# **Signetics**

### Linear Products

### DESCRIPTION

The SAB3035 provides closed-loop digital tuning of TV receivers, with or without AFC, as required. It also controls up to 8 analog functions, 4 general purpose I/O ports, and 4 high-current outputs for tuner band selection.

The IC is used in conjunction with a microcomputer from the MAB8400 family and is controlled via a two-wire, bidirectional  $I^2C$  bus.

### **FEATURES**

- Combined analog and digital circuitry minimizes the number of additional interfacing components required
- Frequency measurement with resolution of 50kHz
- Selectable prescaler divisor of 64 or 256
- 32V tuning voltage amplifier

### **ORDERING INFORMATION**

DESCRIPTION	TEMPERATURE RANGE	ORDER CODE
28-Pin Plastic DIP (SOT-117)	-20°C to +70°C	SAB3035N

### **ABSOLUTE MAXIMUM RATINGS**

SYMBOL	PARAMETER	RATING	UNIT
V <sub>CC1</sub> V <sub>CC2</sub> V <sub>CC3</sub>	Supply voltage ranges: (Pin 16) (Pin 22) (Pin 17)	-0.3 to +18 -0.3 to +18 -0.3 to +36	v v v
VSDA VSCL VC2X VAFC+, AFC- VTI VTUN VCC1X VFDIV VOSC VDACX	Input/output voltage ranges: (Pin 5) (Pin 6) (Pins 7 to 10) (Pins 11 and 12) (Pin 13) (Pin 15) (Pins 18 to 21) (Pin 23) (Pin 24) (Pins 1 to 4 and 25 to 28)	$\begin{array}{c} -0.3 \text{ to } +18 \\ -0.3 \text{ to } +18 \\ -0.3 \text{ to } +18 \\ -0.3 \text{ to } V_{CC1} \\ 1 \\ -0.3 \text{ to } V_{CC2} \\ 1 \\ -0.3 \text{ to } V_{CC2} \\ -0.3 \text{ to } V_{CC2} \\ -0.3 \text{ to } V_{CC1} \\ 1 \\ -0.3 \text{ to } +5 \\ -0.3 \text{ to } V_{CC1} \\ 1 \end{array}$	<<<<<<<
P <sub>TOT</sub>	Total power dissipation	1000	mW
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C
TA	Operating ambient temperature range	-20 to +70	°C

### PIN CONFIGURATION

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#### NOTES:

1. Pin voltage may exceed supply voltage if current is limited to 10mA.

2. Pin voltage must not exceed 18V but may exceed V<sub>CC2</sub> if current is limited to 200mA.

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**Product Specification** 

• 4 high-current outputs for direct

converters (DACs) for control of

• Tuning with control of speed and

band selection

analog functions

output (I/O) ports

direction

oscillator

APPLICATIONS

Satellite receivers

CATV converters

Television receivers

• 8 static digital-to-analog

Four general purpose input/

Tuning with or without AFC

Single-pin, 4MHz on-chip

I<sup>2</sup>C bus slave transceiver

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### **BLOCK DIAGRAM**



### SAB3035

## DC AND AC ELECTRICAL CHARACTERISTICS $T_A = 25^{\circ}C$ ; $V_{CC1}$ , $V_{CC2}$ , $V_{CC3}$ at typical voltages, unless otherwise specified.

			LIMITS		
SYMBOL	PARAMETER	Min	Тур	Max	UNIT
V <sub>CC1</sub> V <sub>CC2</sub> V <sub>CC3</sub>	Supply voltages	10.5 4.7 30	12 13 32	13.5 16 35	v v v
I <sub>CC1</sub> I <sub>CC2</sub> I <sub>CC3</sub>	Supply currents (no outputs loaded)	20 0 0.2	32 0.6	50 0.1 2	mA mA mA
ICC2A ICC3A	Additional supply currents (A) See Note 1	-2 0.2		I <sub>ОНР1X</sub> 2	mA mA
Ртот	Total power dissipation		400		mW
T <sub>A</sub>	Operating ambient temperature	-20		+70	°C
I <sup>2</sup> C bus in	puts/outputs SDA input (Pin 5) SCL input (Pin 6)				
V <sub>IH</sub>	Input voltage HIGH <sup>2</sup>	3		V <sub>CC1</sub> - 1	v
VIL	Input voltage LOW	-0.3		1.5	V
lн	Input current HIGH <sup>2</sup>			10	μA
կլ	Input current LOW <sup>2</sup>			10	μA
	SDA output (Pin 5, open-collector)				
VOL	Output voltage LOW at I <sub>OL</sub> = 3mA			0.4	v
IOL	Maximum output sink current		5		mA
Open-colle	ctor I/O ports P20, P21, P22, P23 (Pins 7 to 10, open-collector)				
VIH	Input voltage HIGH	2		16	v
VIL	Input voltage LOW	-0.3		0.8	V
Чн	Input current HIGH			25	μA
-I <sub>IL</sub>	Input current LOW			25	<u>μ</u> Α
VOL	Output voltage LOW at I <sub>OL</sub> = 2mA			0.4	٧
IOL	Maximum output sink current		4		mA
AFC ampli	fier Inputs AFC+, AFC- (Pins 11, 12)		1		
	Transconductance for input voltages up to 1V differential:				
	AFCS1 AFCS2				
g00	0 0	100	250	800	nA/V
g01		15	25	35	μΑ/V
g10 g11	1 1	60	100	140	μΑ/ν μΑ/ν
ΔMg	Tolerance of transconductance multiplying factor (2, 4, or 8) when correction-in-band is used	-20		+ 20	%
VIOFF	Input offset voltage	-75		+ 75	mV
V <sub>COM</sub>	Common-mode input voltage	3		V <sub>CC1</sub> - 2.5	V
CMRR	Common-mode rejection ratio		50		dB
PSRR	Power supply (V <sub>CC1</sub> ) rejection ratio		50		dB
ų	Input current			500	nA

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### DC AND AC ELECTRICAL CHARACTERISTICS (Continued) $T_A = 25^{\circ}C$ ; $V_{CC1}$ , $V_{CC2}$ , $V_{CC3}$ at typical voltage, unless

,	· · ·		002	000	
	otherwise	specified	1.		

			LIMITS		
SYMBOL	PARAMETER	Min	Тур	Max	UNIT
Tuning vol	tage amplifier Input TI, output TUN (Pins 13, 15)				
V <sub>TUN</sub>	Maximum output voltage at $I_{LOAD} = \pm 2.5 \text{mA}$	V <sub>CC3</sub> – 1.6		V <sub>CC3</sub> -0.4	V
	Minimum output voltage at ILOAD = ± 2.5mA:				
	VTMI1 VTMI0				
	0 0	300		500	mV mV
VTM10 VTM11	1 1	650		900	mV
	Maximum output source current	2.5		8	mA
ITUNL	Maximum output sink current		40		mA
I <sub>TI</sub>	Input bias current	-5		+5	nA
PSRR	Power supply V <sub>CC3</sub> rejection ratio		60		dB
	Minimum charge IT to tuning voltage amplifier				
	TUHN1 TUHN0				
CH00	0 0	0.4	1	1.7	μA/μs
CH <sub>01</sub>	1 0	4	30	14	μΑ/μs μΔ/μs
	1 1	130	250	370	μΑ/μs
ДСН	Tolerance of charge (or $\Delta V_{TUN}$ ) multiplying factor when COIB and/or TUS are used	-20	···· <u> </u>	+ 20	%
	Maximum current I into tuning amplifier			<u>├</u> †	
	TUHN1 TUHN0				
TOO	0 0	1.7	3.5	5.1	μA
T01	0 1	15	29	41	μA
T10	1 U 1 1	530	110 875	1220	μΑ
Correction	-in-band				
ΔV <sub>CIB</sub>	Tolerance of correction-in-band levels 12V, 18V, and 24V	-15	~~	+15	%
Band-selec	t output ports P10, P11, P12, P13 (Pins 18 to 21)			4	
VOH	Output voltage HIGH at -I <sub>OH</sub> = 50mA <sup>3</sup>	V <sub>CC2</sub> - 0.6			V
VOL	Output voltage LOW at I <sub>OL</sub> = 2mA	1		0.4	v
-I <sub>ОН</sub>	Maximum output source current <sup>3</sup>		130	200	mA
IOL	Maximum output sink current		5		mA
FDIV input	(Pin 23)				
V <sub>FDIV</sub> (P-P)	Input voltage (peak-to-peak value) $t_{\sf RISE}$ and $t_{\sf FALL}{\leqslant}40ns$	0.1		2	v
	Duty cycle	40		60	%
f <sub>MAX</sub>	Maximum input frequency	14.5			MHz
ZI	Input impedance		8		kΩ
CI	Input capacitance		5		pF
OSC input	(Pin 24)			· · · · · · · · · · · ·	
R <sub>X</sub>	Crystal resistance at resonance (4MHz)			150	Ω

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### DC AND AC ELECTRICAL CHARACTERISTICS (Continued) T<sub>A</sub> = 25°C; V<sub>CC1</sub>, V<sub>CC2</sub>, V<sub>CC3</sub> at typical voltage, unless otherwise specified.

OVMBOI				LIMITS		
STMDUL	PARAMETER		Min	Тур	Max	UNIT
DAC outpu	uts 0 to 7 (Pins 25 to 28 and 1 to 4)					
VDH	Maximum output voltage (no load) at $V_{CC1}$	= 12V <sup>4</sup>	10		11.5	V
VDL	Minimum output voltage (no load) at V <sub>CC1</sub>	= 12V <sup>4</sup>	0.1		1	V
ΔV <sub>D</sub>	Positive value of smallest step (1 least sig	nificant bit)	0		350	mV
	Deviation from linearity			0.5	V	
ZO	Output impedance at ILOAD = ± 2mA			70	Ω	
~IDH	Maximum output source current				6	mA
IDL	Maximum output sink current			8		mA
Power-dow	vn reset					
V <sub>PD</sub>	Maximum supply voltage V <sub>CC1</sub> at which po active	ower-down reset is	7.5		9.5	v
tR	$V_{CC1}$ rise time during power-up (up to $V_{PD}$	»)	5			μs
Voltage le	vel for valid module address					
	Voltage level at P20 (Pin 7) for valid mod function of MA1, MA0	ule address as a				
	MA1	MAO				
V <sub>VA00</sub>	0	0	-0.3		16	v
V <sub>VA01</sub>	0	1	-0.3		0.8	v
V <sub>VA10</sub>	1	0	2.5		V <sub>CC1</sub> - 2	v
VVA11	1	1	V <sub>CC1</sub> - 0.3		V <sub>CC1</sub>	V

NOTES:

1. For each band-select output which is programmed at logic 1, sourcing a current IOHP1X, the additional supply currents (A) shown must be added to  $I_{CC2}$  and  $I_{CC3}$ , respectively. 2. If  $V_{CC1} < 1V$ , the input current is limited to 10µA at input voltages up to 16V.

3. At continuous operation the output current should not exceed 50mA. When the output is short-circuited to ground for several seconds, the device may be damaged.

4. Values are proportional to V<sub>CC1</sub>.

### FUNCTIONAL DESCRIPTION

The SAB3035 is a monolithic computer interface which provides tuning and control functions and operates in conjunction with a microcomputer via an  $I^2C$  bus.

### Tuning

This is performed using frequency-locked loop digital control. Data corresponding to the required tuner frequency is stored in a 15-bit frequency buffer. The actual tuner frequency, divided by a factor of 256 (or by 64) by a prescaler, is applied via a gate to a 15-bit frequency counter. This input (FDIV) is measured over a period controlled by a time reference counter and is compared with the contents of the frequency buffer. The result of the comparison is used to control the tuning voltage so that the tuner frequency equals the contents of the frequency buffer multiplied by 50kHz within a programmable tuning window (TUW).

The system cycles over a period of 6.4ms (or 2.56ms), controlled by the time reference counter which is clocked by an on-chip 4MHz reference oscillator. Regulation of the tuning voltage is performed by a charge pump frequency-locked loop system. The charge IT flowing into the tuning voltage amplifier is controlled by the tuning counter, 3-bit DAC, and the charge pump circuit. The charge IT is linear with the frequency deviation  $\Delta f$  in steps of 50kHz. For loop gain control, the relationship  $\Delta IT/\Delta f$  is programmable. In the normal mode (when control bits TUHNO and TUHN1 are both at logic 1, see OPERATION), the minimum charge IT at  $\Delta f = 50$ kHz equals 250µA/µs (typical).

By programming the tuning sensitivity bits (TUS), the charge IT can be doubled up to 6 times. If correction-in-band (COIB) is programmed, the charge can be further doubled up to three times in relation to the tuning voltage level. From this, the maximum charge IT at  $\Delta f$ =50kHz equals  $2^6 \times 2^3 \times 250 \mu$ A/ $\mu$ s (typical).

The maximum tuning current I is  $875\mu$ A (typical). In the tuning-hold (TUHN) mode (TUHN is Active-LOW), the tuning current I is reduced and, as a consequence, the charge into the tuning amplifier is also reduced.

An in-lock situation can be detected by reading FLOCK. When the tuner oscillator frequency is within the programmable tuning window (TUW), FLOCK is set to logic 1. If the frequency is also within the programmable AFC hold range (AFCR), which always occurs if AFCR is wider than TUW, control bit AFCT can be set to logic 1. When set, digital tuning will be switched off, AFC will be switched on and FLOCK will stay at logic 1 as long as the oscillator frequency is within AFCR. If the frequency of the tuning oscillator does not remain within AFCR, AFCT is cleared automatically and the system reverts to digital tuning. To be able to detect this situation, the occurrence of positive and negative transitions in the FLOCK signal can be read (FL/ 1N and FL/0N). AFCT can also be cleared by programming the AFCT bit to logic 0.

The AFC has programmable polarity and transconductance; the latter can be doubled up to 3 times, depending on the tuning voltage level if correction-in-band is used.

The direction of tuning is programmable by using control bits TDIRD (tuning direction down) and TDIRU (tuning direction up). If a tuner enters a region in which oscillation stops, then, providing the prescaler remains stable, no FDIV signal is supplied to CITAC. In this situation the system will tune up, moving away from frequency lock-in. This situation is avoided by setting TDIRD which causes the system to tune down. In normal operation TDIRD must be cleared.

If a tuner stops oscillating and the prescaler becomes unstable by going into self-oscillation at a very high frequency, the system will react by tuning down, moving away from frequency lock-in. To overcome this, the system can be forced to tune up at the lowest sensitivity (TUS) value, by setting TDIRU.

Setting both TDIRD and TDIRU causes the digital tuning to be interrupted and AFC to be switched on.

The minimum tuning voltage which can be generated during digital tuning is programmable by VTMI to prevent the tuner from being driven into an unspecified low tuning voltage region.

#### Control

For tuner band selection there are four outputs — P10 to P13 — which are capable of sourcing up to 50mA at a voltage drop of less than 600mV with respect to the separate power supply input  $V_{CC2}$ 

For additional digital control, four open-collector I/O ports — P20 to P23 — are provided. Ports P22 and P23 are capable of detecting positive and negative transitions in their input signals. With the aid of port P20, up to three independent module addresses can be programmed.

Eight 6-bit digital-to-analog converters — DACO to DAC7 — are provided for analog control.

#### Reset

CITAC goes into the power-down reset mode when  $V_{CC1}$  is below 8.5V (typical). In this mode all registers are set to a defined state. Reset can also be programmed.

### **OPERATION**

#### Write

CITAC is controlled via a bidirectional twowire  $1^2C$  bus. For programming, a module address, R/W bit (logic 0), an instruction byte, and a data/control byte, are written into CITAC in the format shown in Figure 1.



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the module address bits MA1, MA0 are used to give a 2-bit module address as a function of the voltage at port P20 as shown in Table 1.

Acknowledge (A) is generated by CITAC only when a valid address is received and the device is not in the power-down reset mode ( $V_{CC1} > 8.5V$  (typical)).

### Tuning

Tuning is controlled by the instruction and data/control bytes as shown in Figure 2.

### Frequency

Frequency is set when Bit I<sub>7</sub> of the instruction byte is set to logic 1; the remainder of this byte together with the data/control byte are loaded into the frequency buffer. The frequency to which the tuner oscillator is regulated equals the decimal representation of the 15-bit word multiplied by 50kHz. All frequency bits are set to logic 1 at reset.

### **Tuning Hold**

The TUHN bits are used to decrease the maximum tuning current and, as a consequence, the minimum charge IT (at  $\Delta f = 50 \text{ kHz}$ ) into the tuning amplifier.

### Table 1. Valid Module Addresses

MA1	MAO	P20
0	0	Don't care
0	1	GND
1	0	1/2 V <sub>CC1</sub>
1	1	V <sub>CC1</sub>

### Table 2. Tuning Current Control

TUHN1	TUHNO	ΤΥΡ. Ι <sub>ΜΑΧ</sub> (μΑ)	<b>ΤΥΡ. ΙΤ<sub>ΜΙΝ</sub></b> (μΑ/μs)	TYP. $\Delta V_{TUNmin}$ at $C_{INT} = 1 \mu F$ ( $\mu V$ )
0	0	3.5 <sup>1</sup>	11	11
0	1	29	8	8
1	0	110	30	30
1	1	875	250	250

NOTE:

1. Values after reset.

During tuning but before lock-in, the highest current value should be selected. After lock-in the current may be reduced to decrease the tuning voltage ripple.

The lowest current value should not be used for tuning due to the input bias current of the

tuning voltage amplifier (maximum 5nA). However, it is good practice to program the lowest current value during tuner band switching.

	17	1 <sub>6</sub>	۱ <sub>5</sub>	14	دا	12	4	1 <sub>0</sub>	D,	D <sub>6</sub>	Dş	D <sub>4</sub>	D3	02	D <sub>1</sub>	DO
REQ	1	T F14	F13	F12	F11	F10	F9	F8	F7	F6	F5	F4	F3	F2	F1	FO
rcoo	0	•	1	0	1	0	0	1	AFCT	VTMIO	AFCR1	AFCRO	TUHN1	TUHNO	TUW1	TUWO
rcD1	0	0	1	0	1	0	1	0	VTMI1	COIB1	COIBO	AFCS1	AFCS0	TUS2	TUS1	TUSO
rCD2	0	. •	1	. •	1	. •	1	, 1	0	. 0	. •	0	AFCP	FDIVM	TDIRD	TDIRU

### Table 3. Minimum Charge IT as a Function of TUS $\Delta f$ = 50kHz; TUHN0 = Logic 1; TUHN1 = Logic 1

TUS2	TUS1	TUSO	TYP. IT <sub>MIN</sub> (mA/μs)	TYP. $\Delta V_{TUNmin}$ at $C_{INT} = 1 \mu F$ (mV)
0	0	0	0.25 <sup>1</sup>	0.25 <sup>1</sup>
0	0	1	0.5	0.5
0	1	0	1 1	1
0	1	1	2	2
1	0	0	4	4
1	0	1	8	8
1	1	0	16	16

NOTE:

1. Values after reset.

### **Table 4. Programming Correction-In-Band**

COIB1	COIBO	CI	HARGE MULTIPL TYPICAL VALU	YING FACTORS ES OF V <sub>TUN</sub> AT:	AT
		< 12V	12 to 18V	18 to 24V	> 24V
0	0	11	11	11	11
0	1	1	1	1	2
1	0	1	1	2	4
1	1	1	2	4	8

NOTE:

1. Values after reset.

### **Table 5. Tuning Window Programming**

TUW1	TUWO	∆f  (kHz)	TUNING WINDOW (kHz)
0	0	01	01
0	1	50	100
1	0	150	300

NOTE:

1. Values after reset.

### Table 6. AFC Hold Range Programming

AFCR1			AFC HOLD RANGE (kHz)
0	0	01	0 <sup>1</sup>
0	1	350	700
1	0	750	1500

NOTE:

1. Values after reset.

### **Table 7. Transconductance Programming**

AFCS1 AFCS0		TYP. TRANSCONDUCTANCE (µA/V)		
0	0	0.25 <sup>1</sup>		
0	1	25		
1	0	50		
1	1	100		

NOTE:

1. Value after reset.

### **Tuning Sensitivity**

To be able to program an optimum loop gain, the charge IT can be programmed by changing T using tuning sensitivity (TUS). Table 3 shows the minimum charge IT obtained by programming the TUS bits at  $\Delta f$ =50kHz; TUHN0 and TUHN1 = logic 1.

#### Correction-In-Band

This control is used to correct the loop gain of the tuning system to reduce in-band variations due to a non-linear voltage/frequency characteristic of the tuner. Correction-in-band (COIB) controls the time T of the charge equation IT and takes into account the tuning voltage  $V_{TUN}$  to give charge multiplying factors as shown in Table 4.

The transconductance multiplying factor of the AFC amplifier is similar when COIB is used, except for the lowest transconductance which is not affected.

### **Tuning Window**

Digital tuning is interrupted and FLOCK is set to logic 1 (in-lock) when the absolute deviation  $|\Delta I|$  between the tuner oscillator frequency and the programmed frequency is smaller than the programmed TUW value (see Table 5). If  $|\Delta f|$  is up to 50kHz above the values listed in Table 5, it is possible for the system to be locked depending on the phase relationship between FDIV and the reference counter.

#### AFC

When AFCT is set to logic 1 it will not be cleared and the AFC will remain on as long as  $\lfloor \Delta f \rfloor$  is less than the value programmed for the AFC hold range AFCR (see Table 6). It is possible for the AFC to remain on for values of up to 50kHz more than the programmed value depending on the phase relationship between FDIV and the reference counter.

### Transconductance

The transconductance (g) of the AFC amplifier is programmed via the AFC sensitivity bits AFCS as shown in Table 7.

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#### **AFC Polarity**

If a positive differential input voltage is applied to the (switched on) AFC amplifier, the tuning voltage  $V_{TUN}$  falls when the AFC polarity bit AFCP is at logic 0 (value after reset). At AFCP = logic 1,  $V_{TUN}$  rises.

#### Minimum Tuning Voltage

Both minimum tuning voltage control bits, VTMI1 and VTMI0, are at logic 0 after reset. Further details are given in the DC Electrical Characteristics table.

#### Frequency Measuring Window

The frequency measuring window which is programmed must correspond with the division factor of the prescaler in use (see Table 8).

### Tuning Direction

Both tuning direction bits, TDIRU (up) and TDIRD (down), are at logic 0 after reset.

#### Control

The instruction bytes POD (port output data) and DACX (digital-to-analog converter con-

Table 8. Frequency	Measuring	Window	Programming	
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FDIVM	PRESCALER DIVISION	CYCLE PERIOD	MEASURING WINDOW		
	FACTOR	(ms)	(ms)		
0	256	6.4 <sup>1</sup>	5.12 <sup>1</sup>		
1	64	2.56	1.28		

NOTE: 1. Values after reset.

trol) are shown in Figure 3, together with the corresponding data/control bytes. Control is implemented as follows:

**P13, P12, P11, P10** — Band select outputs. If a logic 1 is programmed on any of the POD bits  $D_3$  to  $D_0$ , the relevant output goes HIGH. All outputs are LOW after reset.

**P23, P22, P21, P20** — Open-collector I/O ports. If a logic 0 is programmed on any of the POD bits  $D_7$  to  $D_4$ , the relevant output is forced LOW. All outputs are at logic 1 after reset (high impedance state).

DACX — Digital-to-analog converters. The digital-to-analog converter selected corre-

sponds to the decimal equivalent of the DACX bits X2, X1, X0. The output voltage of the selected DAC is set by programming the bits AX5 to AX0; the lowest output voltage is programmed with all data AX5 to AX0 at logic 0, or after reset has been activated.

### Read

Information is read from CITAC when the R/  $\overline{W}$  bit is set to logic 1. An acknowledge must be generated by the master after each data byte to allow transmission to continue. If no acknowledge is generated by the master, the slave (CITAC) stops transmitting. The format of the information bytes is shown in Figure 4.

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#### **Tuning/Reset Information Bits**

**FLOCK** — Set to logic 1 when the tuning oscillator frequency is within the programmed tuning window.

FL/1N — Set to logic 0 (Active-LOW) when FLOCK changes from 0 to 1 and is reset to logic 1 automatically after tuning information has been read.

**FL/ON** — As for FL/1N, but is set to logic 0 when FLOCK changes from 1 to 0.

FOV — Indicates frequency overflow. When the tuner oscillator frequency is too high with respect to the programmed frequency, FOV is at logic 1, and when too low, FOV is at logic 0. FOV is not valid when TDIRU and/or TDIRD are set to logic 1.

**RESN** — Set to logic 0 (Active-LOW) by a programmed reset or a power-down reset. It is reset to logic 1 automatically after tuning/ reset information has been read.

MWN — MWN (frequency measuring window, Active-LOW) is at logic 1 for a period of 1.28ms, during which time the results of frequency measurement are processed. This time is independent of the cycle period. During the remaining time, MWN is at logic 0 and the received frequency is measured.

When slightly different frequencies are programmed repeatedly and AFC is switched on, the received frequency can be measured using FOV and FLOCK. To prevent the frequency counter and frequency buffer being loaded at the same time, frequency should be programmed only during the period of MWN = logic 0.

#### Port Information Bits

P23/1N, P22/1N — Set to logic 0 (Active-LOW) at a LOW-to-HIGH transition in the input voltage on P23 and P22, respectively. Both are reset to logic 1 after the port information has been read.

**P23/0N, P22/0N** — As for P23/1N and P22/ 1N, but are set to logic 0 at a HIGH-to-LOW transition.

**PI23, PI21, PI20, PI** — Indicate input voltage levels at P23, P22, P21, and P20, respectively. A logic 1 indicates a HIGH input level.

#### Reset

The programming to reset all registers is shown in Figure 5. Reset is activated only at data byte HEX06. Acknowledge is generated at every byte, provided that CITAC is not in the power-down reset mode. After the general call address byte, transmission of more than one data byte is not allowed.



### I<sup>2</sup>C BUS TIMING (Figure 6)

I<sup>2</sup>C bus load conditions are as follows:

 $4k\Omega$  pull-up resistor to +5V; 200pF capacitor to GND.

All values are referred to  $V_{IH} = 3V$  and  $V_{IL} = 1.5V$ .

0/4000	PARAMETER		LIMITS		
SYMBOL			Тур	Max	UNIT
t <sub>BUF</sub>	Bus free before start	4			μs
tsu, tsta	Start condition setup time	4			μs
t <sub>HD</sub> , t <sub>STA</sub>	Start condition hold time	4			μs
tLOW	SCL, SDA LOW period	4			μs
thigh	SCL HIGH period	4			μs
t <sub>R</sub>	SCL, SDA rise time			1	μs
tF	SCL, SDA fall time			0.3	μs
t <sub>SU</sub> , t <sub>DAT</sub>	Data setup time (write)	1			μs
t <sub>HD</sub> , t <sub>DAT</sub>	Data hold time (write)	1			μs
tsu, tcac	Acknowledge (from CITAC) setup time			2	μs
t <sub>HD</sub> , t <sub>CAC</sub>	Acknowledge (from CITAC) hold time	0			μs
tsu, tsto	Stop condition setup time	4			μs
t <sub>SU</sub> , t <sub>RDA</sub>	Data setup time (read)			2	μs
t <sub>HD</sub> , t <sub>RDA</sub>	Data hold time (read)	0			μs
t <sub>SU</sub> , t <sub>MAC</sub>	Acknowledge (from master) setup time	1			μs
t <sub>HD</sub> , t <sub>MAC</sub>	Acknowledge (from master) hold time	2			μs

NOTE:

Timings t<sub>SU</sub>, t<sub>DAT</sub> and t<sub>HD</sub>, t<sub>DAT</sub> deviate from the I<sup>2</sup>C bus specification.

After reset has been activated, transmission may only be started after a 50µs delay.

