B	Inverting Input		5.0	10	5.0	10	5.0	17.5	μA max
	Bias Current			22		22		27.0	
	Non-Inverting Input		0.25	1.5	0.25	1.5	0.25	3.0	
	Bias Current			1.5		1.5		5.0	
TC_{I_B}	Inverting Input Bias		50		50		50		nA/ $^\circ\text{C}$
	Current Drift								
	Non-Inverting Input		3.0		3.0		3.0		
	Bias Current Drift								
I_B	Inverting Input Bias Current	$V_S = \pm 4.0\text{V}, \pm 6.0\text{V}$	0.3	0.5	0.3	0.5	0.3	1.0	$\mu\text{A}/\text{V}$ max
PSR	Power Supply Rejection			0.5		0.5		1.0	
	Non-Inverting Input	$V_S = \pm 4.0\text{V}, \pm 6.0\text{V}$	0.05	0.5	0.05	0.5	0.05	0.5	
	Bias Current								
	Power Supply Rejection			0.5		0.5		0.5	
I_B	Inverting Input Bias Current	$-2.5\text{V} \leq V_{CM} \leq +2.5\text{V}$	0.3	0.5	0.3	0.5	0.3	1.0	
CMR	Common Mode Rejection			1.0		1.0		1.5	dB min
	Non-Inverting Input	$-2.5\text{V} \leq V_{CM} \leq +2.5\text{V}$	0.12	0.5	0.12	0.5	0.12	0.5	
	Bias Current								
	Common Mode Rejection			1.0		0.5		0.5	
CMRR	Common Mode	$-2.5\text{V} \leq V_{CM} \leq +2.5\text{V}$	57	50	57	50	57	50	
	Rejection Ratio			47		47		47	
PSRR	Power Supply	$V_S = \pm 4.0\text{V}, \pm 6.0\text{V}$	80	70	80	70	80	64	dB min
	Rejection Ratio			70		70		64	
R_O	Output Resistance	$A_V = -1, f = 300\text{ kHz}$	0.25		0.25		0.25		Ω
R_{IN}	Non-Inverting		8		8		8		M Ω
	Input Resistance								min
V_O	Output Voltage Swing	$R_L = 1\text{ k}\Omega$	2.6	2.25	2.6	2.25	2.6	2.25	V min
				2.2		2.25		2.25	
		$R_L = 100\Omega$	2.2	2.0	2.2	2.0	2.2	2.0	
				2.0		2.0		2.0	
I_{SC}	Output Short		100	75	100	75	100	75	mA
	Circuit Current			70		70		70	min
Z_T	Transimpedance	$R_L = 1\text{ k}\Omega$	1.4	0.75	1.4	0.75	1.0	0.6	
				0.35		0.4		0.3	M Ω
		$R_L = 100\Omega$	1.0	0.5	1.0	0.5	1.0	0.4	min
				0.25		0.25		0.2	
I_S	Supply Current	No Load, $V_O = 0\text{V}$	6.5	8.5	6.5	8.5	6.5	8.5	mA
				8.5		8.5		8.5	max

(1) Typical values represent the most likely parametric norm.

(2) All limits guaranteed at room temperature (standard type face) or at operating temperature extremes (**bold face type**).

±5V DC Electrical Characteristics (continued)

The following specifications apply for Supply Voltage = ±5V, $R_F = 820\Omega$, and $R_L = 1\text{ k}\Omega$ unless otherwise noted. **Boldface** limits apply at the temperature extremes; all other limits $T_J = 25^\circ\text{C}$.

Symbol	Parameter	Conditions	LM6181AM		LM6181AI		LM6181I		Units
			Typical	Limit	Typical	Limit	Typical	Limit	
			(1)	(2)	(1)	(2)	(1)	(2)	
V_{CM}	Input Common Mode		$V^+ - 1.7V$		$V^+ - 1.7V$		$V^+ - 1.7V$		V
	Voltage Range		$V^- + 1.7V$		$V^- + 1.7V$		$V^- + 1.7V$		

±5V AC Electrical Characteristics

The following specifications apply for Supply Voltage = $\pm 5V$, $R_F = 820\Omega$, and $R_L = 1\text{ k}\Omega$ unless otherwise noted. **Boldface** limits apply at the temperature extremes; all other limits $T_J = 25^\circ\text{C}$.

Symbol	Parameter	Conditions	LM6181AM		LM6181AI		LM6181I		Units
			Typical	Limit	Typical	Limit	Typical	Limit	
			(1)	(2)	(1)	(2)	(1)	(2)	
BW	Closed Loop Bandwidth -3 dB	$A_V = +2$	50		50		50		MHz min
		$A_V = +10$	40		40		40		
		$A_V = -1$	55	35	55	35	55	35	
		$A_V = -10$	35		35		35		
PBW	Power Bandwidth	$A_V = -1$, $V_O = 4\text{ V}_{PP}$	40		40		40		
SR	Slew Rate	$A_V = -1$, $V_O = \pm 2V$, $R_L = 150\Omega$ ⁽³⁾	500	375	500	375	500	375	V/ μs min
t_s	Settling Time (0.1%)	$A_V = -1$, $V_O = \pm 2V$ $R_L = 150\Omega$	50		50		50		ns
t_r , t_f	Rise and Fall Time	$V_O = 1\text{ V}_{PP}$	8.5		8.5		8.5		
t_p	Propagation Delay Time	$V_O = 1\text{ V}_{PP}$	8		8		8		
$i_{n(+)}$	Non-Inverting Input Noise	$f = 1\text{ kHz}$	3		3		3		
	Current Density								pA/ $\sqrt{\text{Hz}}$ (4)
$i_{n(-)}$	Inverting Input Noise	$f = 1\text{ kHz}$	16		16		16		pA/ $\sqrt{\text{Hz}}$ (5)
	Current Density								
e_n	Input Noise Voltage Density	$f = 1\text{ kHz}$	4		4		4		nV/ $\sqrt{\text{Hz}}$ (6)
	Second Harmonic Distortion	2 V_{PP} , 10 MHz	-45		-45		-45		
	Third Harmonic Distortion	2 V_{PP} , 10 MHz	-55		-55		-55		dBc
	Differential Gain	$R_L = 150\Omega$							
		$A_V = +2$	0.063		0.063		0.063		%
		NTSC							
	Differential Phase	$R_L = 150\Omega$							Deg
		$A_V = +2$	0.16		0.16		0.16		
		NTSC							

(1) Typical values represent the most likely parametric norm.

(2) All limits guaranteed at room temperature (standard type face) or at operating temperature extremes (**bold face type**).

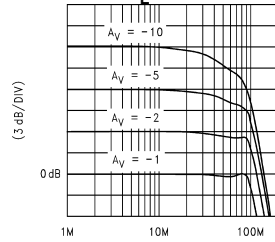
(3) Measured from +25% to +75% of output waveform.

Typical Performance Characteristics

$T_A = 25^\circ\text{C}$ unless otherwise noted

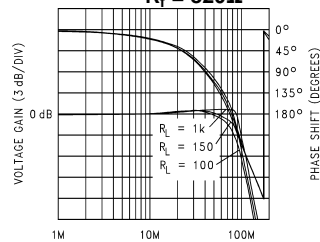
CLOSED-LOOP FREQUENCY RESPONSE

$V_S = \pm 15\text{V}$; $R_f = 820\Omega$;
 $R_L = 1\text{ k}\Omega$



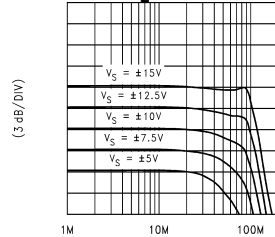
UNITY GAIN FREQUENCY RESPONSE

$V_S = \pm 15\text{V}$; $A_V = +1$;
 $R_f = 820\Omega$



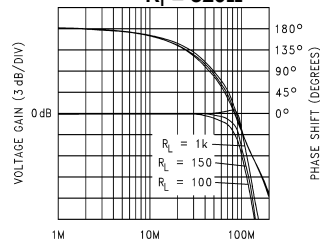
FREQUENCY RESPONSE vs SUPPLY VOLTAGE

$A_V = -1$; $R_f = 820\Omega$;
 $R_L = 1\text{ k}\Omega$



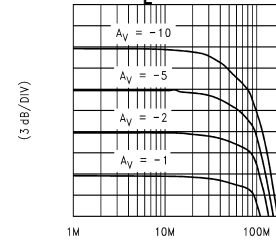
INVERTING GAIN FREQUENCY RESPONSE

$V_S = \pm 15\text{V}$; $A_V = -1$;
 $R_f = 820\Omega$



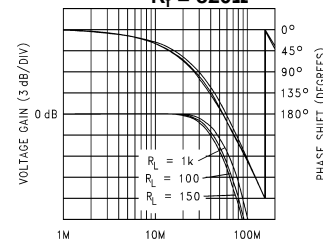
CLOSED-LOOP FREQUENCY RESPONSE

$V_S = \pm 15\text{V}$; $R_f = 820\Omega$;
 $R_L = 150\Omega$



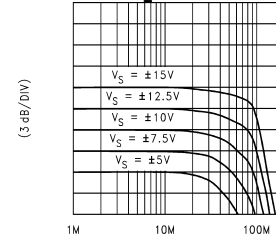
UNIT GAIN FREQUENCY RESPONSE

$V_S = \pm 5\text{V}$; $A_V = +1$;
 $R_f = 820\Omega$



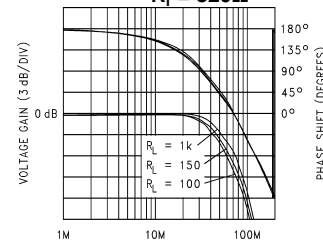
FREQUENCY RESPONSE vs SUPPLY VOLTAGE

$A_V = -1$; $R_f = 820\Omega$;
 $R_L = 150\Omega$



INVERTING GAIN FREQUENCY RESPONSE

$V_S = \pm 5\text{V}$; $A_V = -1$;
 $R_f = 820\Omega$

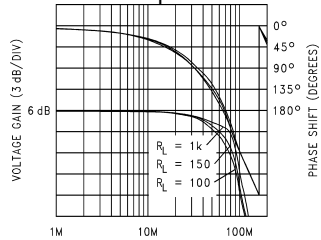


Typical Performance Characteristics (continued)

$T_A = 25^\circ\text{C}$ unless otherwise noted

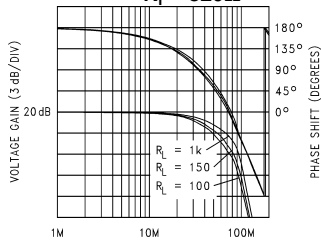
NON-INVERTING GAIN FREQUENCY RESPONSE

$V_S = \pm 15\text{V}$; $A_V = +2$;
 $R_f = 820\Omega$



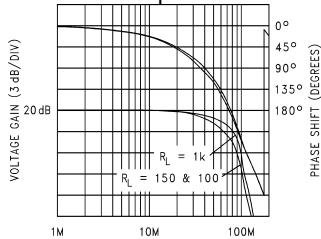
INVERTING GAIN FREQUENCY RESPONSE

$V_S = \pm 15\text{V}$; $A_V = -10$;
 $R_f = 820\Omega$



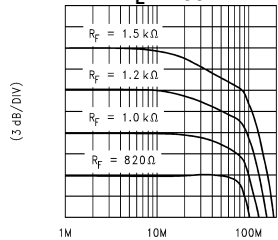
NON-INVERTING GAIN FREQUENCY RESPONSE

$V_S = \pm 15\text{V}$; $A_V = +10$;
 $R_f = 820\Omega$



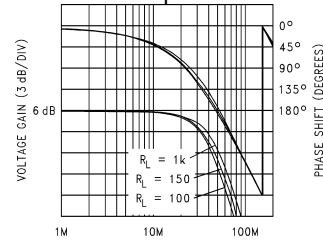
NON-INVERTING GAIN FREQUENCY COMPENSATION

$V_S = \pm 15\text{V}$; $A_V = +2$;
 $R_L = 150\Omega$



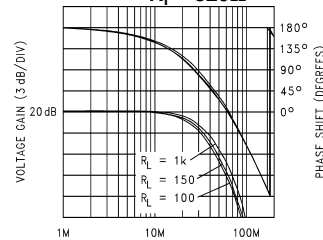
NON-INVERTING GAIN FREQUENCY RESPONSE

$V_S = \pm 5\text{V}$; $A_V = +2$;
 $R_f = 820\Omega$



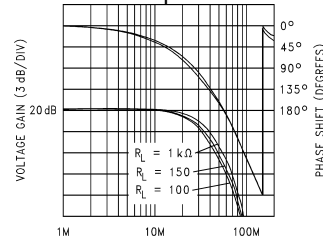
INVERTING GAIN FREQUENCY RESPONSE

$V_S = \pm 5\text{V}$; $A_V = -10$;
 $R_f = 820\Omega$



NON-INVERTING GAIN FREQUENCY RESPONSE

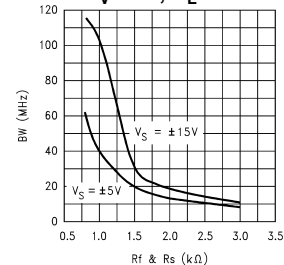
$V_S = \pm 5\text{V}$; $A_V = +10$;
 $R_f = 820\Omega$



BANDWIDTH

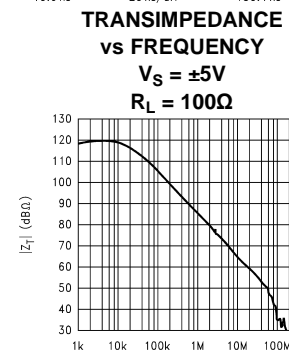
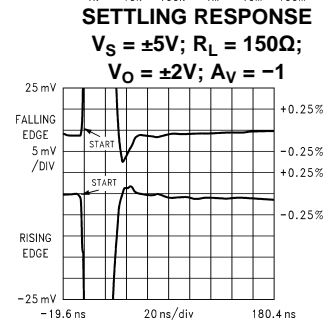
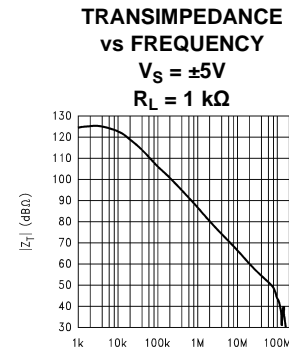
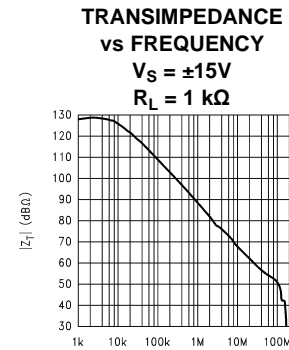
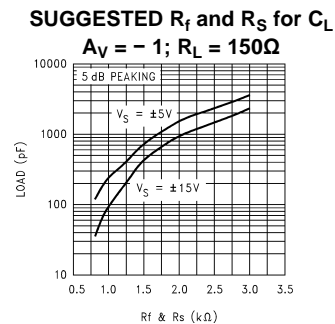
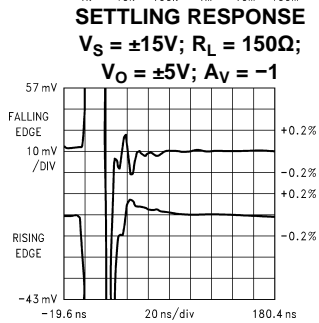
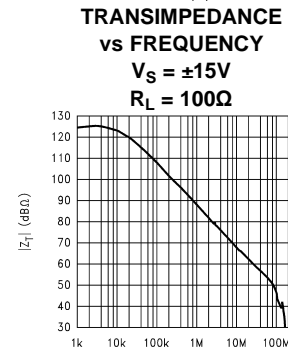
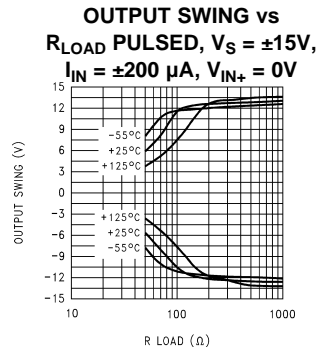
vs
 R_f & R_S

$A_V = -1$, $R_L = 1\text{ k}\Omega$



Typical Performance Characteristics (continued)

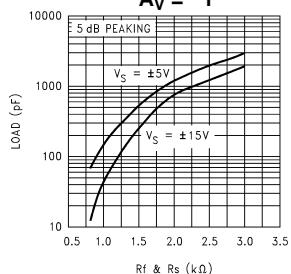
$T_A = 25^\circ\text{C}$ unless otherwise noted



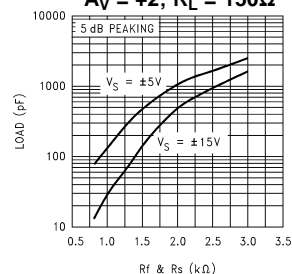
Typical Performance Characteristics (continued)

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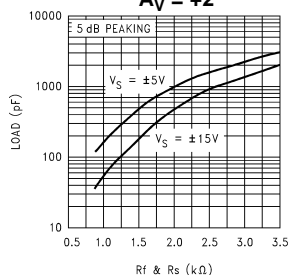
**SUGGESTED R_f
and R_S FOR C_L
 $A_V = -1$**



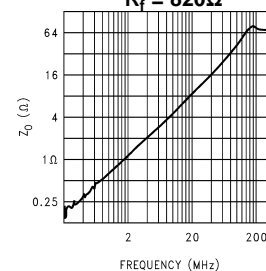
**SUGGESTED R_f
and R_S FOR C_L
 $A_V = +2$; $R_L = 150\Omega$**



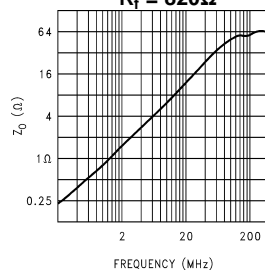
**SUGGESTED R_f
and R_S FOR C_L
 $A_V = +2$**



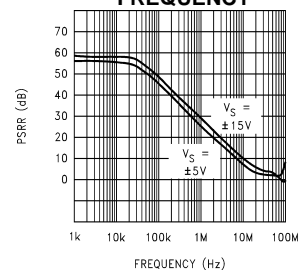
**OUTPUT IMPEDANCE
vs FREQ
 $V_S = \pm 15\text{V}$; $A_V = -1$
 $R_f = 820\Omega$**



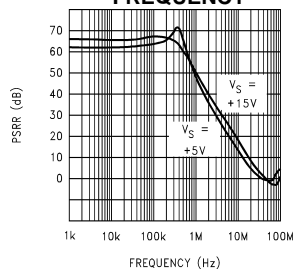
**OUTPUT IMPEDANCE
vs FREQ
 $V_S = \pm 5\text{V}$; $A_V = -1$
 $R_f = 820\Omega$**



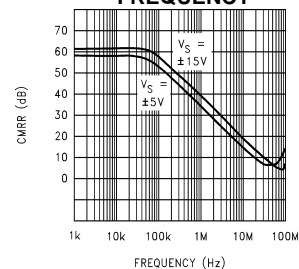
**PSRR (V_S^+)
vs
FREQUENCY**



**PSRR (V_S^-)
vs
FREQUENCY**



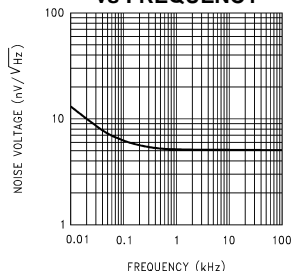
**CMRR
vs
FREQUENCY**



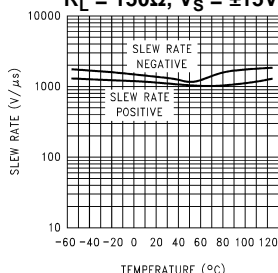
Typical Performance Characteristics (continued)

$T_A = 25^\circ\text{C}$ unless otherwise noted

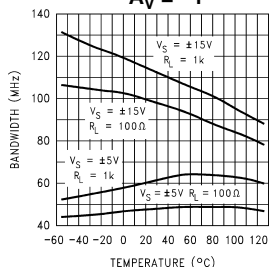
**INPUT VOLTAGE NOISE
vs FREQUENCY**



**SLEW RATE vs
TEMPERATURE $A_V = -1$;
 $R_L = 150\Omega$, $V_S = \pm 15V$**

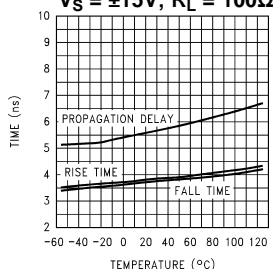


**-3 dB BANDWIDTH
vs TEMPERATURE
 $A_V = -1$**

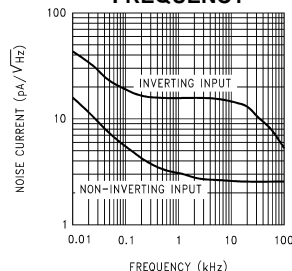


**SMALL SIGNAL PULSE
RESPONSE**

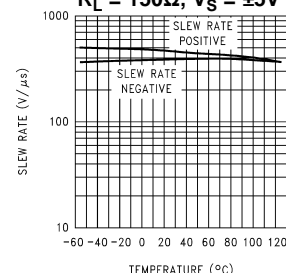
**vs
TEMP,
 $A_V = +1$
 $V_S = \pm 15V$; $R_L = 100\Omega$**



**INPUT CURRENT
NOISE
vs
FREQUENCY**

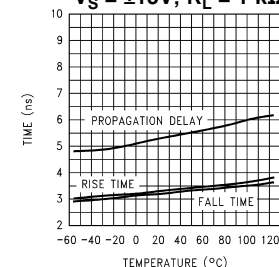


**SLEW RATE vs
TEMPERATURE $A_V = -1$;
 $R_L = 150\Omega$, $V_S = \pm 5V$**



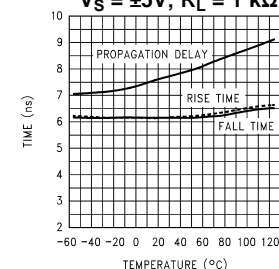
**SMALL SIGNAL PULSE
RESPONSE**

**vs
TEMP,
 $A_V = +1$
 $V_S = \pm 15V$; $R_L = 1\text{ k}\Omega$**



**SMALL SIGNAL PULSE
RESPONSE**

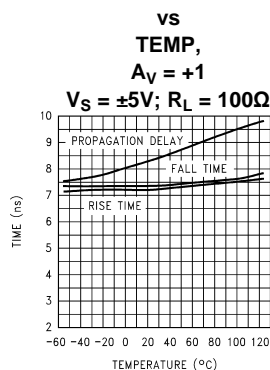
**vs
TEMP,
 $A_V = +1$
 $V_S = \pm 5V$; $R_L = 1\text{ k}\Omega$**



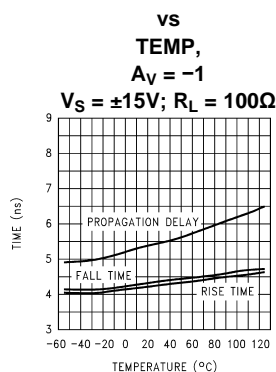
Typical Performance Characteristics (continued)

$T_A = 25^\circ\text{C}$ unless otherwise noted

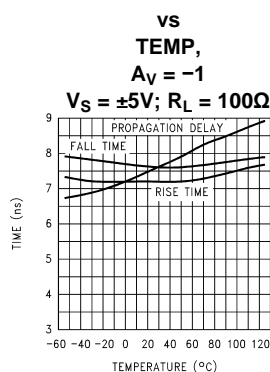
SMALL SIGNAL PULSE RESPONSE



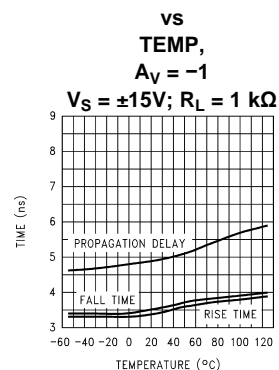
SMALL SIGNAL PULSE RESPONSE



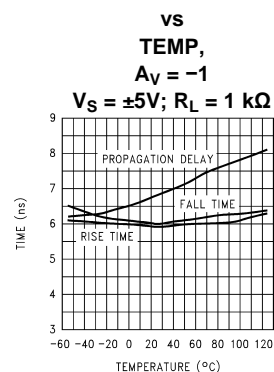
SMALL SIGNAL PULSE RESPONSE



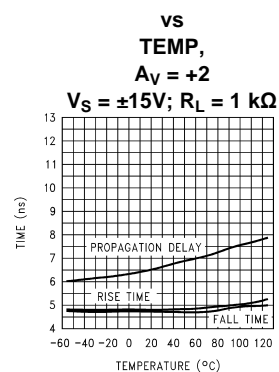
SMALL SIGNAL PULSE RESPONSE



SMALL SIGNAL PULSE RESPONSE



SMALL SIGNAL PULSE RESPONSE



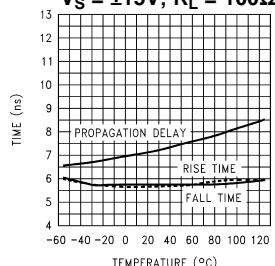
Typical Performance Characteristics (continued)

$T_A = 25^\circ\text{C}$ unless otherwise noted

SMALL SIGNAL PULSE RESPONSE

vs
TEMP,
 $A_V = +2$

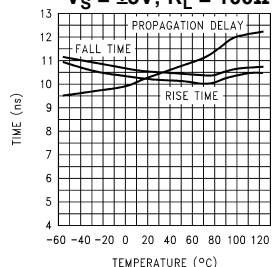
$V_S = \pm 15\text{V}; R_L = 100\Omega$



SMALL SIGNAL PULSE RESPONSE

vs
TEMP,
 $A_V = +2$

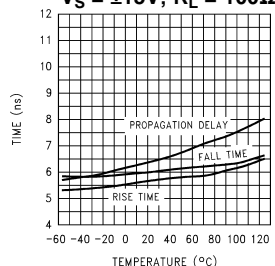
$V_S = \pm 5\text{V}; R_L = 100\Omega$



SMALL SIGNAL PULSE RESPONSE

vs
TEMP,
 $A_V = -10$

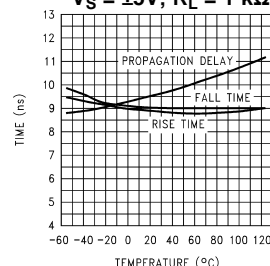
$V_S = \pm 15\text{V}; R_L = 100\Omega$



SMALL SIGNAL PULSE RESPONSE

vs
TEMP,
 $A_V = +2$

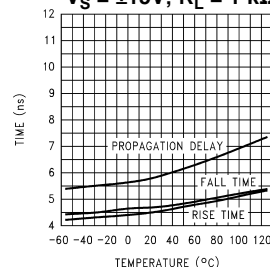
$V_S = \pm 5\text{V}; R_L = 1\text{ k}\Omega$



SMALL SIGNAL PULSE RESPONSE

vs
TEMP,
 $A_V = -10$

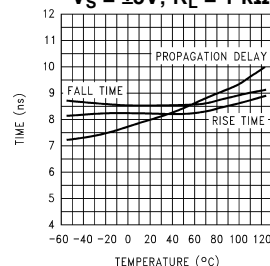
$V_S = \pm 15\text{V}; R_L = 1\text{ k}\Omega$



SMALL SIGNAL PULSE RESPONSE

vs
TEMP,
 $A_V = -10$

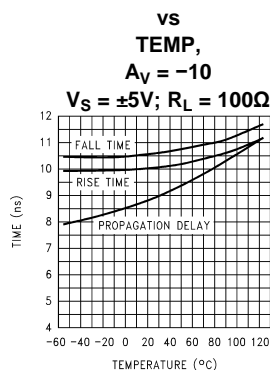
$V_S = \pm 5\text{V}; R_L = 1\text{ k}\Omega$



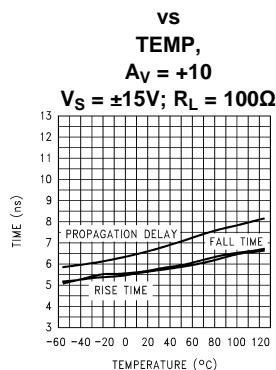
Typical Performance Characteristics (continued)

$T_A = 25^\circ\text{C}$ unless otherwise noted

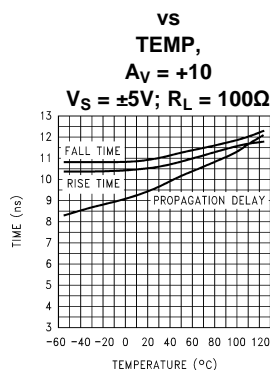
SMALL SIGNAL PULSE RESPONSE



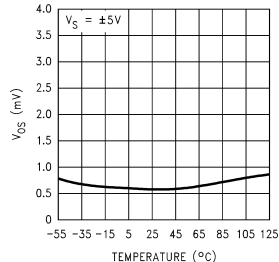
SMALL SIGNAL PULSE RESPONSE



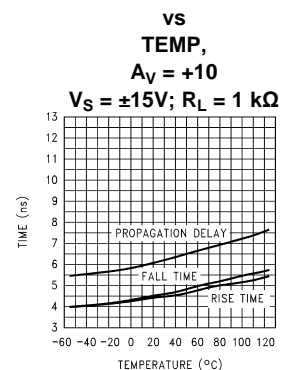
SMALL SIGNAL PULSE RESPONSE



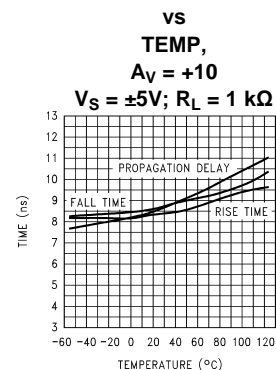
OFFSET VOLTAGE vs TEMPERATURE



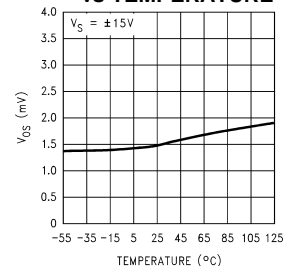
SMALL SIGNAL PULSE RESPONSE



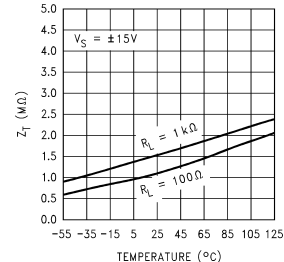
SMALL SIGNAL PULSE RESPONSE



OFFSET VOLTAGE vs TEMPERATURE



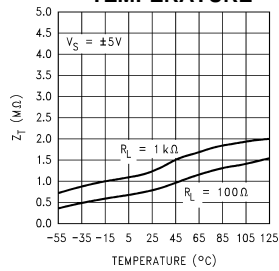
TRANSIMPEDANCE vs TEMPERATURE



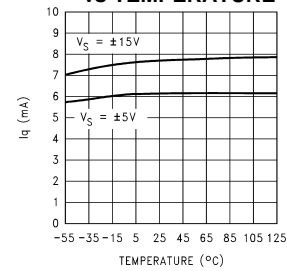
Typical Performance Characteristics (continued)

$T_A = 25^\circ\text{C}$ unless otherwise noted

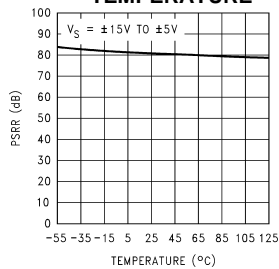
**TRANSIMPEDANCE vs
TEMPERATURE**



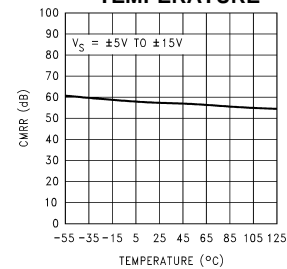
**QUIESCENT CURRENT
vs TEMPERATURE**



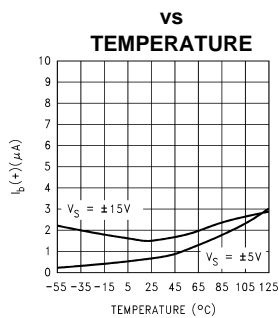
**PSRR
vs
TEMPERATURE**



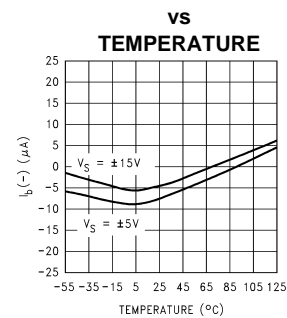
**CMRR
vs
TEMPERATURE**



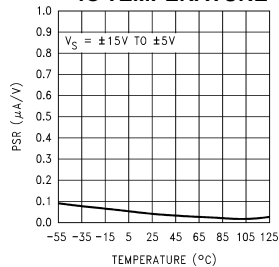
**NON-INVERTING BIAS
CURRENT**



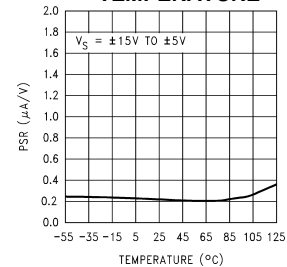
**INVERTING BIAS
CURRENT**



**PSR $I_{B(+)}$
vs TEMPERATURE**

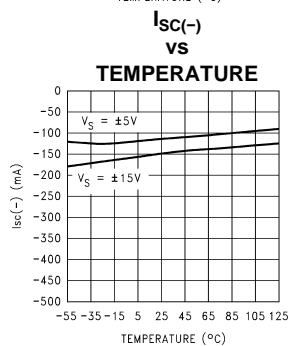
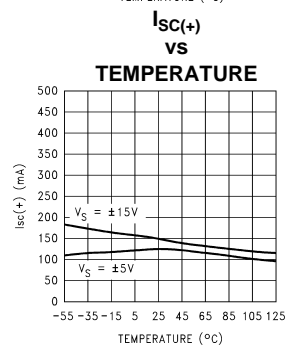
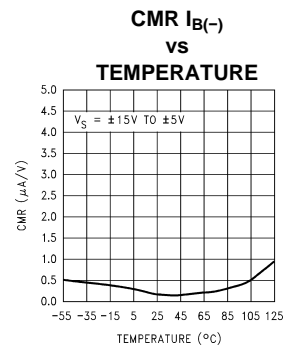
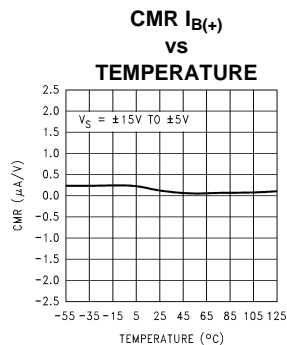


**PSR $I_{B(-)}$
vs
TEMPERATURE**



Typical Performance Characteristics (continued)

$T_A = 25^\circ\text{C}$ unless otherwise noted



Typical Performance Characteristics

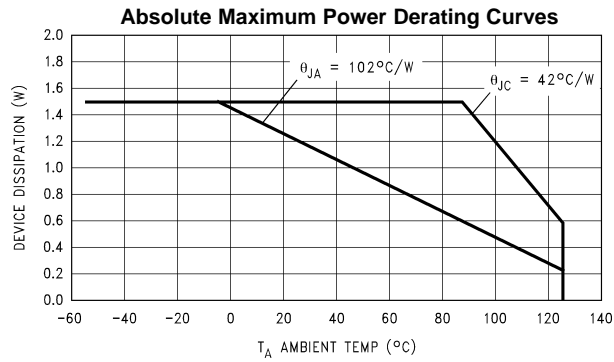


Figure 2. N-Package

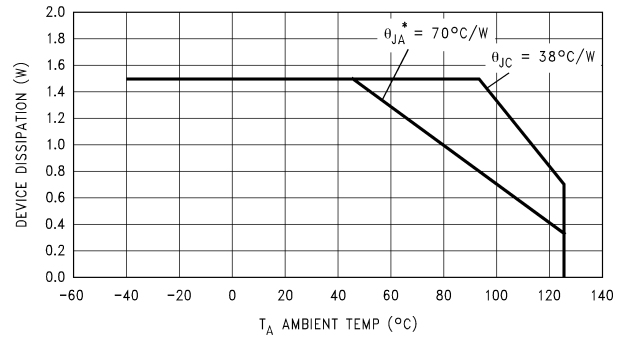


Figure 3. M-Package

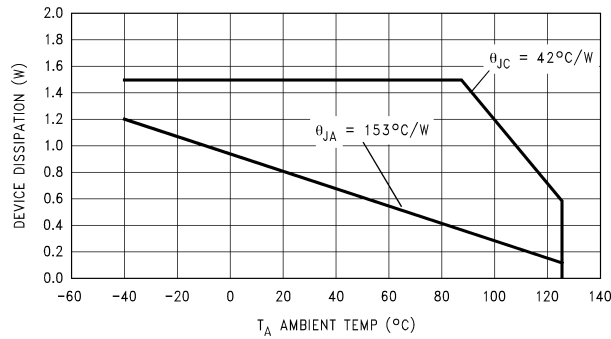
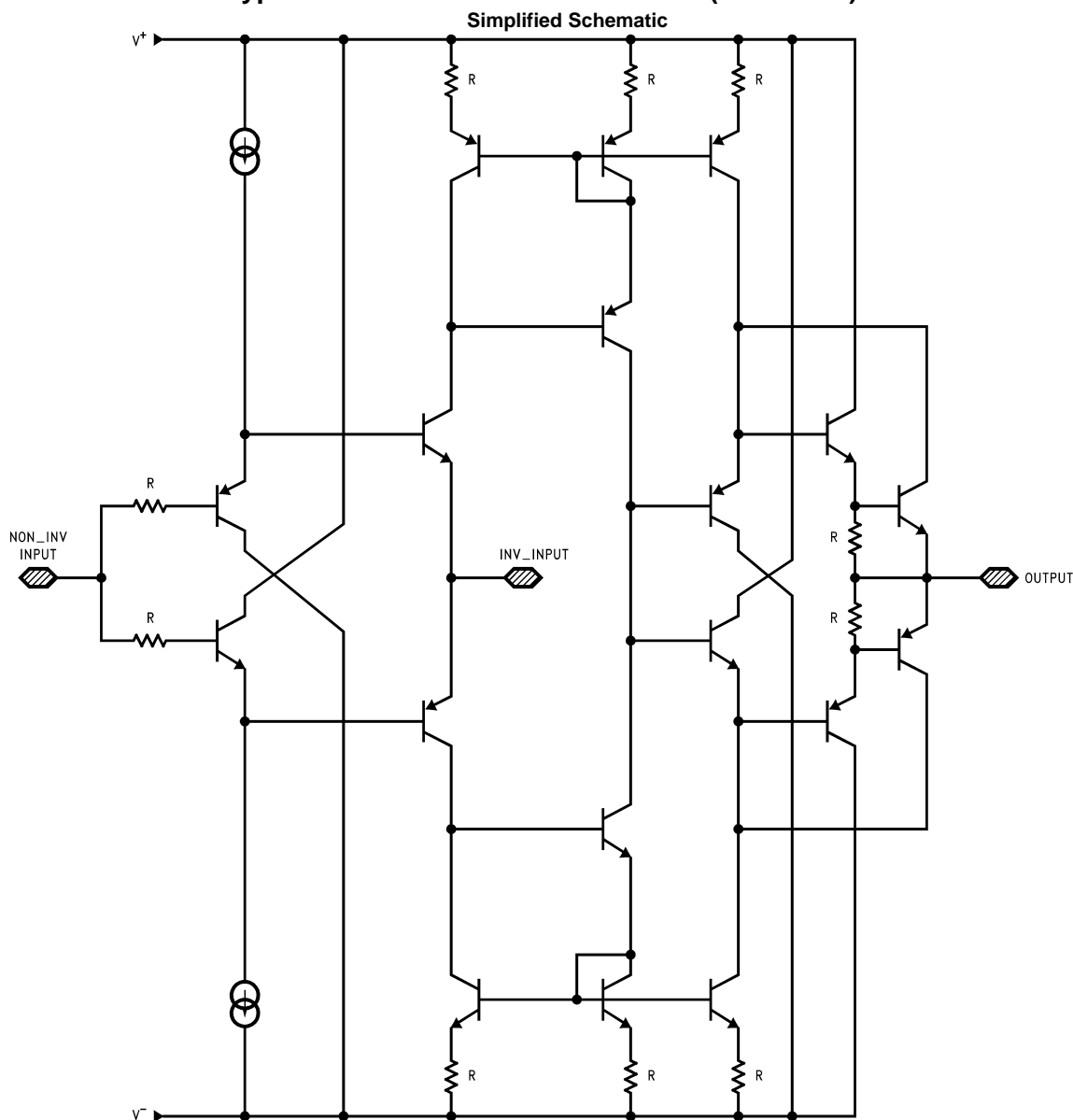


Figure 4. M-8 Package

* θ_{JA} = Thermal Resistance with 2 square inches of 1 ounce Copper tied to Pins 1, 8, 9 and 16.

Typical Performance Characteristics (continued)



Typical Applications

CURRENT FEEDBACK TOPOLOGY

For a conventional voltage feedback amplifier the resulting small-signal bandwidth is inversely proportional to the desired gain to a first order approximation based on the gain-bandwidth concept. In contrast, the current feedback amplifier topology, such as the LM6181, transcends this limitation to offer a signal bandwidth that is relatively independent of the closed-loop gain. [Figure 6a](#) and [Figure 6b](#) illustrate that for closed loop gains of -1 and -5 the resulting pulse fidelity suggests quite similar bandwidths for both configurations.

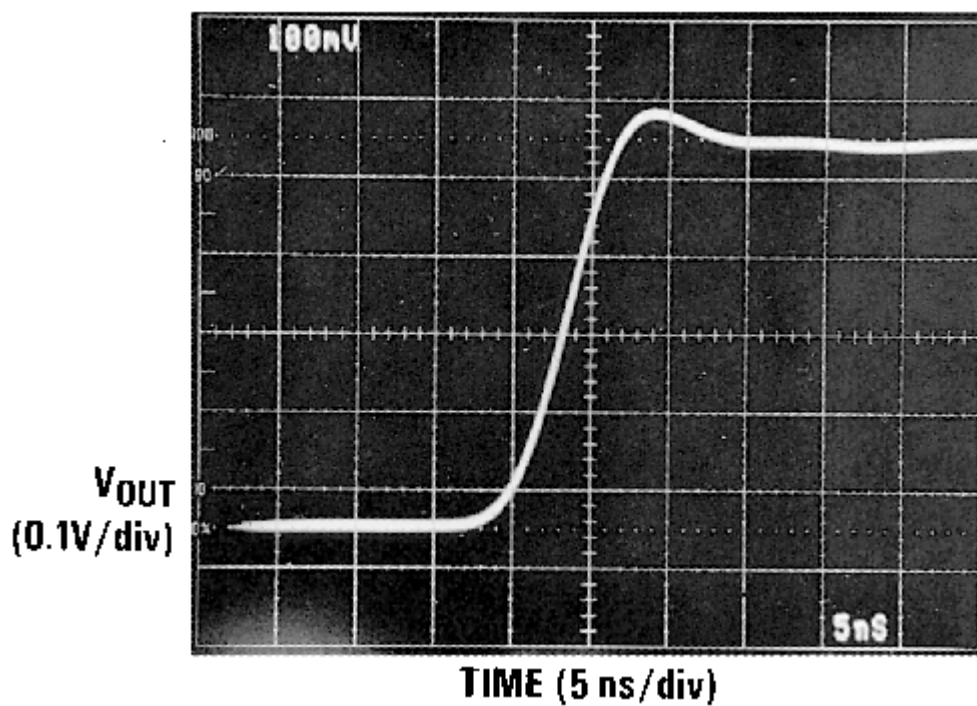
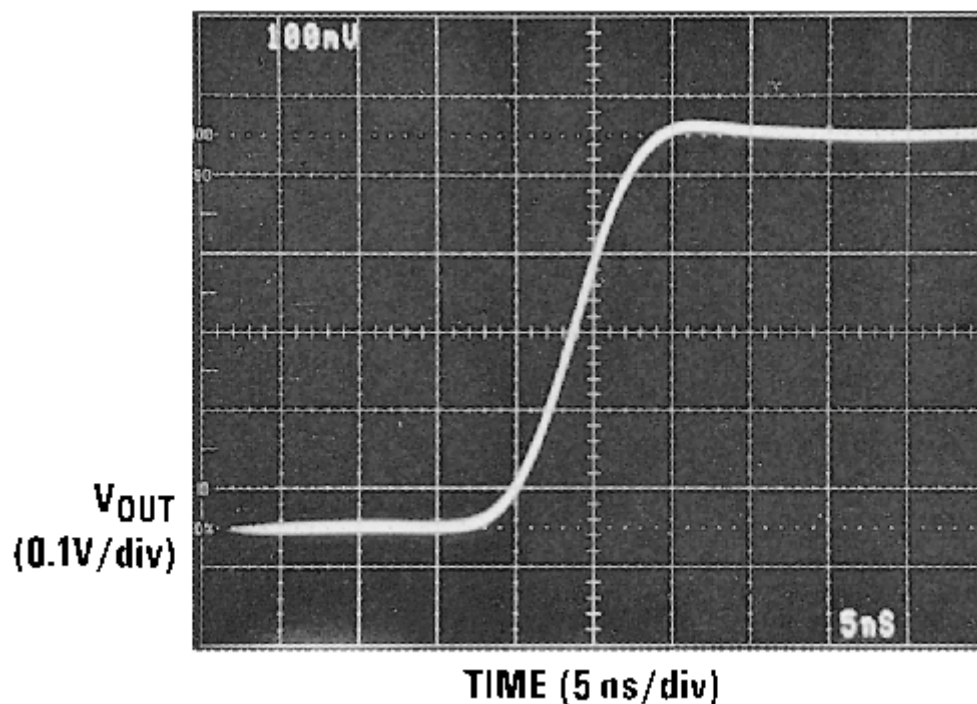


Figure 5. 1a



1b

Figure 6. 1a, 1b: Variation of Closed Loop Gain from -1 to -5 Yields Similar Responses

The closed-loop bandwidth of the LM6181 depends on the feedback resistance, R_f . Therefore, R_s and not R_f , must be varied to adjust for the desired closed-loop gain as in [Figure 7](#).

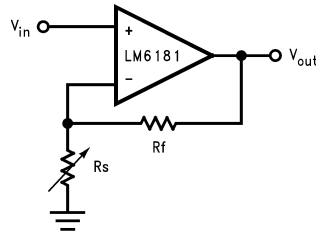


Figure 7. R_s Is Adjusted to Obtain the Desired Closed Loop Gain, A_{VCL}

POWER SUPPLY BYPASSING AND LAYOUT CONSIDERATIONS

A fundamental requirement for high-speed amplifier design is adequate bypassing of the power supply. It is critical to maintain a wideband low-impedance to ground at the amplifiers supply pins to insure the fidelity of high speed amplifier transient signals. 10 μ F tantalum and 0.1 μ F ceramic bypass capacitors are recommended for each supply pin. The bypass capacitors should be placed as close to the amplifier pins as possible (0.5" or less).

FEEDBACK RESISTOR SELECTION: R_f

Selecting the feedback resistor, R_f , is a dominant factor in compensating the LM6181. For general applications the LM6181 will maintain specified performance with an 820 Ω feedback resistor. Although this value will provide good results for most applications, it may be advantageous to adjust this value slightly. Consider, for instance, the effect on pulse responses with two different configurations where both the closed-loop gains are 2 and the feedback resistors are 820 Ω and 1640 Ω , respectively. [Figure 9a](#) and [Figure 9b](#) illustrate the effect of increasing R_f while maintaining the same closed-loop gain—the amplifier bandwidth decreases. Accordingly, larger feedback resistors can be used to slow down the LM6181 (see -3 dB bandwidth vs R_f typical curves) and reduce overshoot in the time domain response. Conversely, smaller feedback resistance values than 820 Ω can be used to compensate for the reduction of bandwidth at high closed loop gains, due to 2nd order effects. For example [Figure 10](#) illustrates reducing R_f to 500 Ω to establish the desired small signal response in an amplifier configured for a closed loop gain of 25.

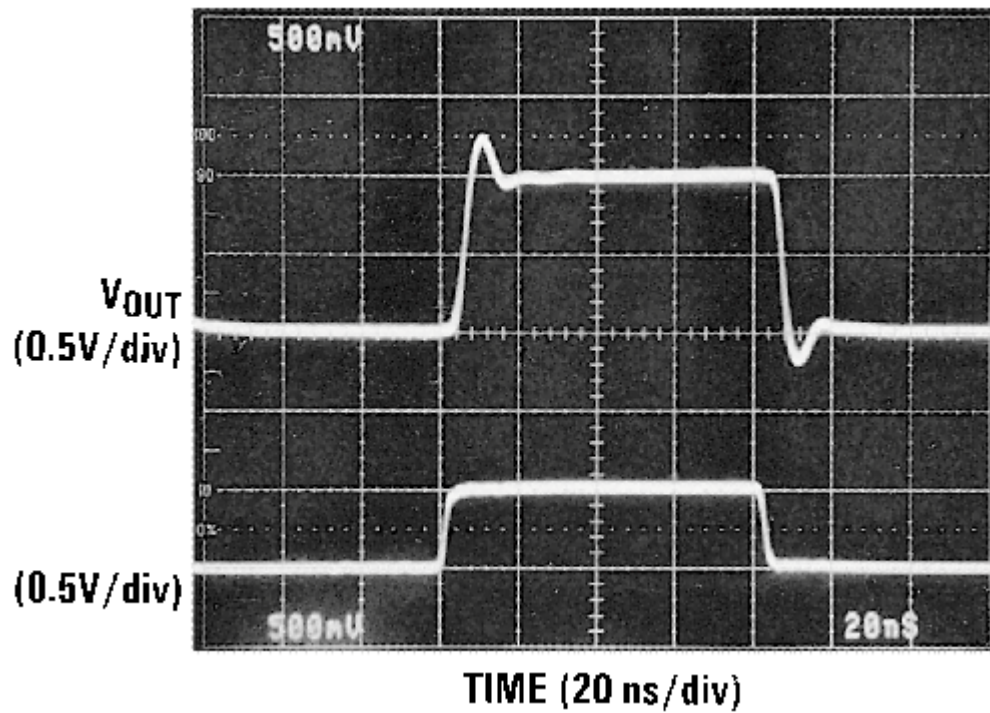
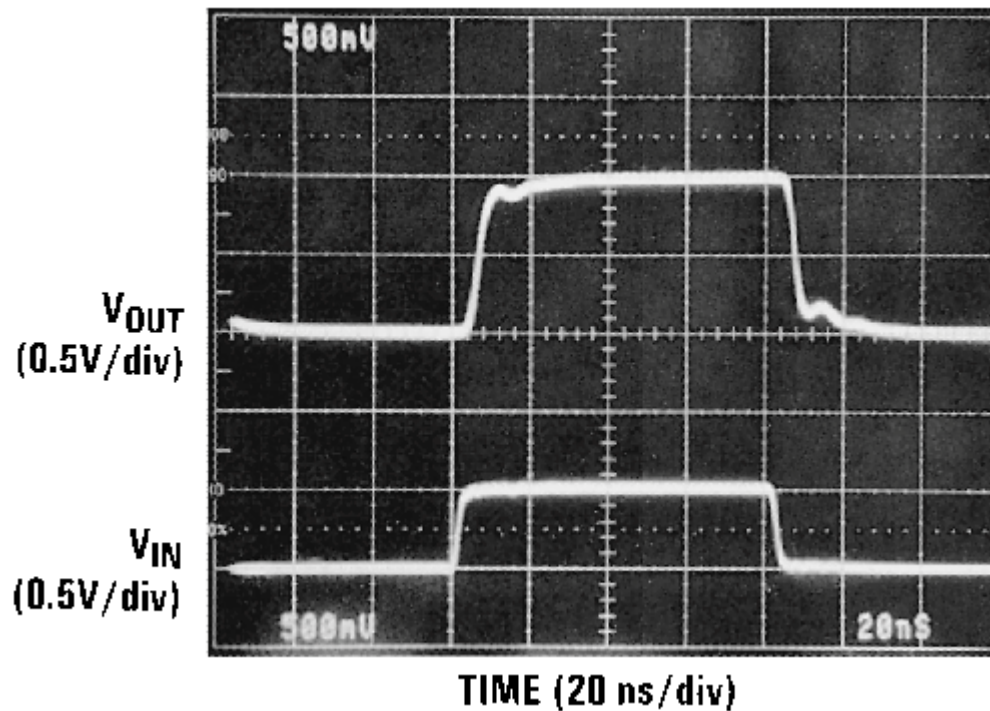


Figure 8. 3a: $R_f = 820\Omega$



3b: $R_f = 1640\Omega$

Figure 9. Increasing Compensation
with Increasing R_f

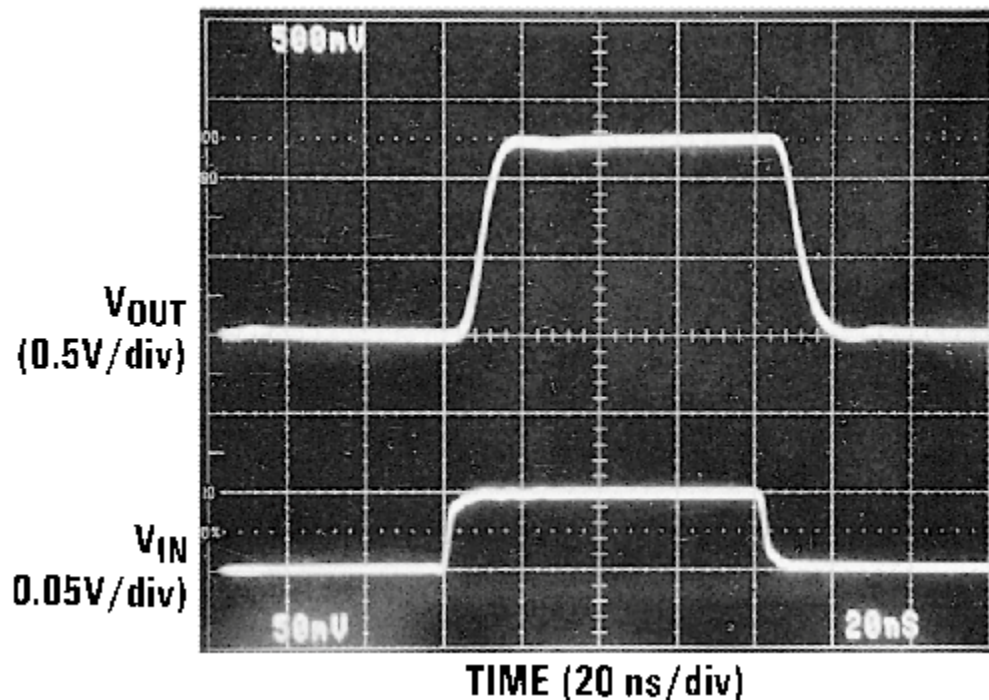


Figure 10. Reducing R_f for Large Closed Loop Gains, $R_f = 500\Omega$

SLEW RATE CONSIDERATIONS

The slew rate characteristics of current feedback amplifiers are different than traditional voltage feedback amplifiers. In voltage feedback amplifiers slew rate limiting or non-linear amplifier behavior is dominated by the finite availability of the 1st stage tail current charging the compensation capacitor. The slew rate of current feedback amplifiers, in contrast, is not constant. Transient current at the inverting input determines slew rate for both inverting and non-inverting gains. The non-inverting configuration slew rate is also determined by input stage limitations. Accordingly, variations of slew rates occur for different circuit topologies.

DRIVING CAPACITIVE LOADS

The LM6181 can drive significantly larger capacitive loads than many current feedback amplifiers. Although the LM6181 can directly drive as much as 100 pF without oscillating, the resulting response will be a function of the feedback resistor value. Figure 12 illustrates the small-signal pulse response of the LM6181 while driving a 50 pF load. Ringing persists for approximately 70 ns. To achieve pulse responses with less ringing either the feedback resistor can be increased (see typical curves Suggested R_f and R_s for C_L), or resistive isolation can be used (10 Ω –51 Ω typically works well). Either technique, however, results in lowering the system bandwidth.

Figure 14 illustrates the improvement obtained with using a 47 Ω isolation resistor.

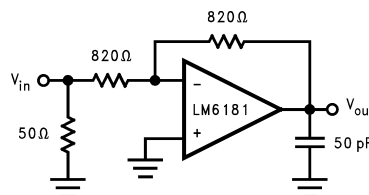
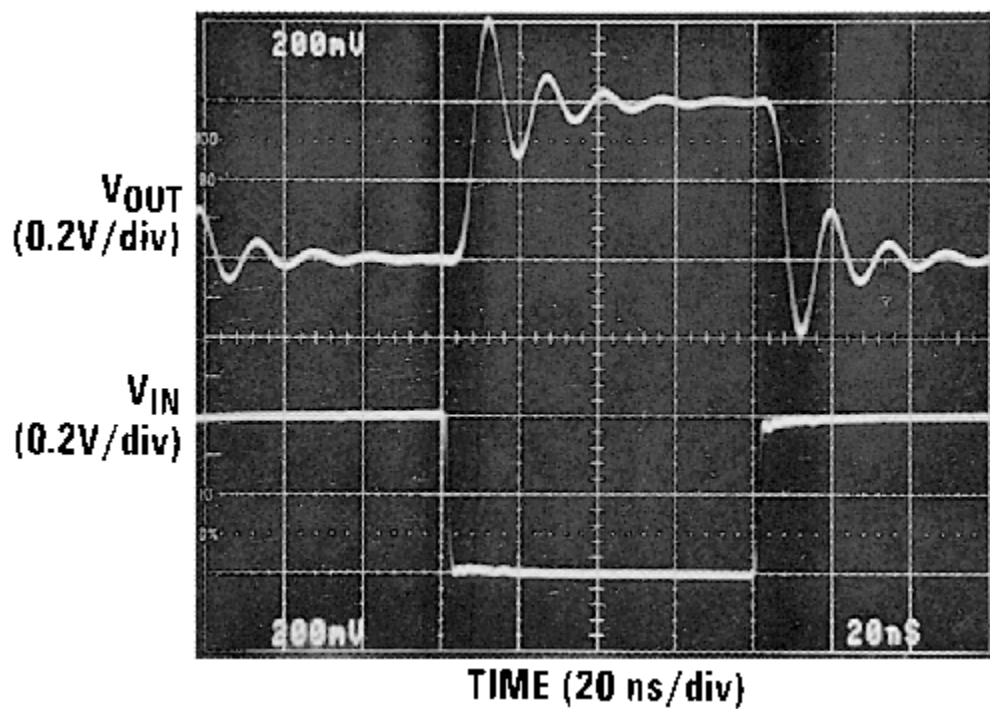


Figure 11. 5a



5b

Figure 12. $A_V = -1$, LM6181 Can Directly Drive 50 pF of Load Capacitance with 70 ns of Ringing Resulting in Pulse Response

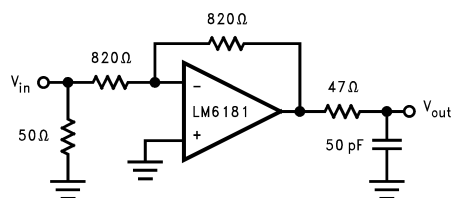
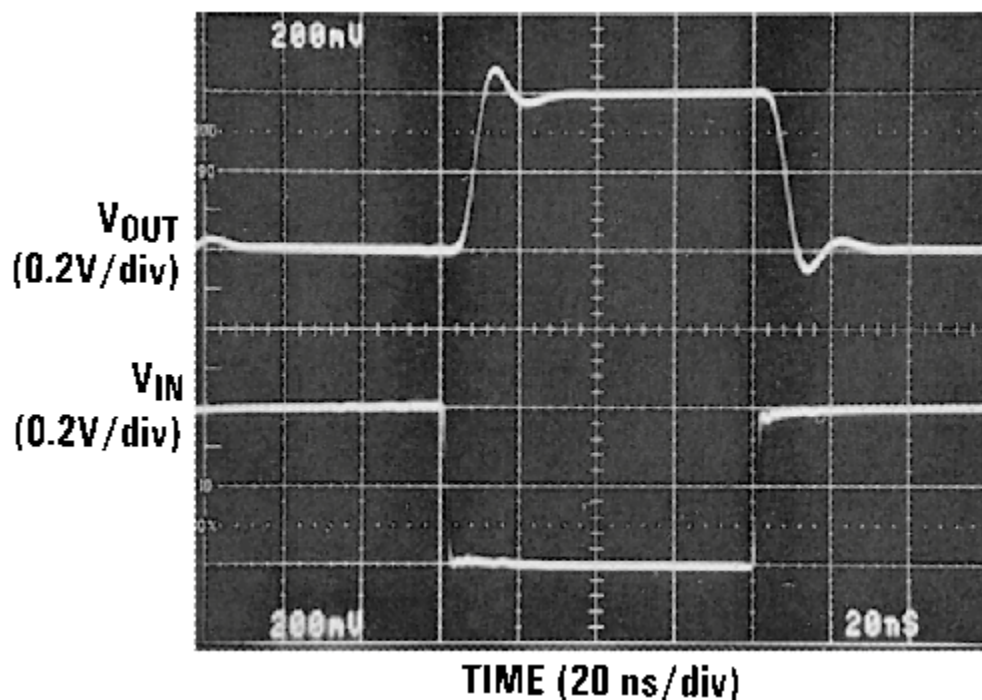


Figure 13. 6a

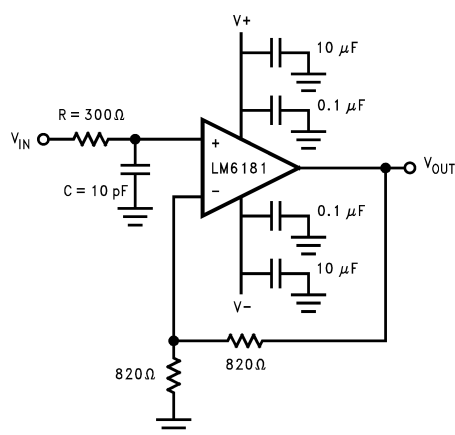


6b

Figure 14. Resistive Isolation of C_L Provides Higher Fidelity Pulse Response. R_f and R_S Could Be Increased to Maintain $A_V = -1$ and Improve Pulse Response Characteristics.

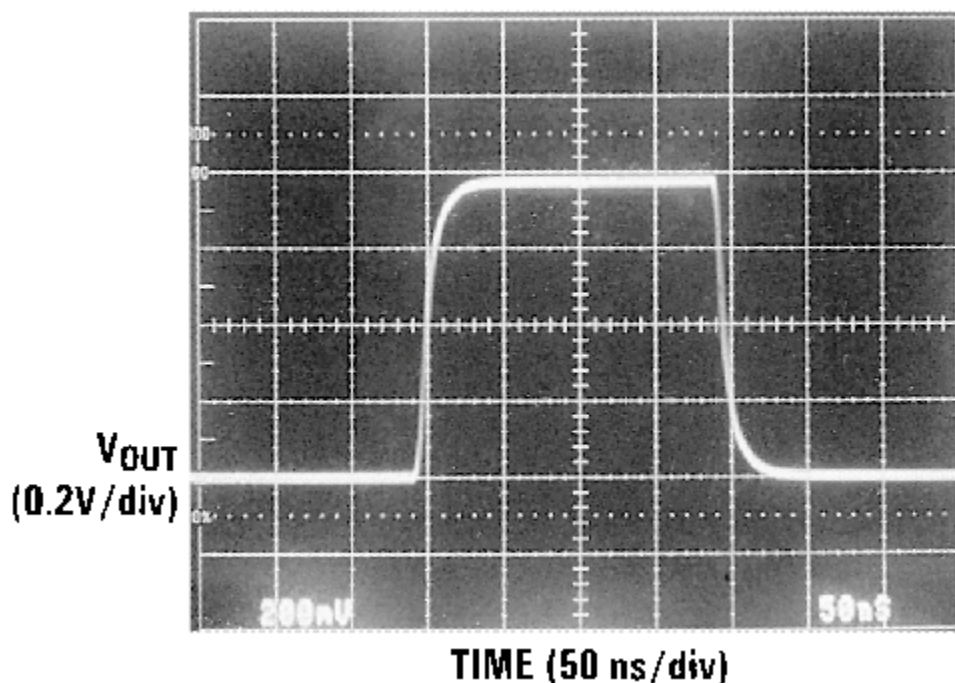
CAPACITIVE FEEDBACK

For voltage feedback amplifiers it is quite common to place a small lead compensation capacitor in parallel with feedback resistance, R_f . This compensation serves to reduce the amplifier's peaking in the frequency domain which equivalently tames the transient response. To limit the bandwidth of current feedback amplifiers, do not use a capacitor across R_f . The dynamic impedance of capacitors in the feedback loop reduces the amplifier's stability. Instead, reduced peaking in the frequency response, and bandwidth limiting can be accomplished by adding an RC circuit, as illustrated in [Figure 16b](#).



$$f_{-3\text{ dB}} = \frac{1}{2\pi RC}$$

Figure 15. 7a



7b

**Figure 16. RC Limits Amplifier
Bandwidth to 50 MHz, Eliminating
Peaking in the Resulting Pulse Response**

Typical Performance Characteristics

OVERDRIVE RECOVERY

When the output or input voltage range of a high speed amplifier is exceeded, the amplifier must recover from an overdrive condition. The typical recovery times for open-loop, closed-loop, and input common-mode voltage range overdrive conditions are illustrated in [Figure 18](#) [Figure 20](#) [Figure 20](#) [Figure 21](#) respectively.

The open-loop circuit of [Figure 17](#) generates an overdrive response by allowing the $\pm 0.5V$ input to exceed the linear input range of the amplifier. Typical positive and negative overdrive recovery times shown in [Figure 18](#) are 5 ns and 25 ns, respectively.

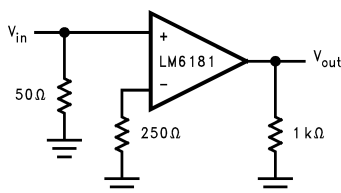


Figure 17.

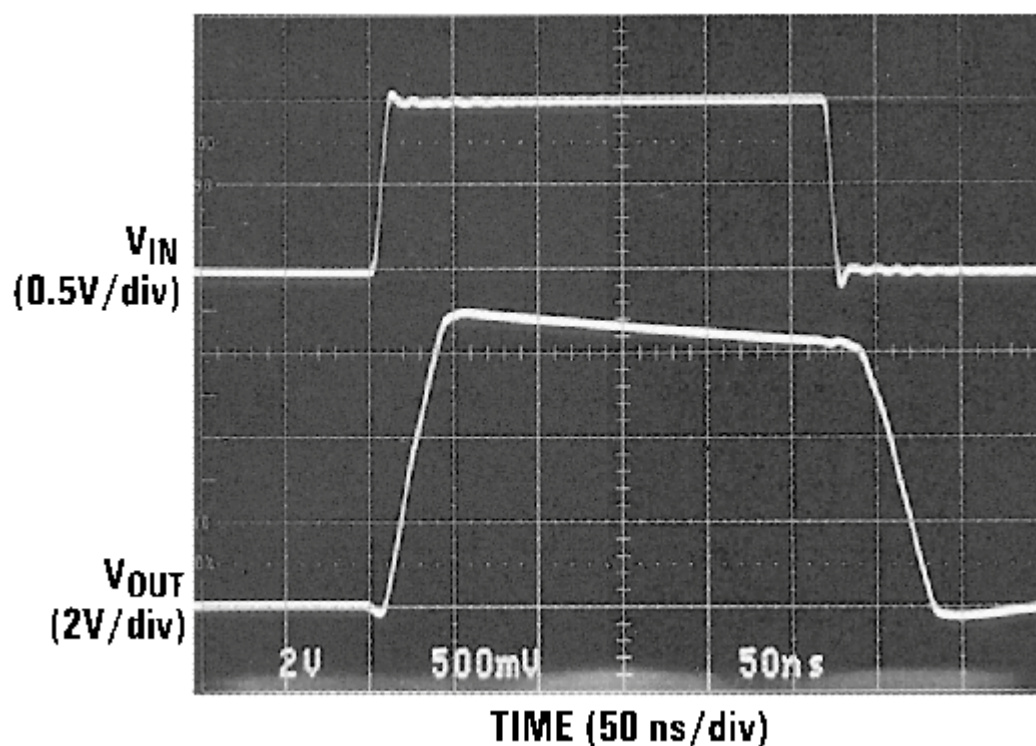


Figure 18. Open-Loop Overdrive Recovery Time of 5 ns, and 25 ns from Test Circuit in [Figure 17](#)

The large closed-loop gain configuration in [Figure 19](#) forces the amplifier output into overdrive. [Figure 20](#) displays the typical 30 ns recovery time to a linear output value.

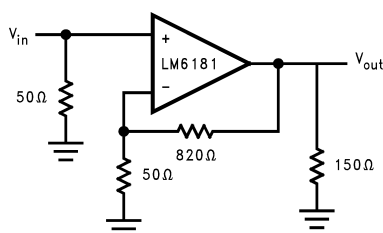


Figure 19.

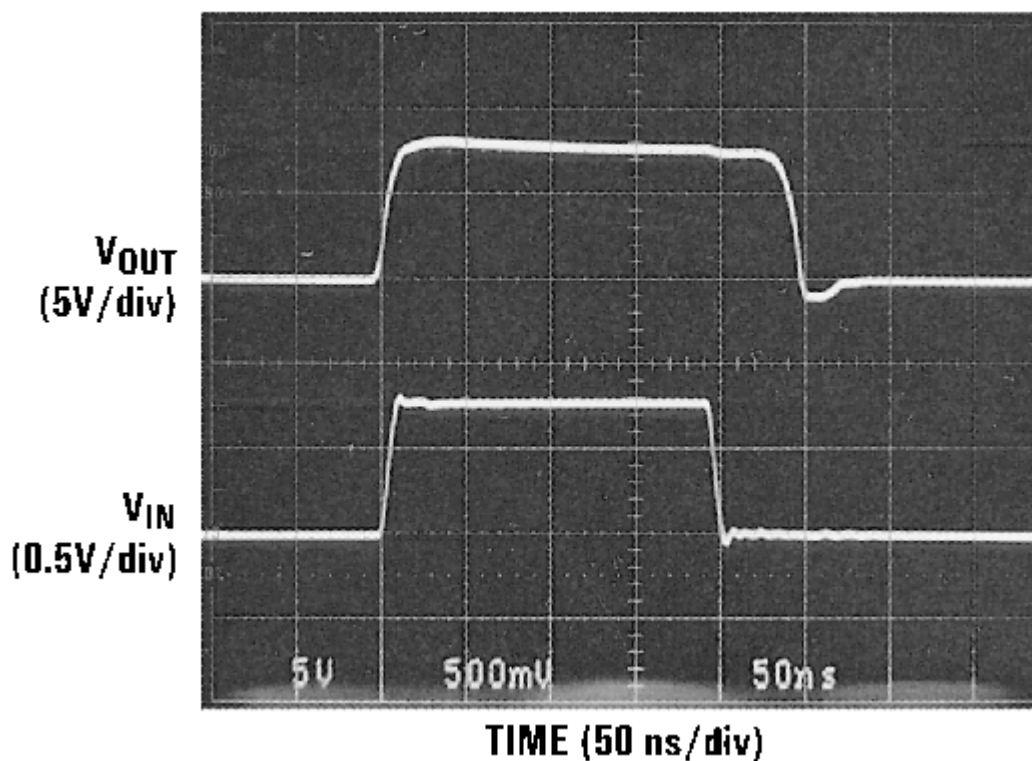


Figure 20. Closed-Loop Overdrive Recovery
Time of 30 ns from Exceeding Output
Voltage Range from Circuit in [Figure 19](#)

The common-mode input of the circuit in [Figure 19](#) is exceeded by a 5V pulse resulting in a typical recovery time of 310 ns shown in [Figure 21](#). The LM6181 supply voltage is $\pm 5V$.

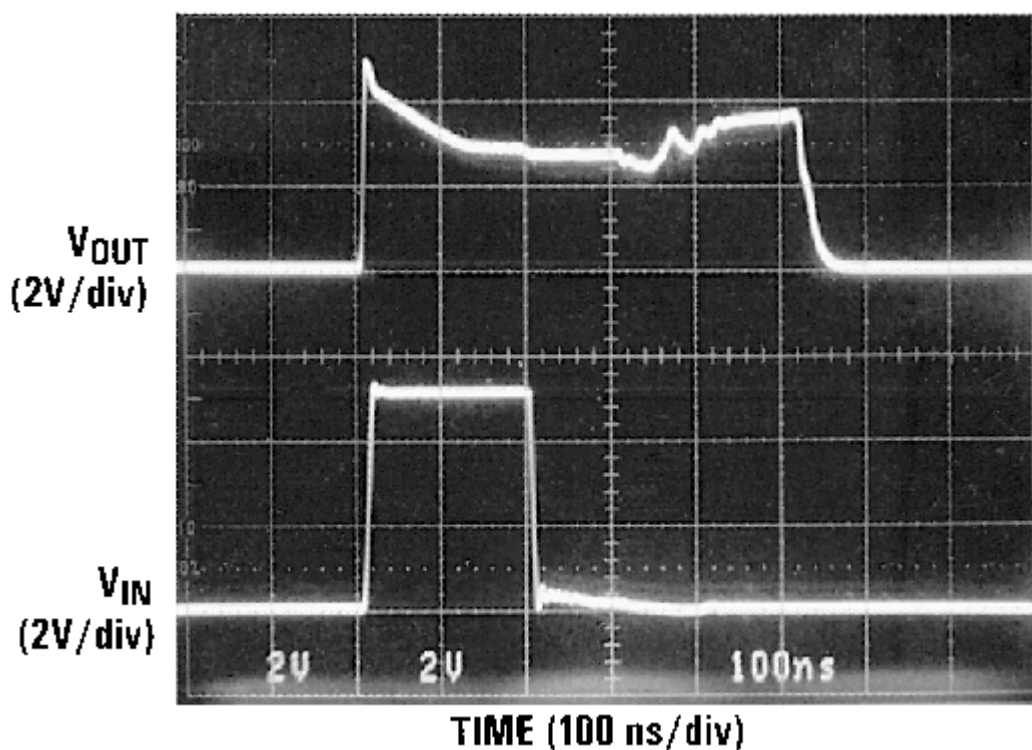
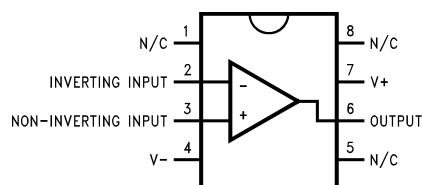


Figure 21. Exceptional Output Recovery from an Input that Exceeds the Common-Mode Range

Connection Diagrams

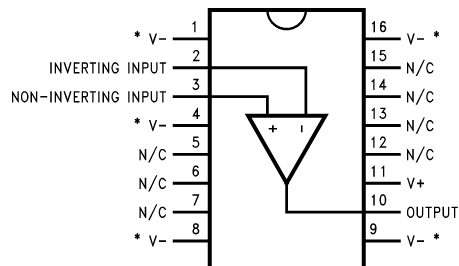
(For Ordering Information See Back Page)

8-Pin Dual-In-Line Package (N)/ Small Outline (M-8)



**Figure 22. Order Number LM6181IN, LM6181AIN, LM6181AMN, LM6181AIM-8, LM6181IM-8 or LM6181AMJ/883
See NS Package Number J08A, M08A or N08E**

16-Pin Small Outline Package (M)



*Heat sinking pins ⁽¹⁾

**Figure 23. Order Number LM6181IM or LM6181AIM
See NS Package Number M16A**

- (1) The typical junction-to-ambient thermal resistance of the molded plastic DIP(N) package soldered directly into a PC board is 102°C/W. The junction-to-ambient thermal resistance of the S.O. surface mount (M) package mounted flush to the PC board is 70°C/W when pins 1, 4, 8, 9 and 16 are soldered to a total 2 in² 1 oz. copper trace. The 16-pin S.O. (M) package must have pin 4 and at least one of pins 1, 8, 9, or 16 connected to V⁻ for proper operation. The typical junction-to-ambient thermal resistance of the S.O. (M-8) package soldered directly into a PC board is 153°C/W.

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish	MSL Peak Temp (3)	Samples (Requires Login)
LM6181IM-8	ACTIVE	SOIC	D	8	95	TBD	CU SNPB	Level-1-235C-UNLIM	
LM6181IM-8/NOPB	ACTIVE	SOIC	D	8	95	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	
LM6181IMX-8/NOPB	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	
LM6181IN	ACTIVE	PDIP	P	8	40	TBD	CU SNPB	Level-1-NA-UNLIM	
LM6181IN/NOPB	ACTIVE	PDIP	P	8	40	Green (RoHS & no Sb/Br)	CU SN	Level-1-NA-UNLIM	

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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TAPE AND REEL INFORMATION


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LM6181IMX-8/NOPB	SOIC	D	8	2500	330.0	12.4	6.5	5.4	2.0	8.0	12.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LM6181IMX-8/NOPB	SOIC	D	8	2500	349.0	337.0	45.0

P (R-PDIP-T8)

PLASTIC DUAL-IN-LINE PACKAGE



- NOTES:
- A. All linear dimensions are in inches (millimeters).
 - B. This drawing is subject to change without notice.
 - C. Falls within JEDEC MS-001 variation BA.

D (R-PDSO-G8)

PLASTIC SMALL OUTLINE



- NOTES:
- A. All linear dimensions are in inches (millimeters).
 - B. This drawing is subject to change without notice.
 - $\triangle C$ Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
 - $\triangle D$ Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
 - E. Reference JEDEC MS-012 variation AA.

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